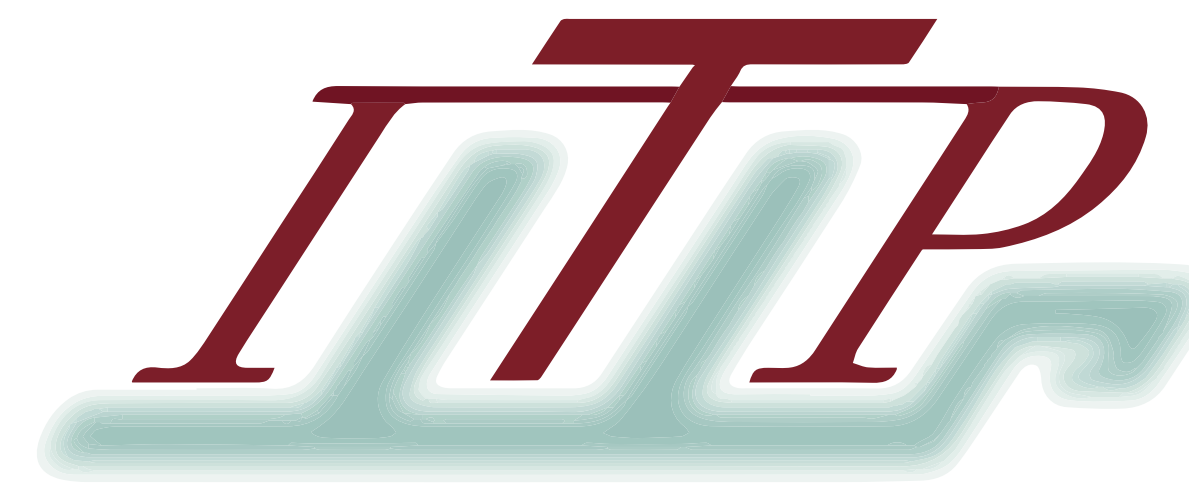


Fast, accurate, and precise neural networks for high-dimensional calorimeters

Luigi Favaro

from 2305.16774, 2312.09290, 2405.09629



UNIVERSITÄT
HEIDELBERG
ZUKUNFT
SEIT 1386

Collaborative Research Center TRR 257

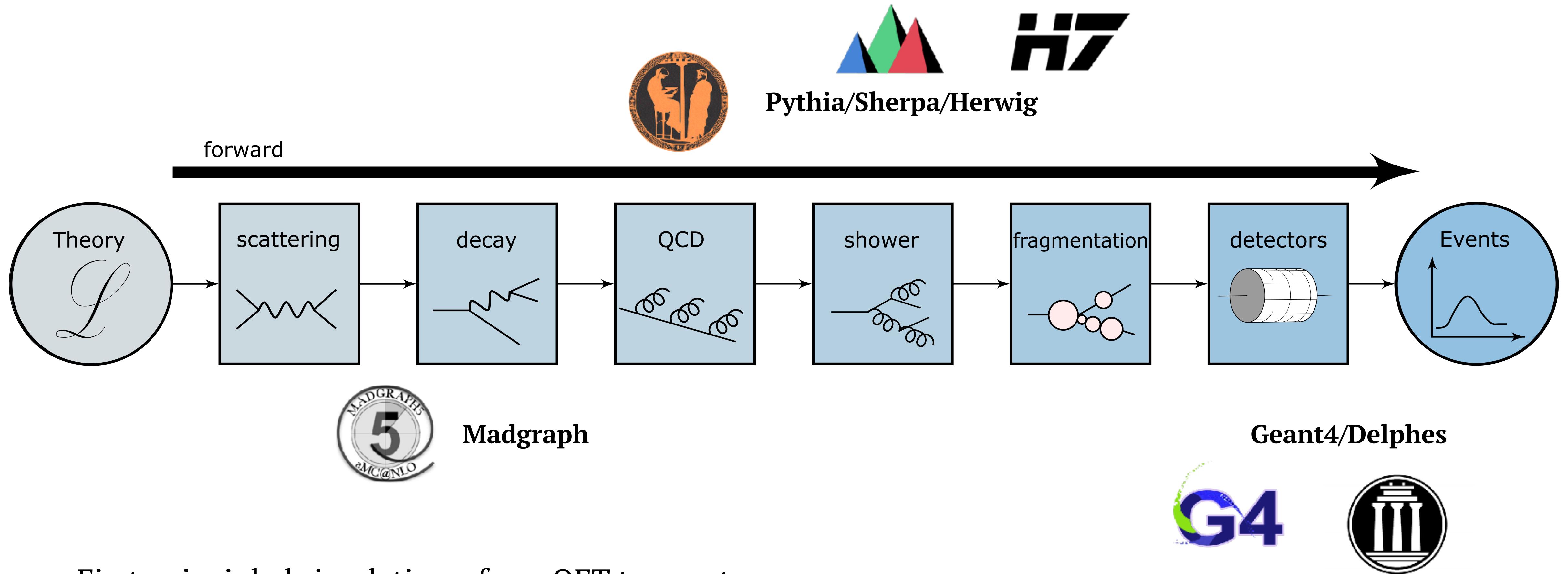


Particle Physics Phenomenology after the Higgs Discovery

DFG Deutsche
Forschungsgemeinschaft
German Research Foundation

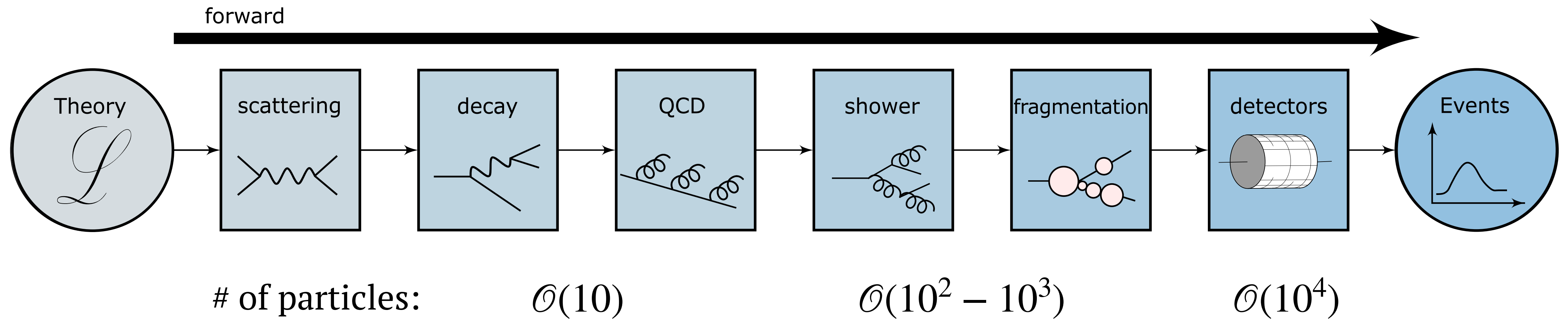
10.09.2024 - Louvain-la-Neuve

Simulation Chain



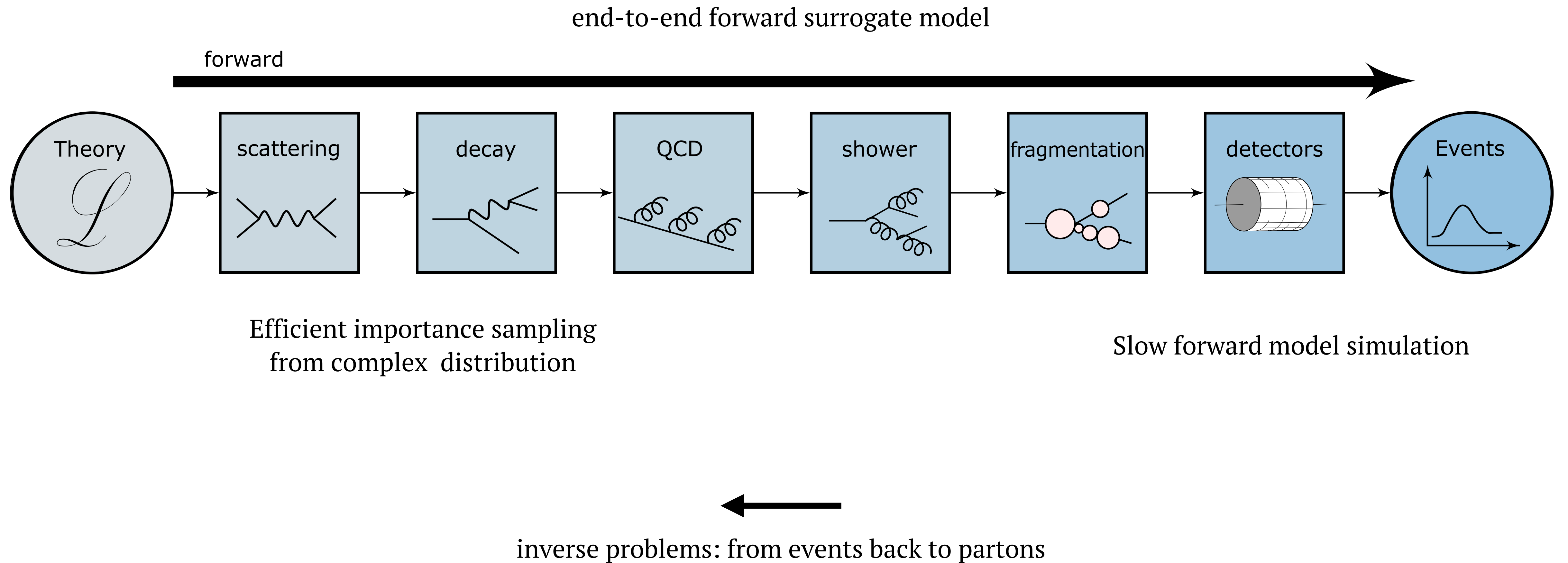
- First-principled simulations, from QFT to events

Simulation Chain

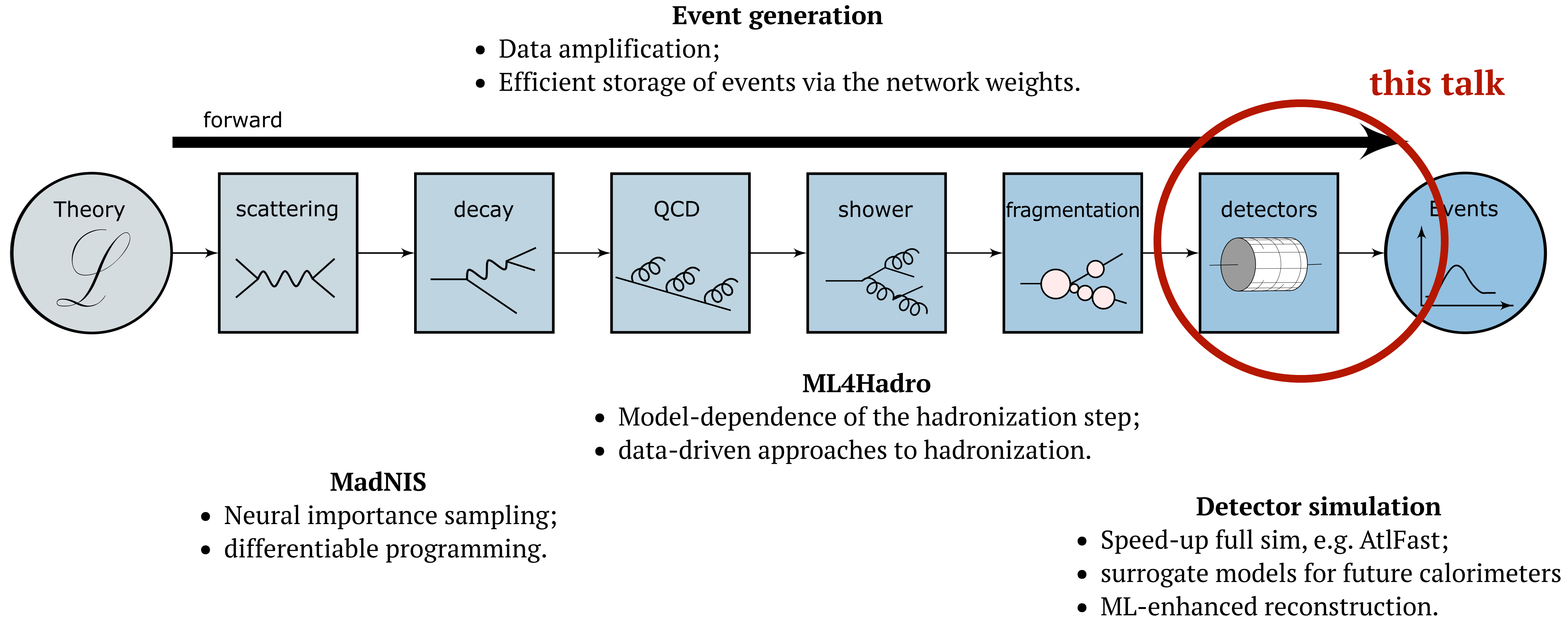


- In the last step we reconstruct $\mathcal{O}(10)$ objects from the detector readouts;
- High-dimensional spaces which pose different questions.

Simulation Chain



Simulation Chain



LHC future plan

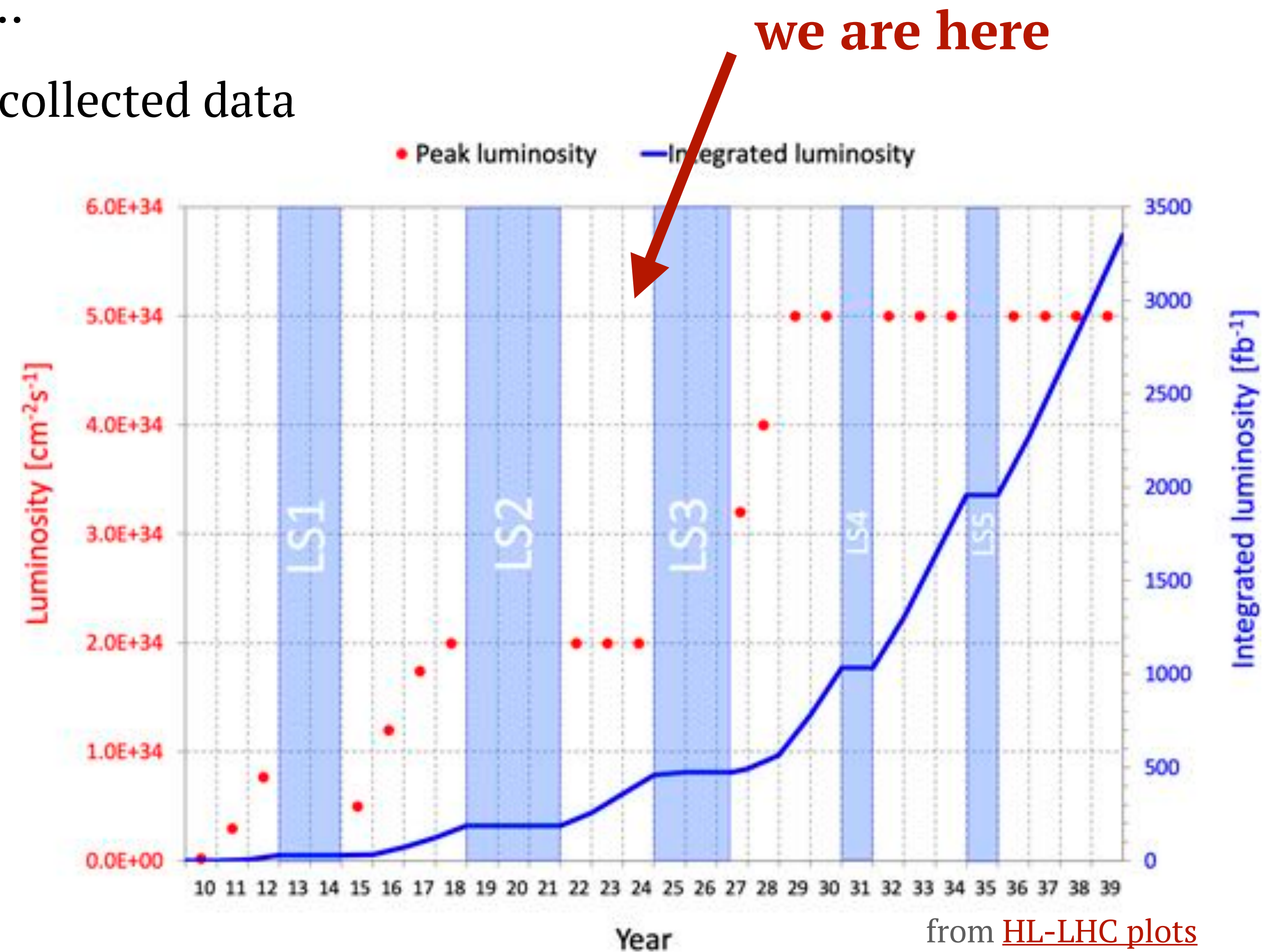
- The high-luminosity data taking phase is close...
- Simulations will have to match the statistics of collected data

Need for fast generators...

... which are still (more) accurate and precise

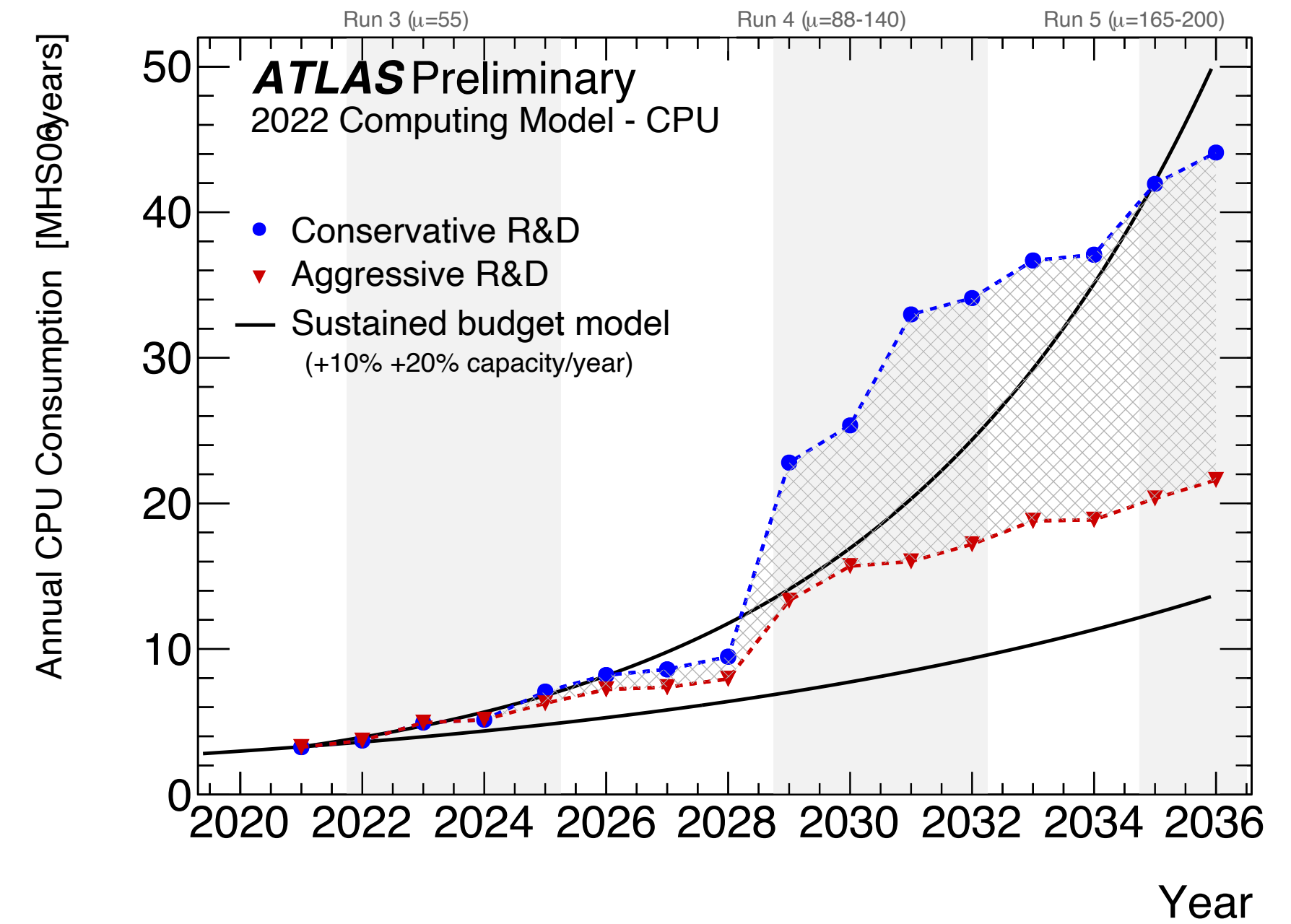
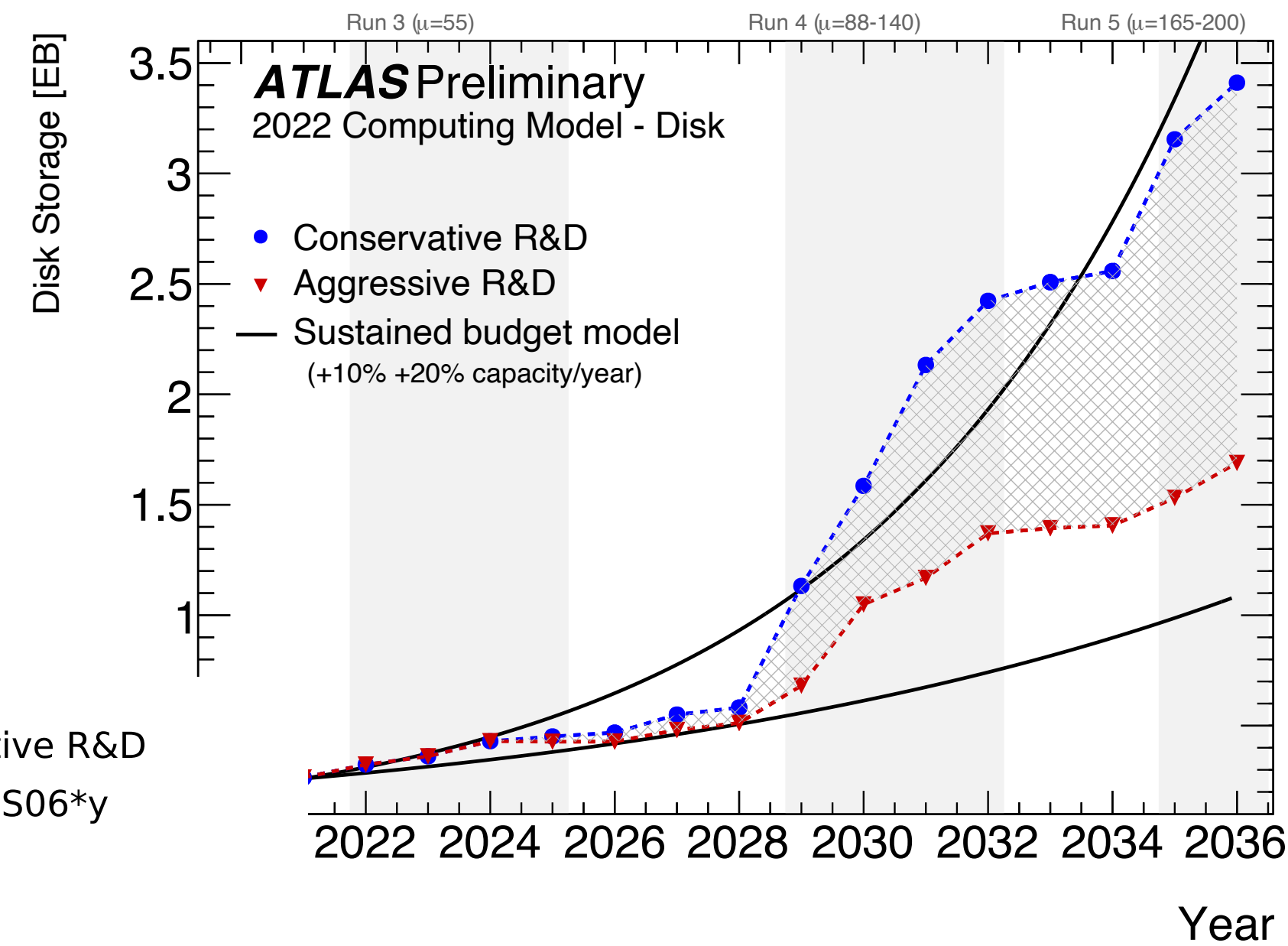
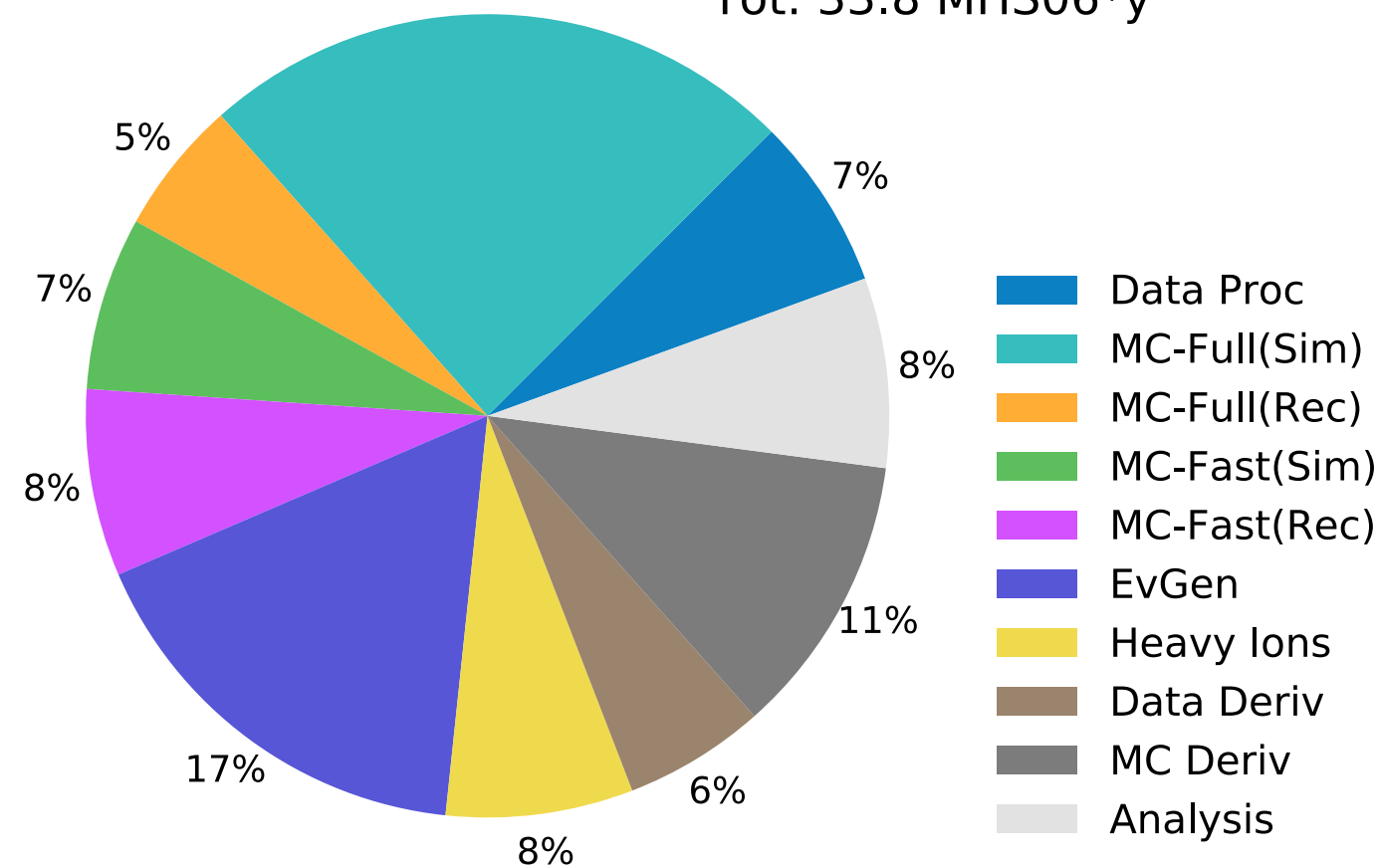


find new physics!
(or rather understand LHC data)



Detector simulation

ATLAS Preliminary
2022 Computing Model - CPU: 2031, Conservative R&D
Tot: 33.8 MHS06*y



- A conservative R&D approach will not be sustainable
- ~ 44 % of computing budget goes into MC full/fast simulation

from [ATLAS computing roadmap](#)

Expensive?

Simple description of an EM shower:

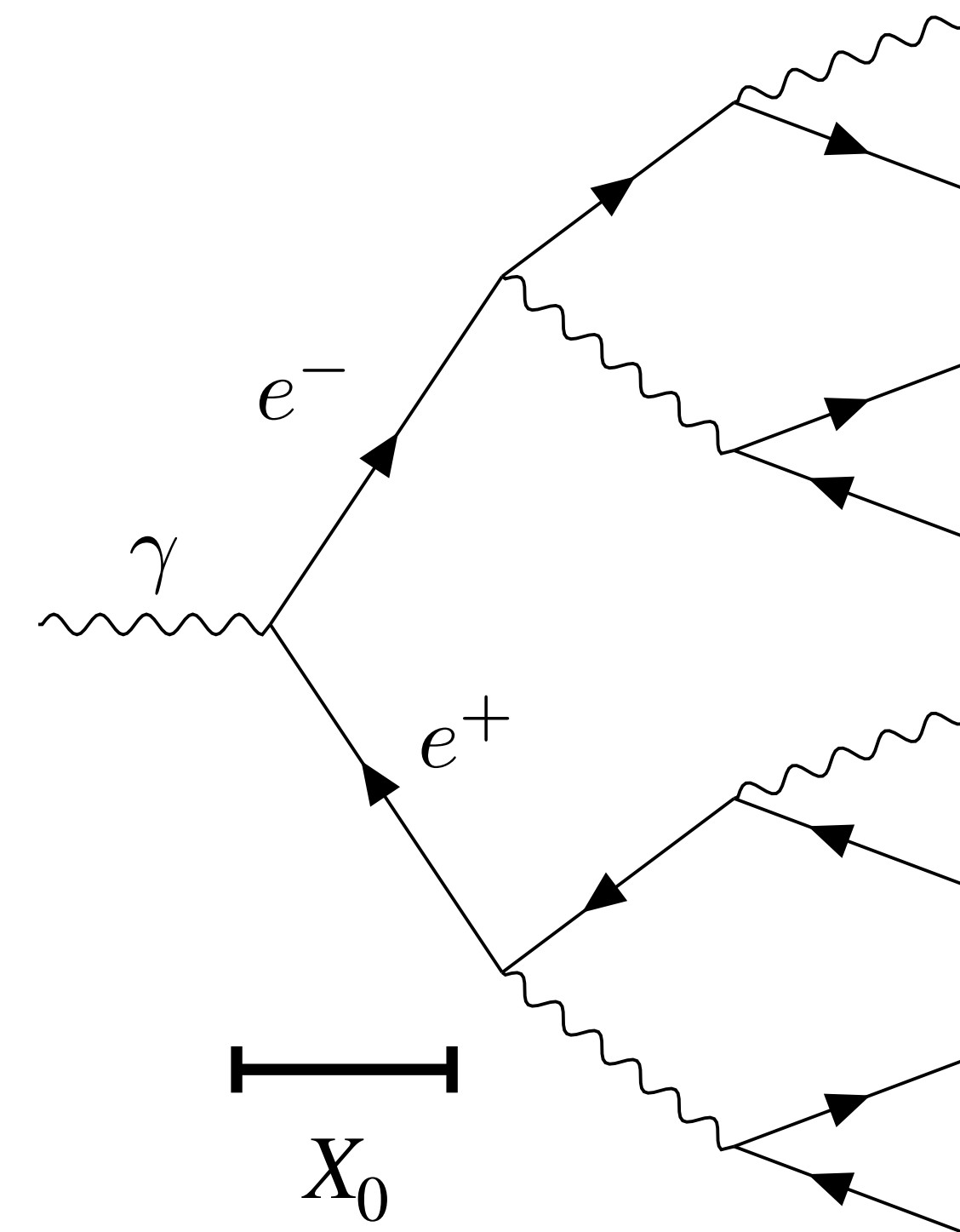
- Assuming one interaction every X_0 with equal energy splitting
- shower stops at the critical energy E_c

- mean energy deposition: $\left\langle \frac{dE}{dx} \right\rangle = -\frac{E}{X_0}$

Features:

- at step t : $N(t) = 2^t$
- $t_{\max} \propto \log E_0$

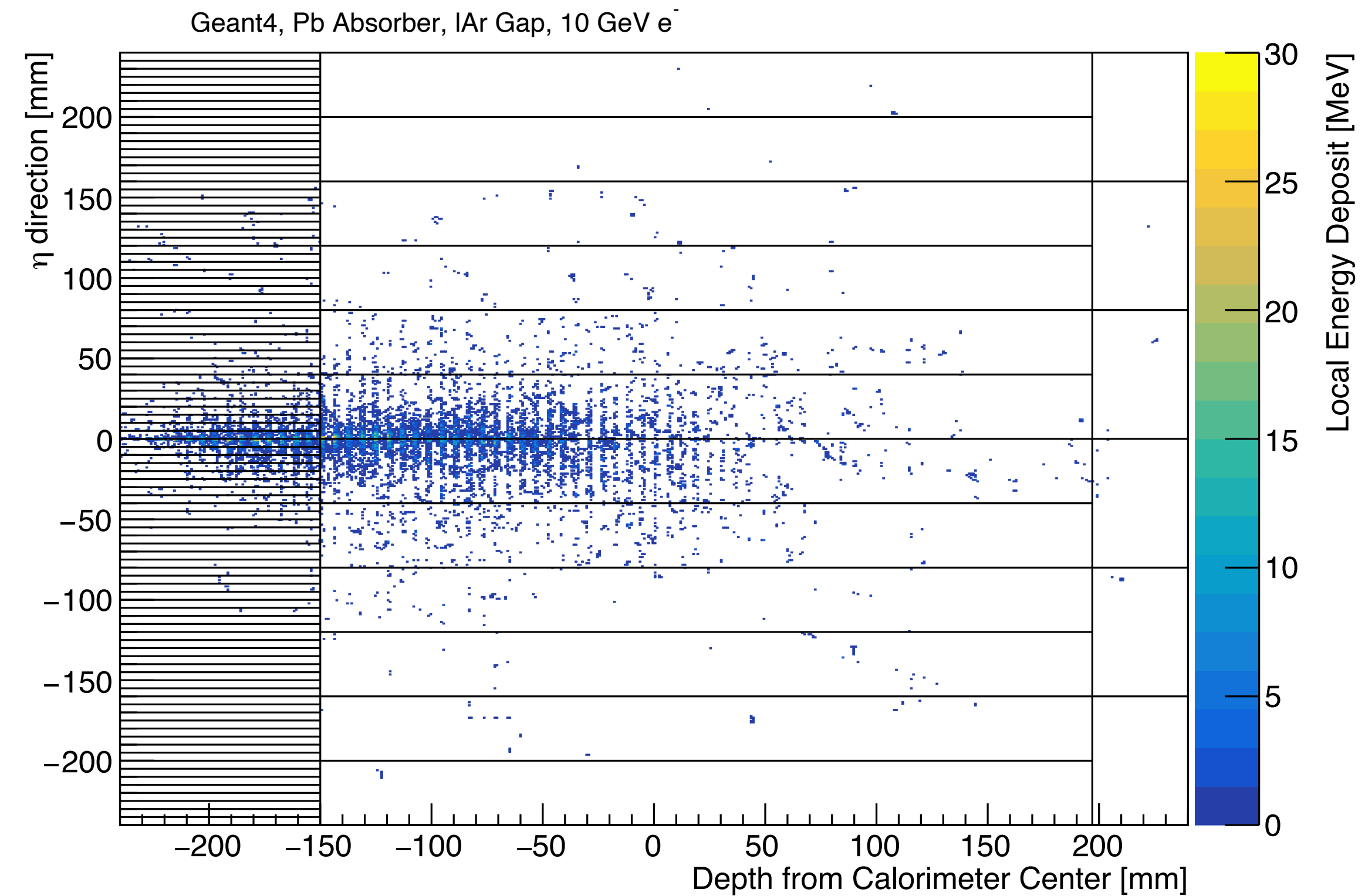
**Exponential scaling
of particle #**



Geant4

Geant4 is the main toolkit for full sims:

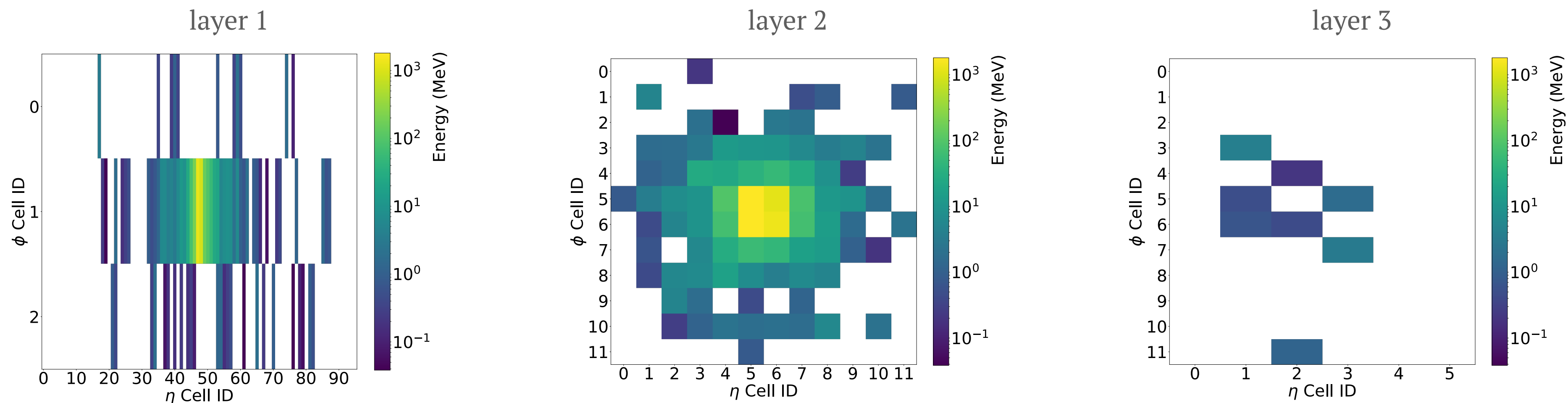
- Defines a custom geometry
- stochastically particles interact with the material
- keeps track of all of them



Energy deposition from hits in one cell are summed together

[CaloGAN](#) data

Geant4



[CaloGAN](#) data

- The shower is represented as 4-tuple (E, x, y, z)
- There can be no-energy deposition
- visualized as an image

Difficulties:

- High-dimensional
- non-trivial correlations
- energy conservation

This is known as “voxelised” approach, can we speed up this process?

ML to the rescue

Measure for the difference between two distributions: Kullback-Leibler divergence:

$$\text{KL}(p \mid q) = \int dx p(x) \log \frac{p(x)}{q(x)}$$

- positive definite
- zero if $p(x) = q(x)$

Turn this expression into a loss function:

$$\begin{aligned} \text{KL}(p \mid q_\theta) &= - \int dx p(x) \log q_\theta(x) + c \\ &= - \langle q_\theta(x) \rangle_{x \sim p(x)} \end{aligned}$$

ML to the rescue

Assume $x \sim p_{\text{data}}(x)$ and model $p_{\theta}(x)$:

$$\mathcal{L} \approx -\frac{1}{N} \sum_{i=1}^N \log p_{\theta}(x_i) \quad x_i \sim p_{\text{data}}(x)$$

Generative “Flow” networks:

- transform from input space to a latent space
- easy to sample from the latent distribution

$$G_{\theta}(x): x \rightarrow z$$

$$\bar{G}_{\theta}(z): z \rightarrow x \quad x, z \in \mathbb{R}^d,$$

ML to the rescue

Change of variable formula:

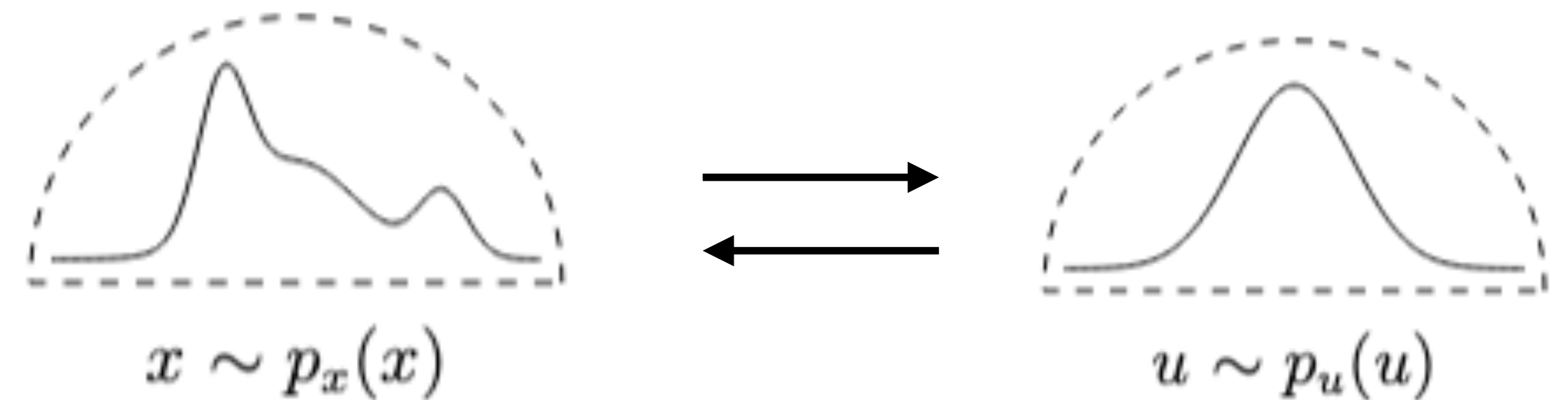
$$p_{lat}(z) = p_{\theta}(G_{\theta}(x)) \left| \frac{\partial G_{\theta}(z)}{\partial z} \right|$$

Typical choice is a standard Gaussian latent space:

$$\log p_{lat}(z) = \log(\sqrt{2\pi}) - \frac{z^2}{2}$$

Aim to a loss function that looks like:

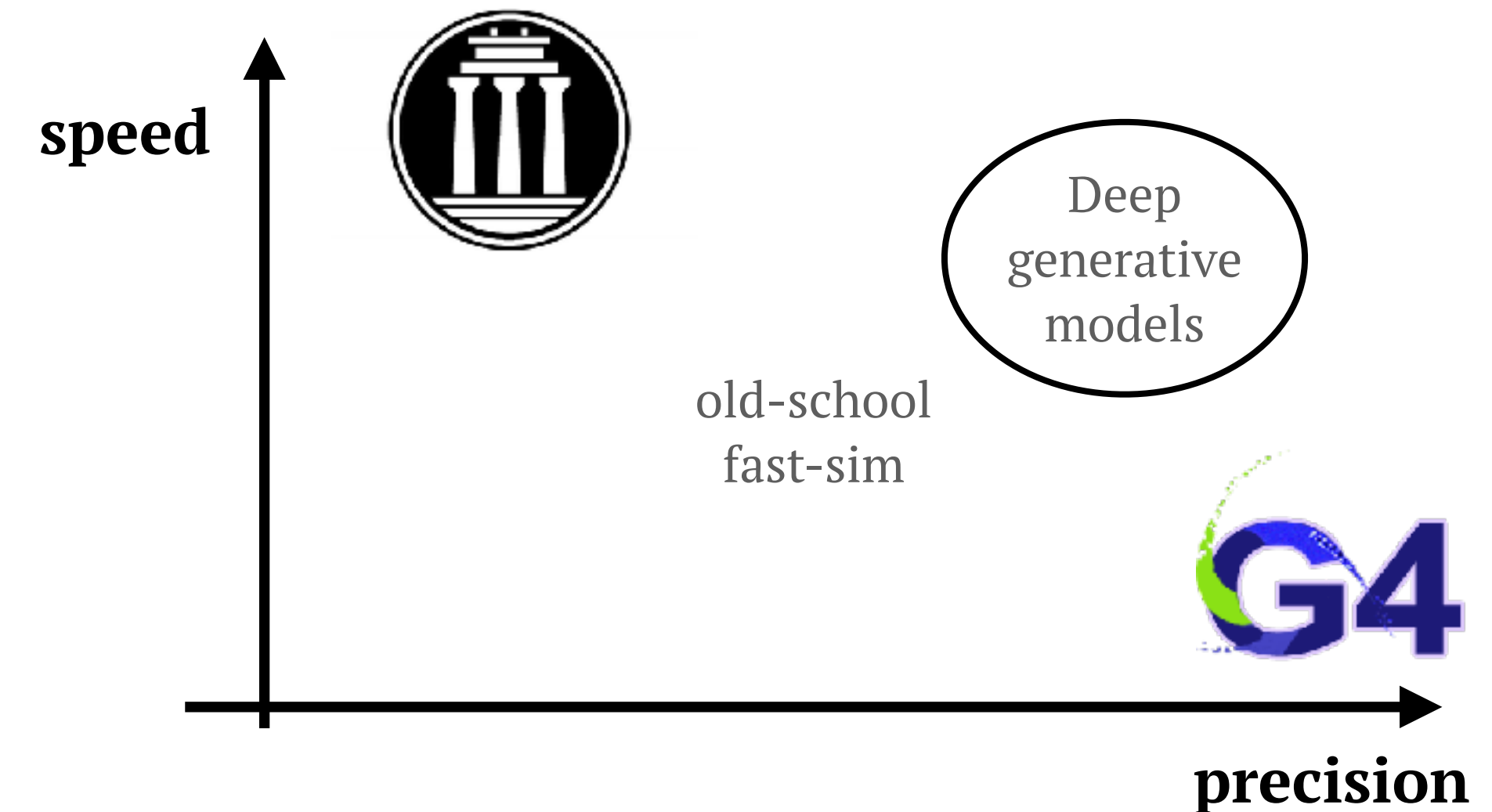
$$\mathcal{L}_F = - \left\langle \log p_{lat}(\bar{G}_{\theta}(x)) + \log \left| \frac{\partial \bar{G}_{\theta}}{\partial x} \right| \right\rangle_{p_{data}} .$$



Modern generative networks

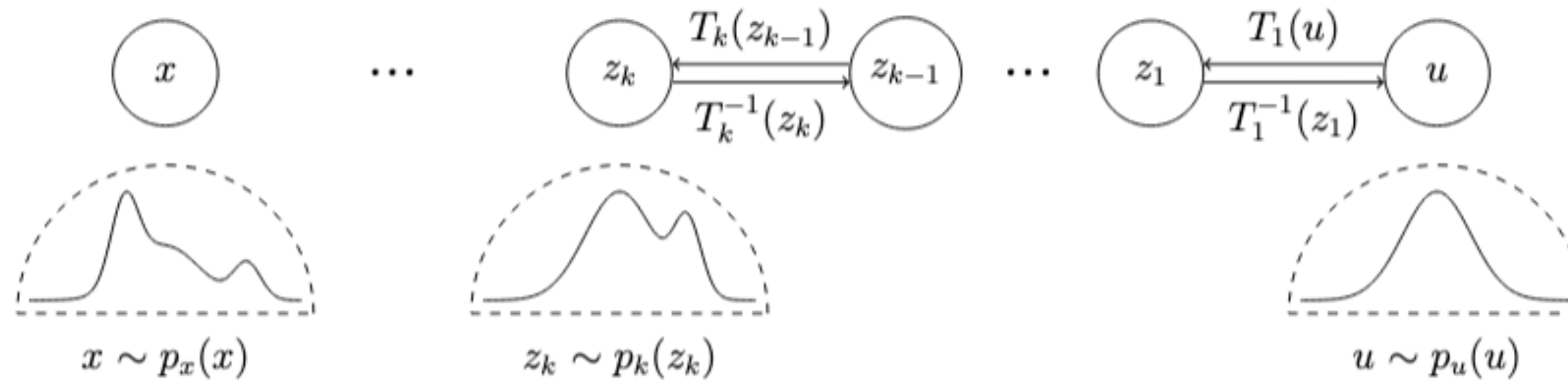
Modern generative networks:

- Complex architectures but still fitting functions
- provided data, approximate Geant4
- speed and precision are key
- tradeoff between speed and precision



Normalizing Flows

figure from future CaloChallenge white paper



Normalizing flows define a discrete number of invertible transformations

Choice of the transformation is crucial \longrightarrow Jacobian has to be tractable

Two popular choices:

- Masked Autoregressive Flows (MAF)
- Invertible Neural Networks (INN) (aka coupling block)

see also [CaloFlow](#)

Coupling blocks

Coupling block transformation:

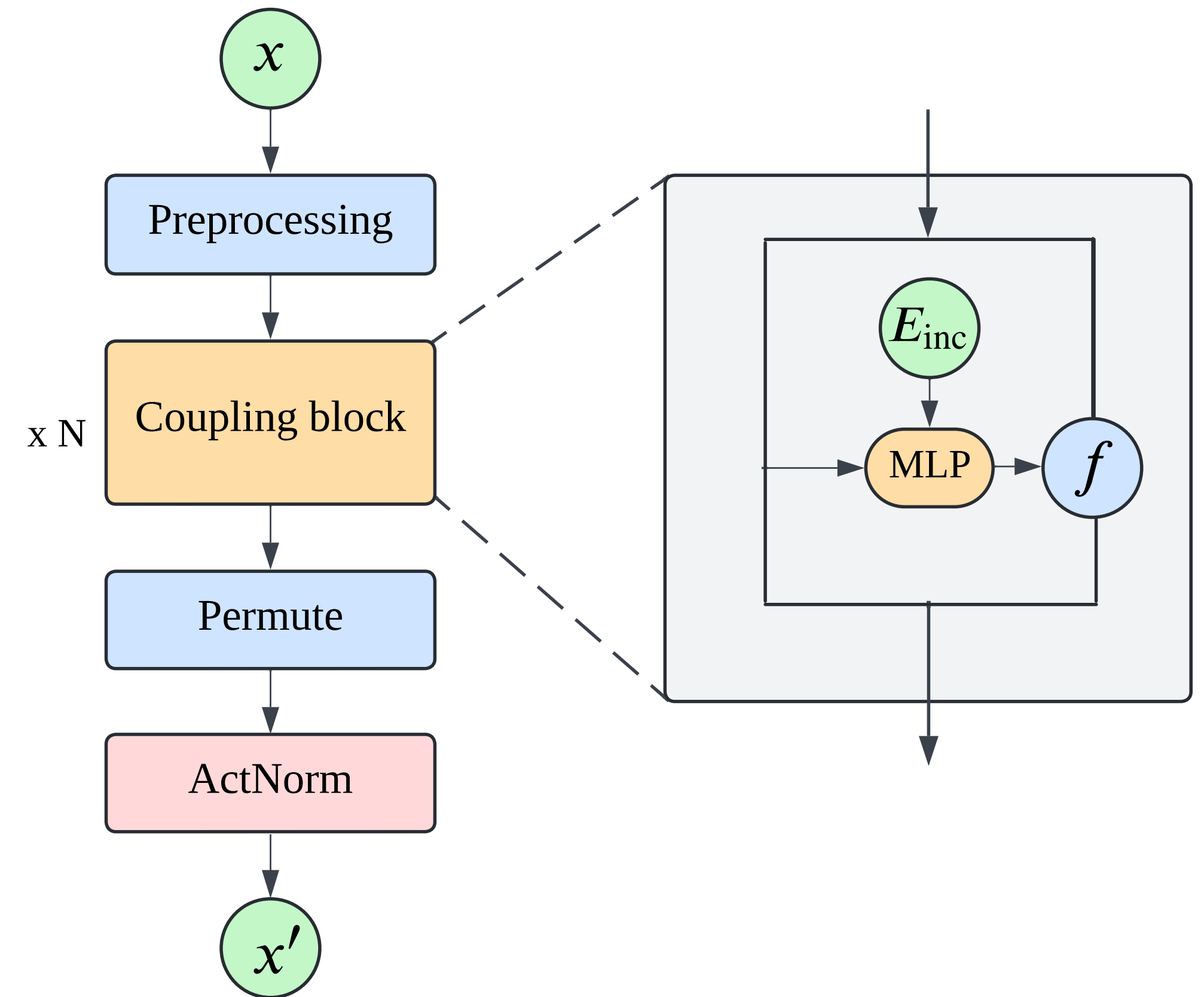
$$\begin{cases} y_i = x_i & i \in 1, \dots, d \\ y_i = f_\theta(x_i | x_1, \dots, x_d) & i \in d + 1, \dots, D, \end{cases}$$

The corresponding Jacobian is

$$\frac{\partial y}{\partial x} = \begin{pmatrix} I_d & (\neq 0) \\ 0 & \frac{\partial y_i}{\partial x_i} \end{pmatrix}$$

Determinant is calculated in $\mathcal{O}(N^2)$ operations

→ fast in both sampling and inference direction



Conditional Flow Matching

Promote the discrete transformation to a continuous one:

$$\frac{dx(t)}{dt} = v(x(t), t) \quad \text{with} \quad x \in \mathbb{R}^d \quad \frac{\partial p(x, t)}{\partial t} + \nabla_x [p(x, t)v(x, t)] = 0 .$$

We want to impose the boundary conditions for $p(x, t)$:

$$p(x, t) \rightarrow \begin{cases} \mathcal{N}(x; 0, 1) & t \rightarrow 1 \\ p_{data}(x) & t \rightarrow 0 . \end{cases}$$

Need to define the training trajectories

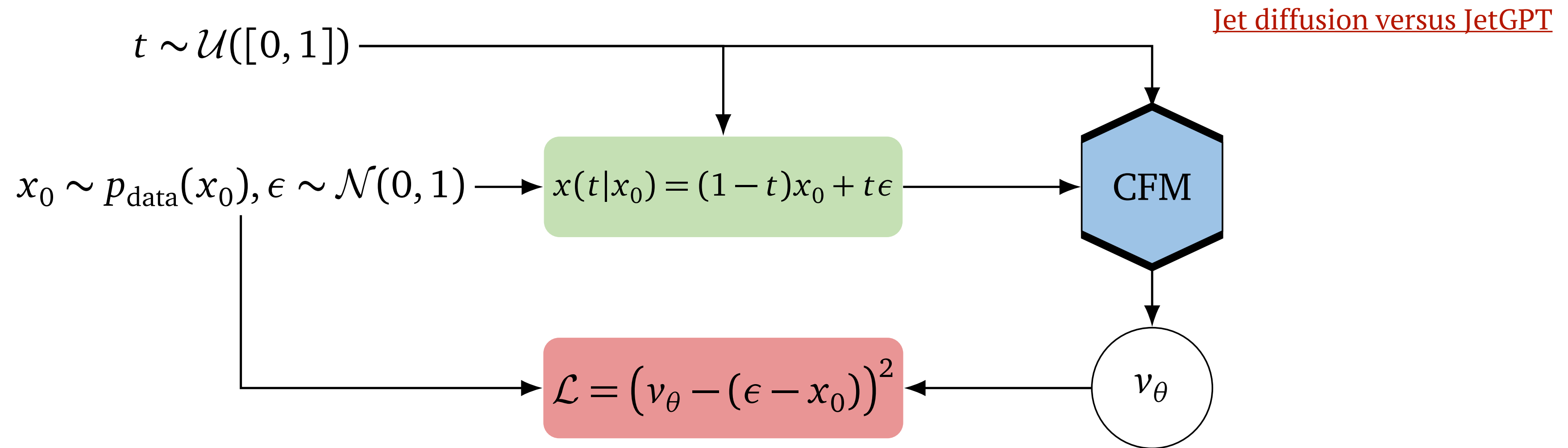
→ linear, simplest choice

$$x(t | x_0) = (1 - t)x_0 + t\epsilon \quad \epsilon \sim \mathcal{N}(0, 1)$$

Learn this velocity field with a NN:

$$\mathcal{L} = ||v(x, t) - v_\phi(x, t)||_{L_2}$$

Conditional Flow Matching



$$\mathcal{L}_{\text{CFM}} = \left\langle \left[v_{\phi}((1-t)x_0 + t\epsilon, t) - (\epsilon - x_0) \right]^2 \right\rangle_{U(0,1), \mathcal{N}, p_{\text{data}}}$$

Sample solving the differential equation numerically: $x(t=0) = x(t=1) - \int_0^1 v_{\phi}(x, t) dx$

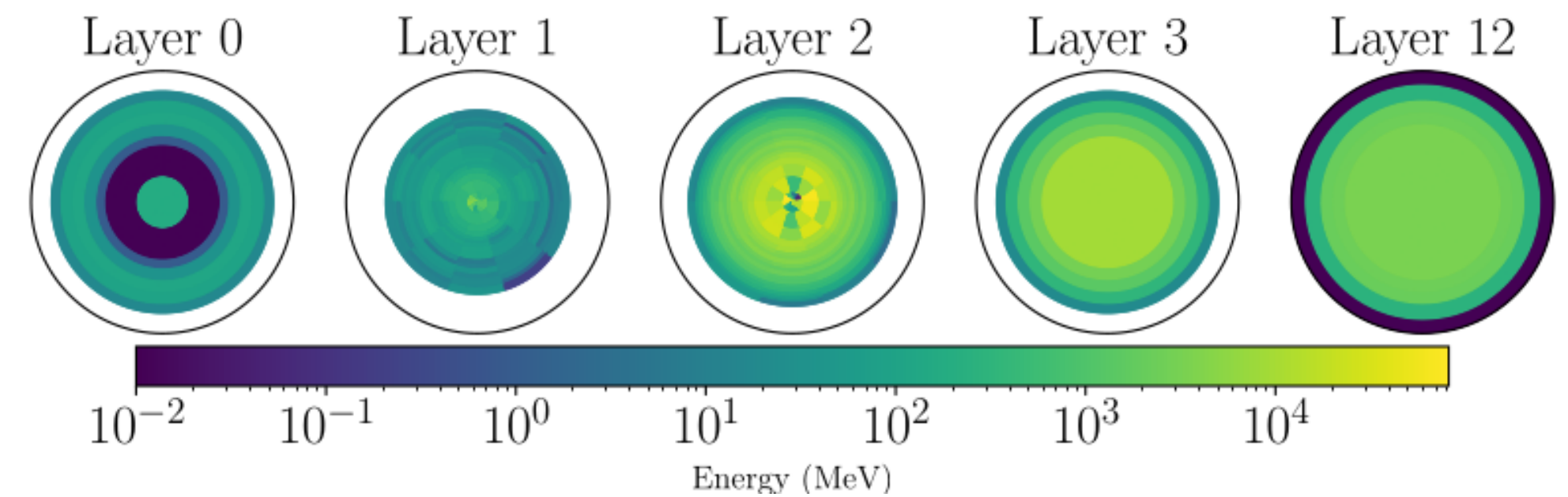
CaloChallenge

Datasets:

[Github](#)

- DS1: Atlas simulation of γ and π^+ showers at $\eta = 0.25$
 - photons have 388 voxels
 - pions have 533 voxels

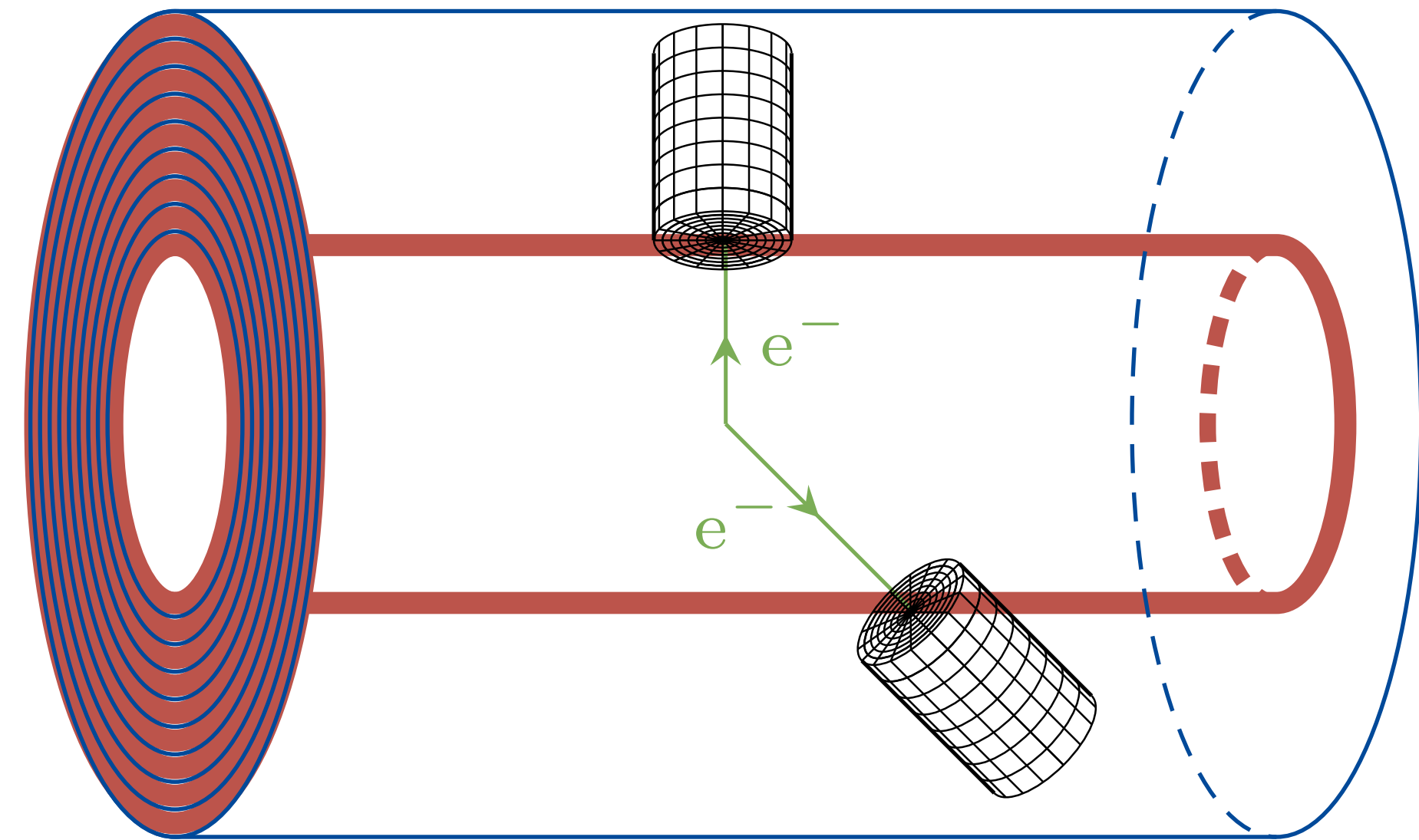
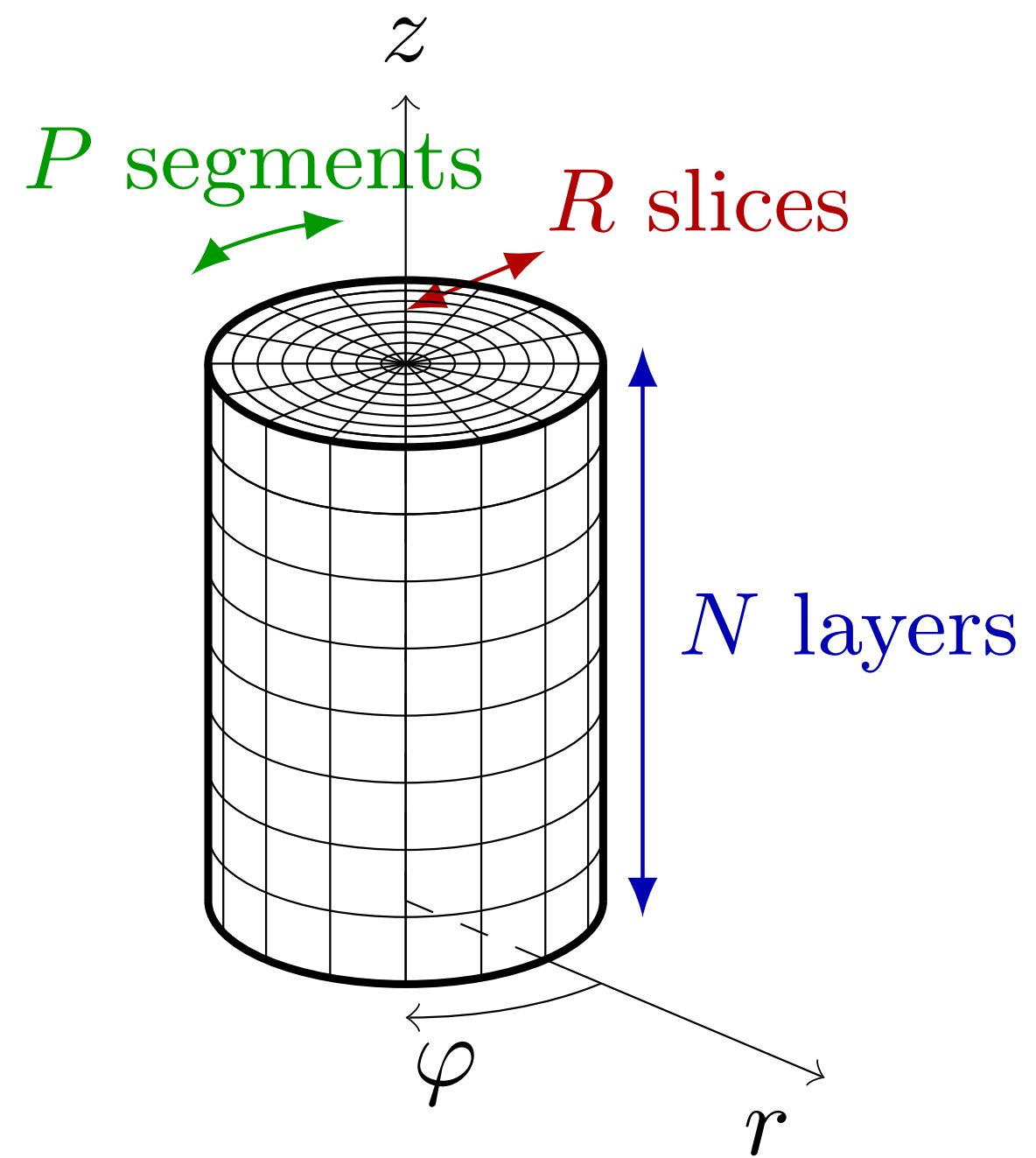
E_{inc}	256 MeV ... 131 GeV	262 GeV	0.524 TeV	1.04 TeV	2.1 TeV	4.2 TeV
photons	10000 per energy	10000	5000	3000	2000	1000
pions	10000 per energy	9800	5000	3000	2000	1000



- DS2/3: Geant simulated e^+ with 45 layers of active silicon detector + tungsten absorber
 - DS2 has a total of 6480 voxels
 - DS3 has 45000 voxels
 - log-uniform energy, $E_{inc} \in [1, 10^3]$ GeV

CaloChallenge

[Github](#)



Preprocessing

Clever preprocessing:

normalized showers

$$u_0 = \frac{\sum_i E_i}{E_{inc}} \quad \text{and} \quad u_i = \frac{E_i}{\sum_{j \geq i} E_j},$$

log/logit

$$x_\alpha = (1 - 2\alpha)x + \alpha \in [\alpha, 1 - \alpha] \quad \text{with} \quad \alpha = 10^{-6}$$
$$x' = \log \frac{x_\alpha}{1 - x_\alpha}.$$

We approached the problem in two ways:

Directly learn the full distribution $p(x_i, u_i | E_{inc})$

CaloINN

arXiv: 2312.09290

Factorise the problem into:

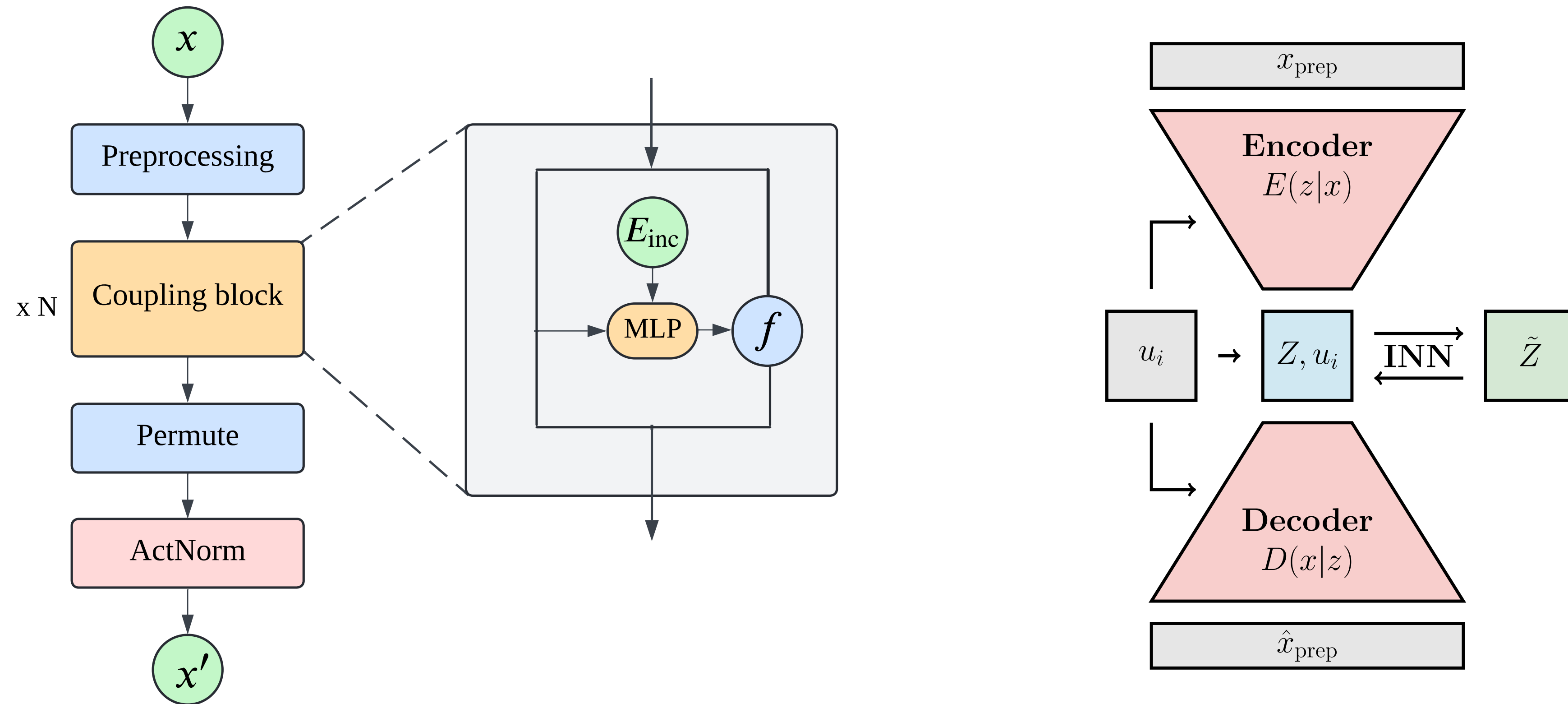
- learn the energy distribution, $p(E_i | E_{inc})$
- learn the normalised voxels $p(x_i | u_i, E_{inc})$

CaloDREAM

arXiv:2405.09629

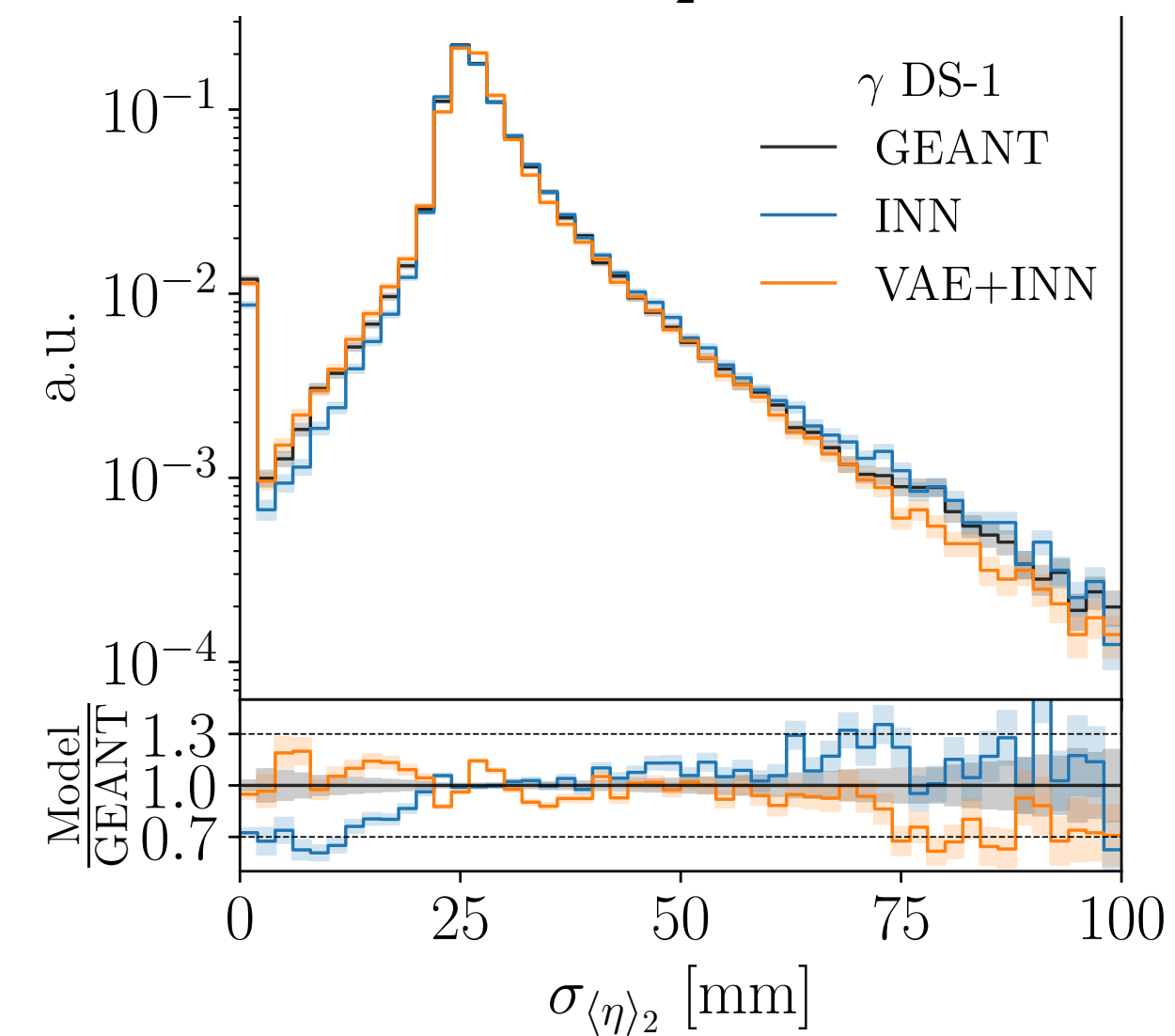
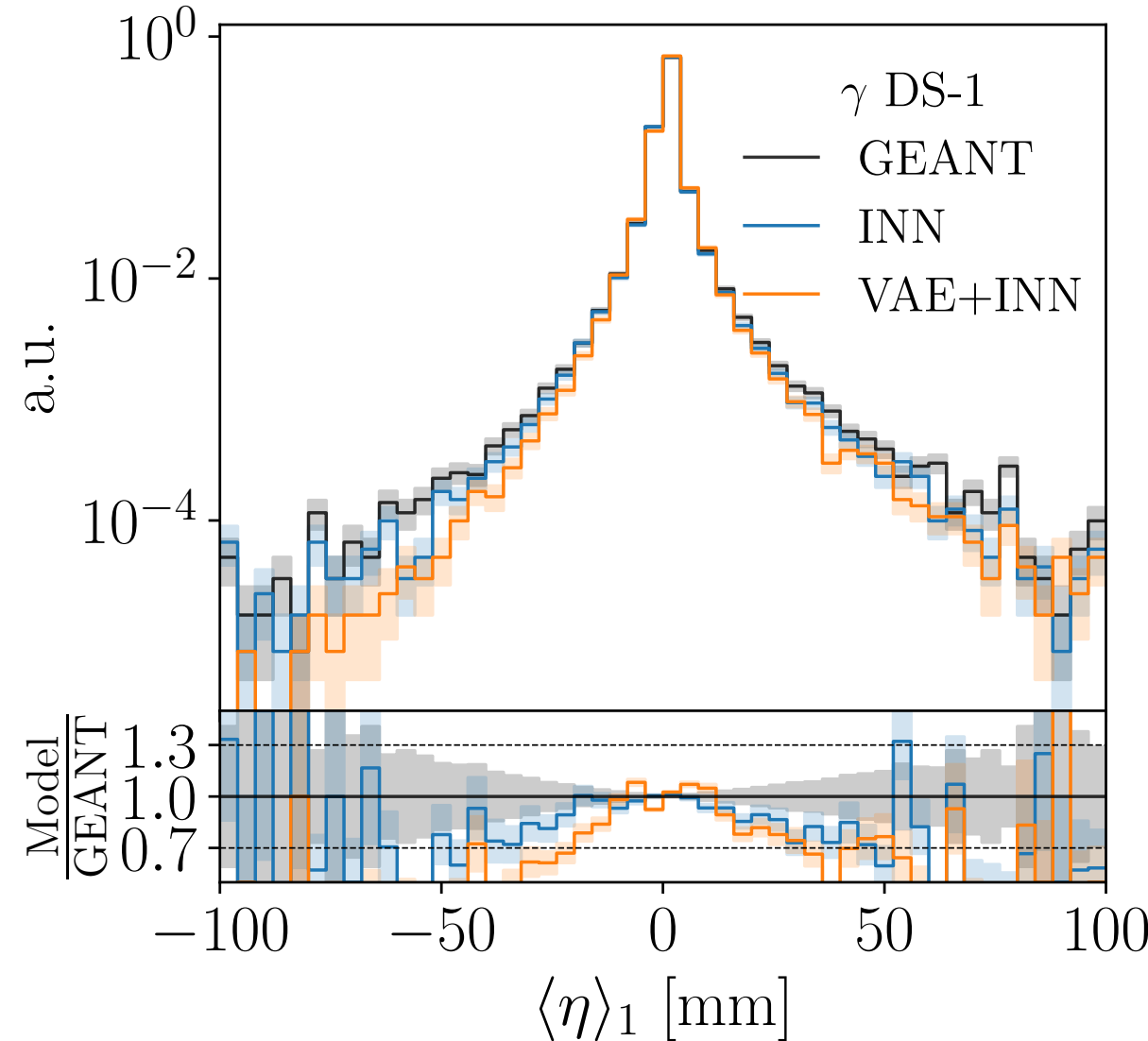
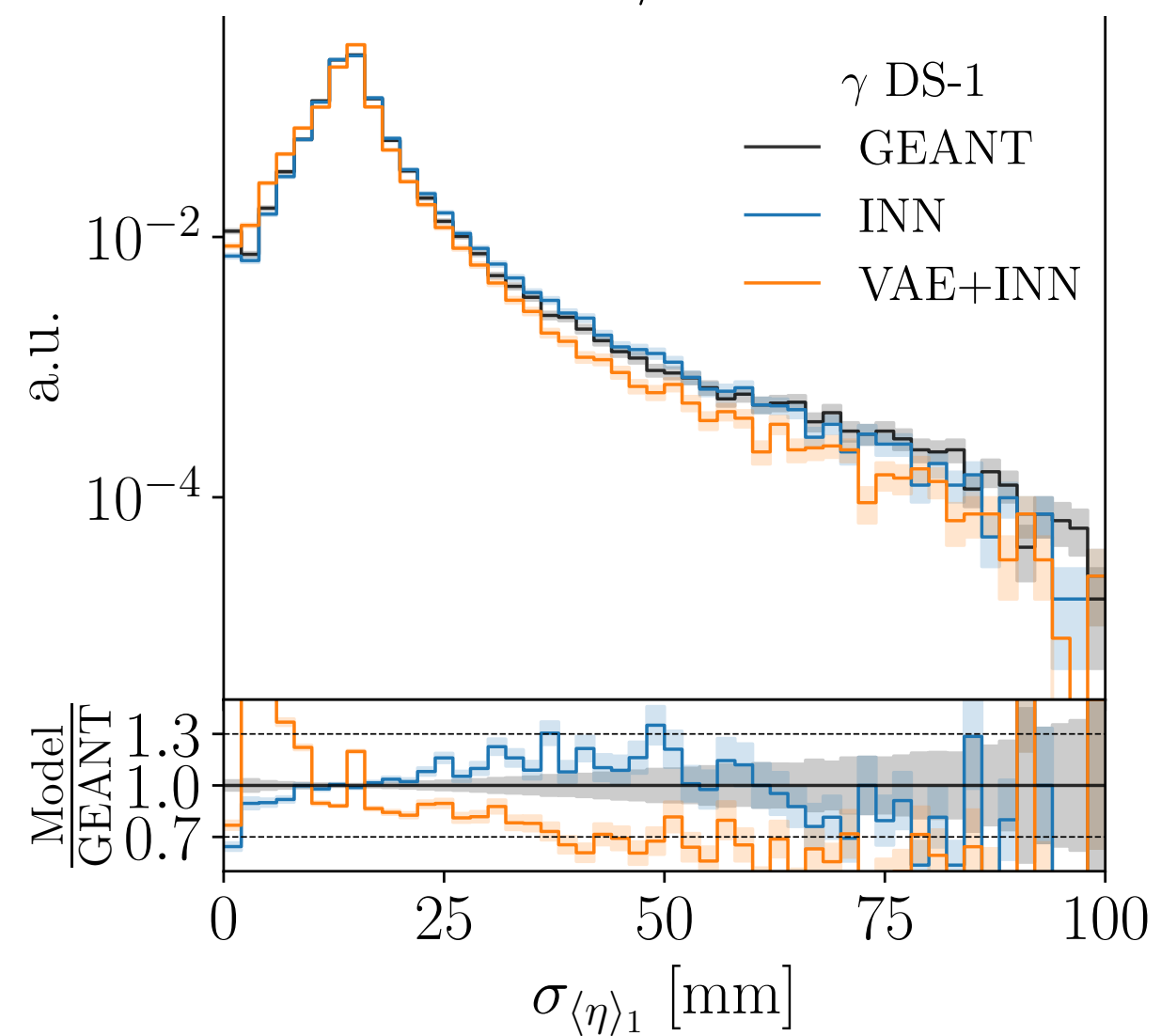
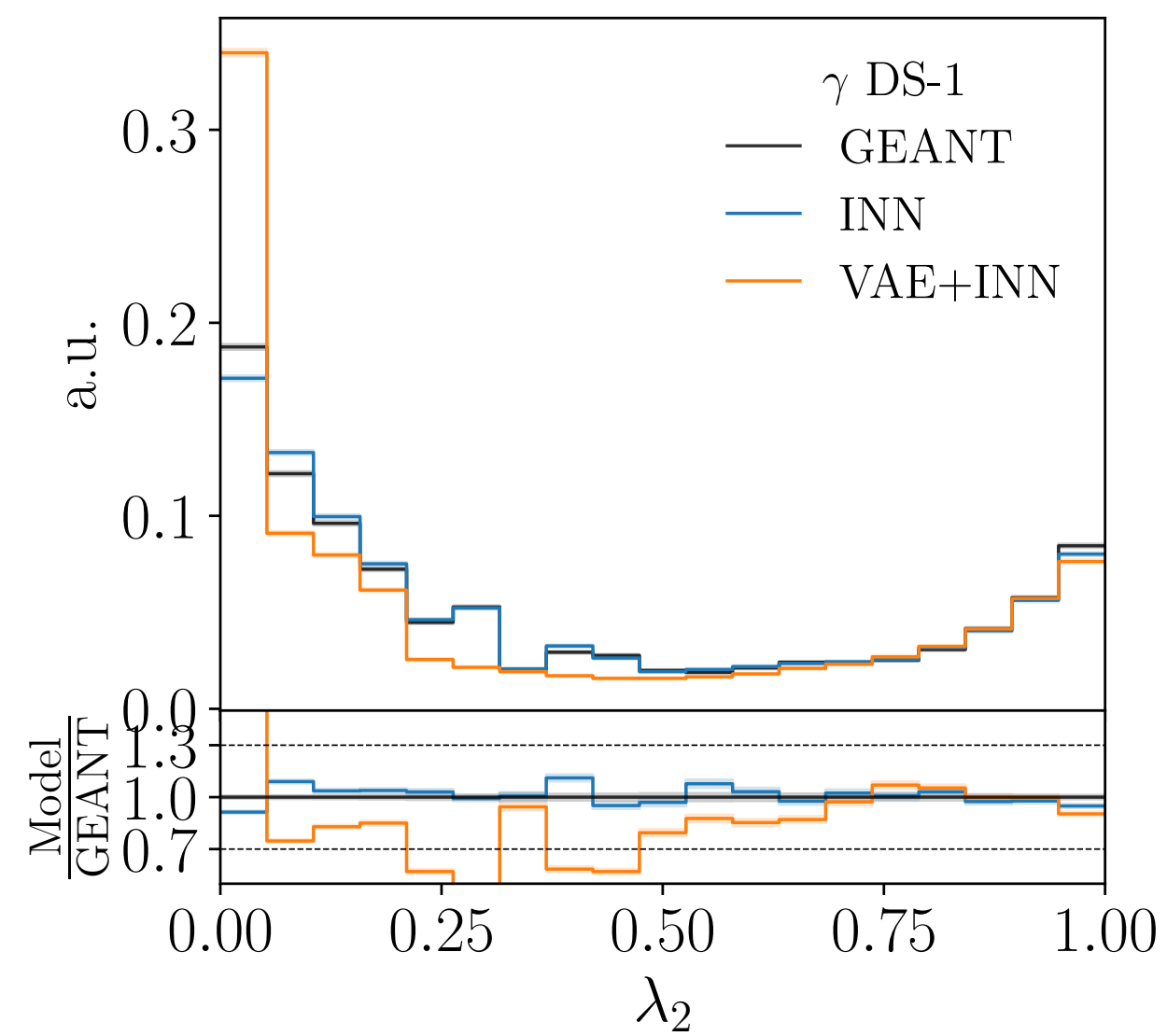
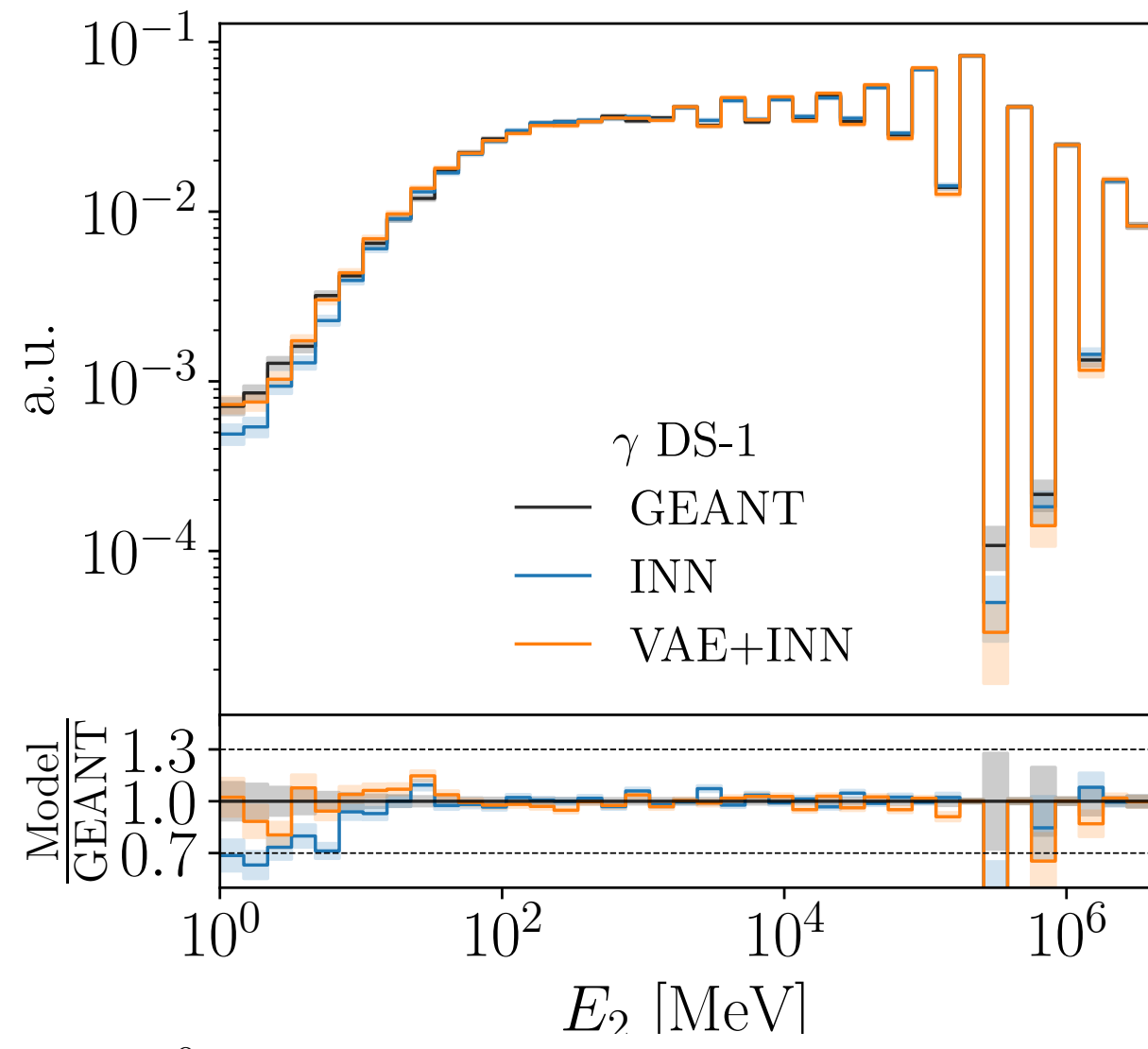
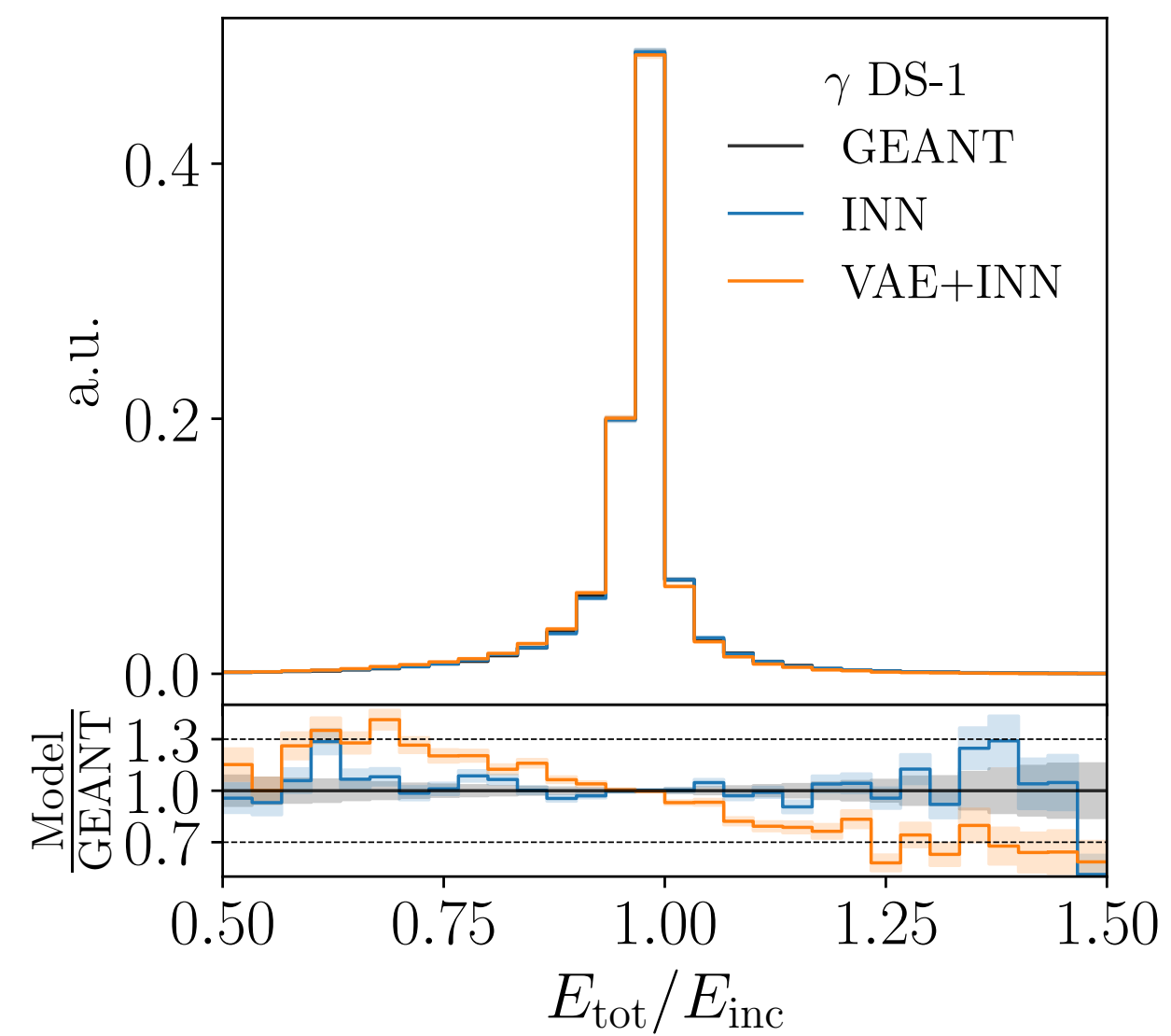
From DS1 to DS2

CaloINN

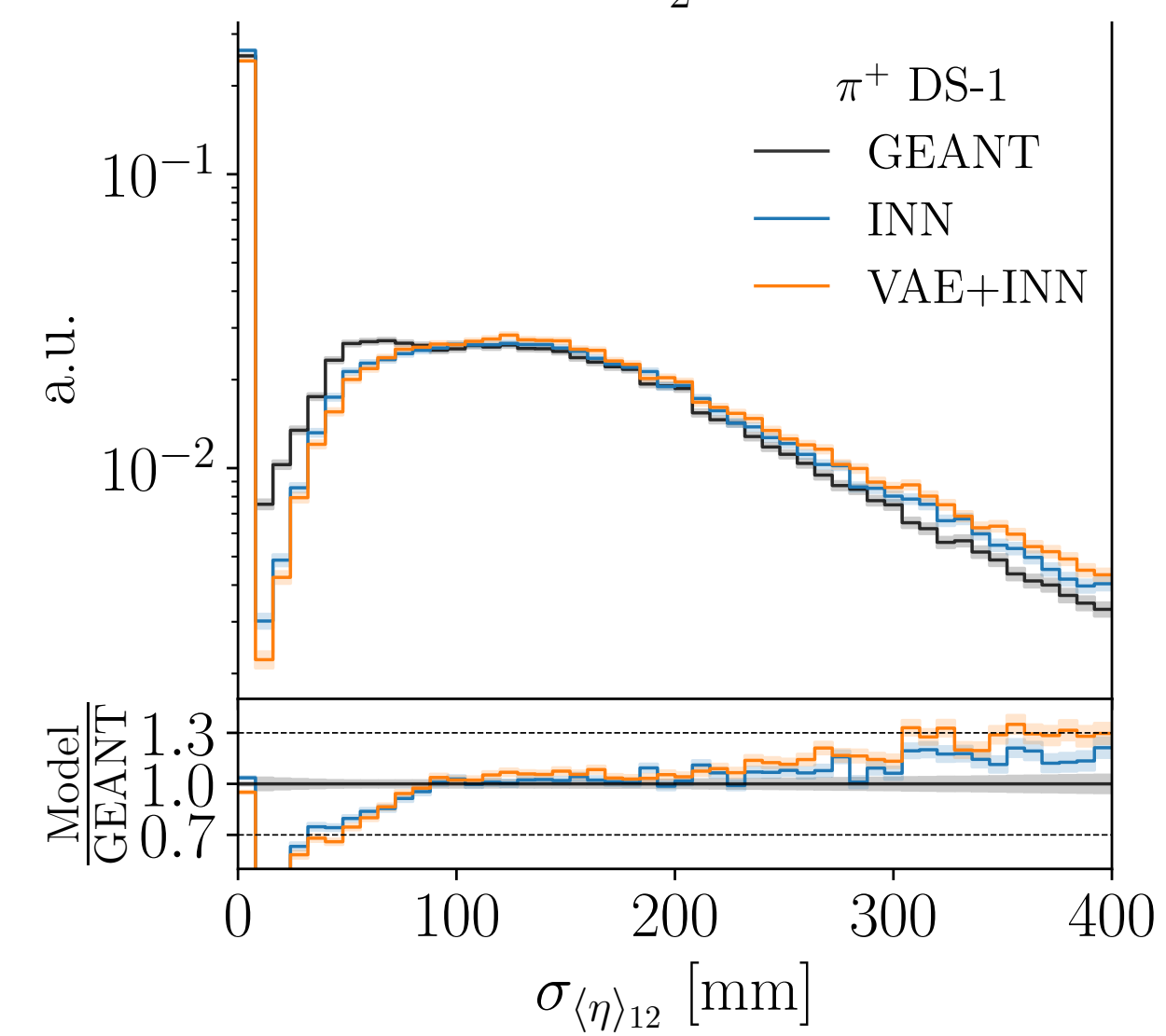
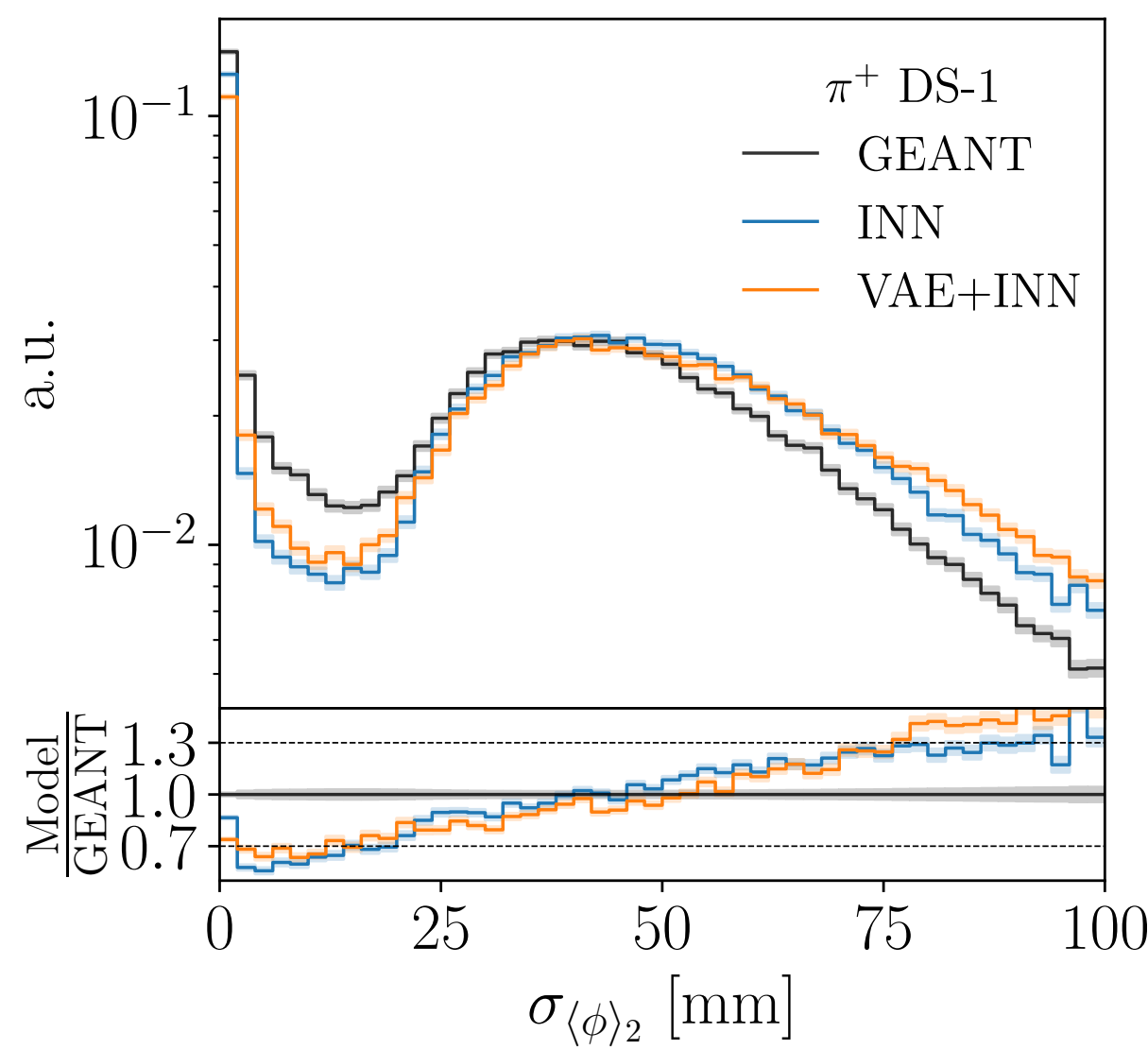
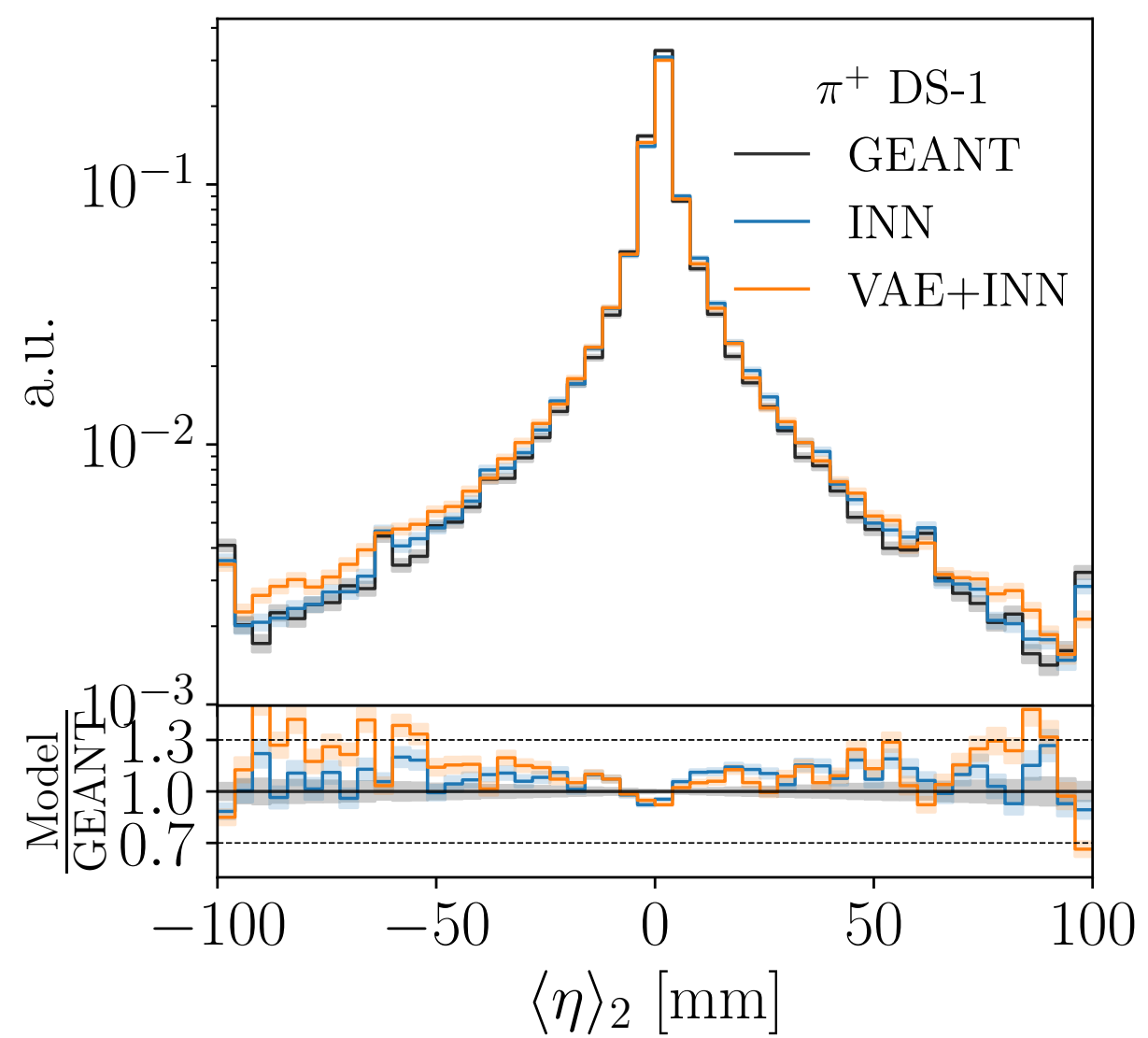
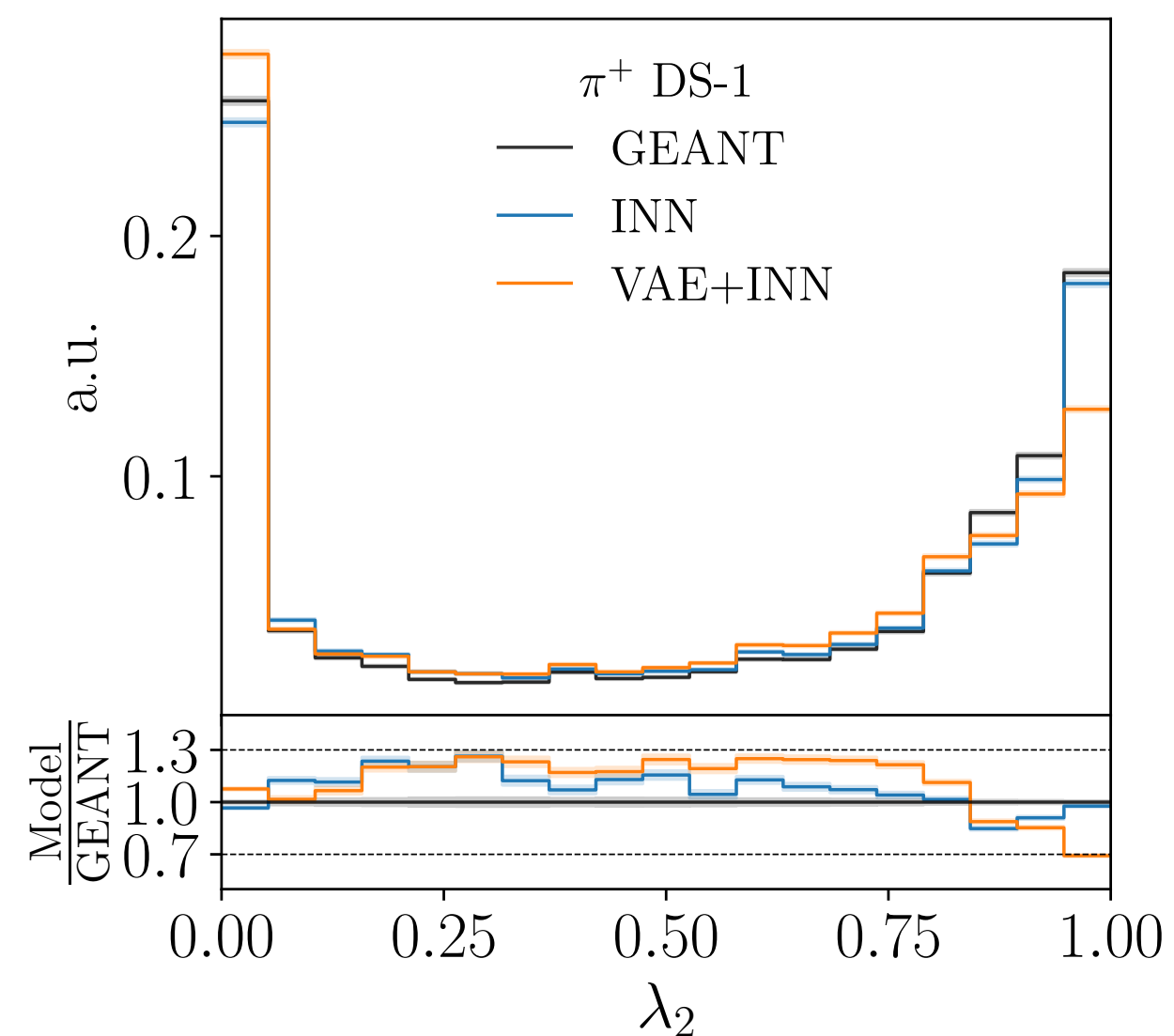
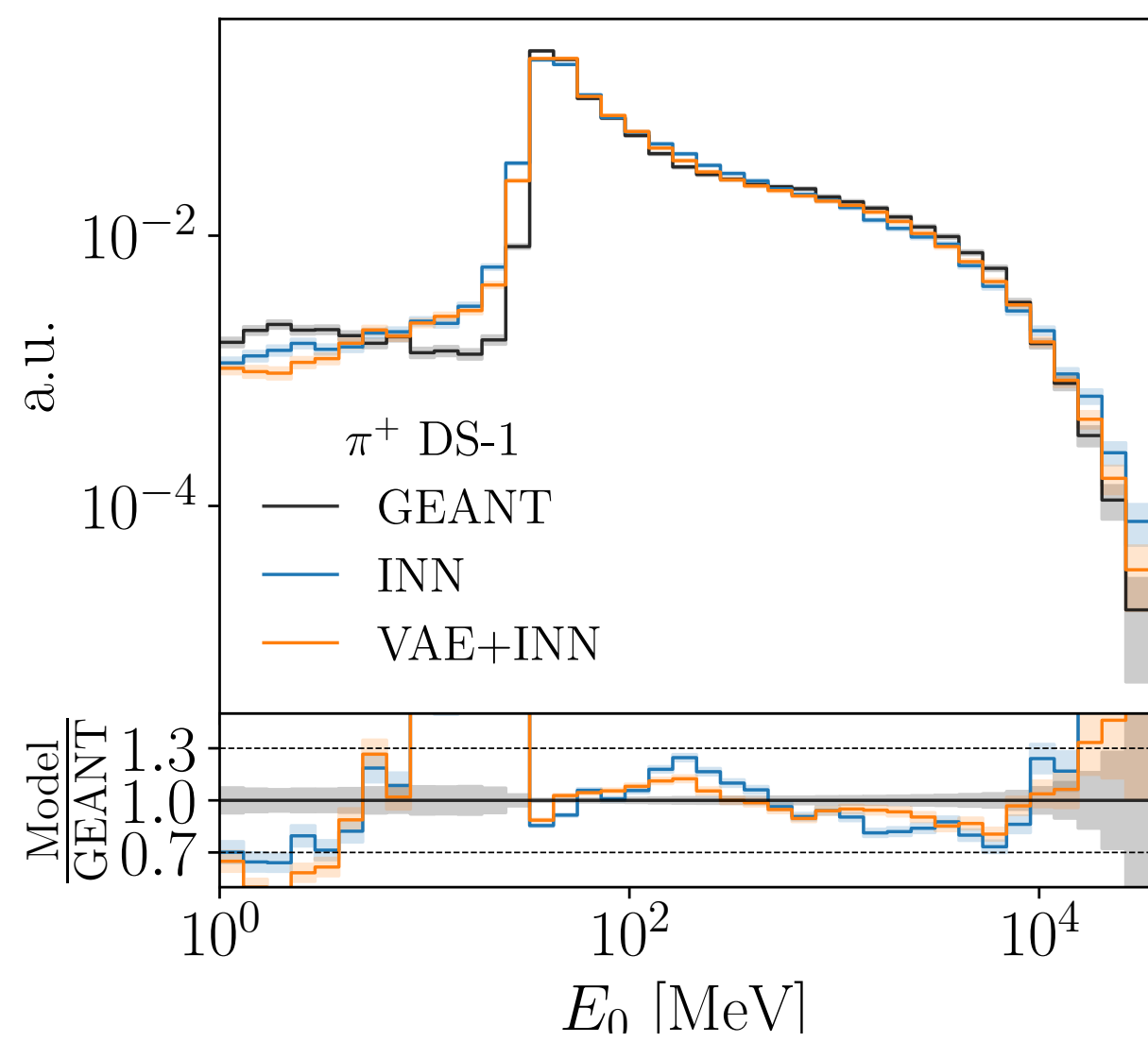
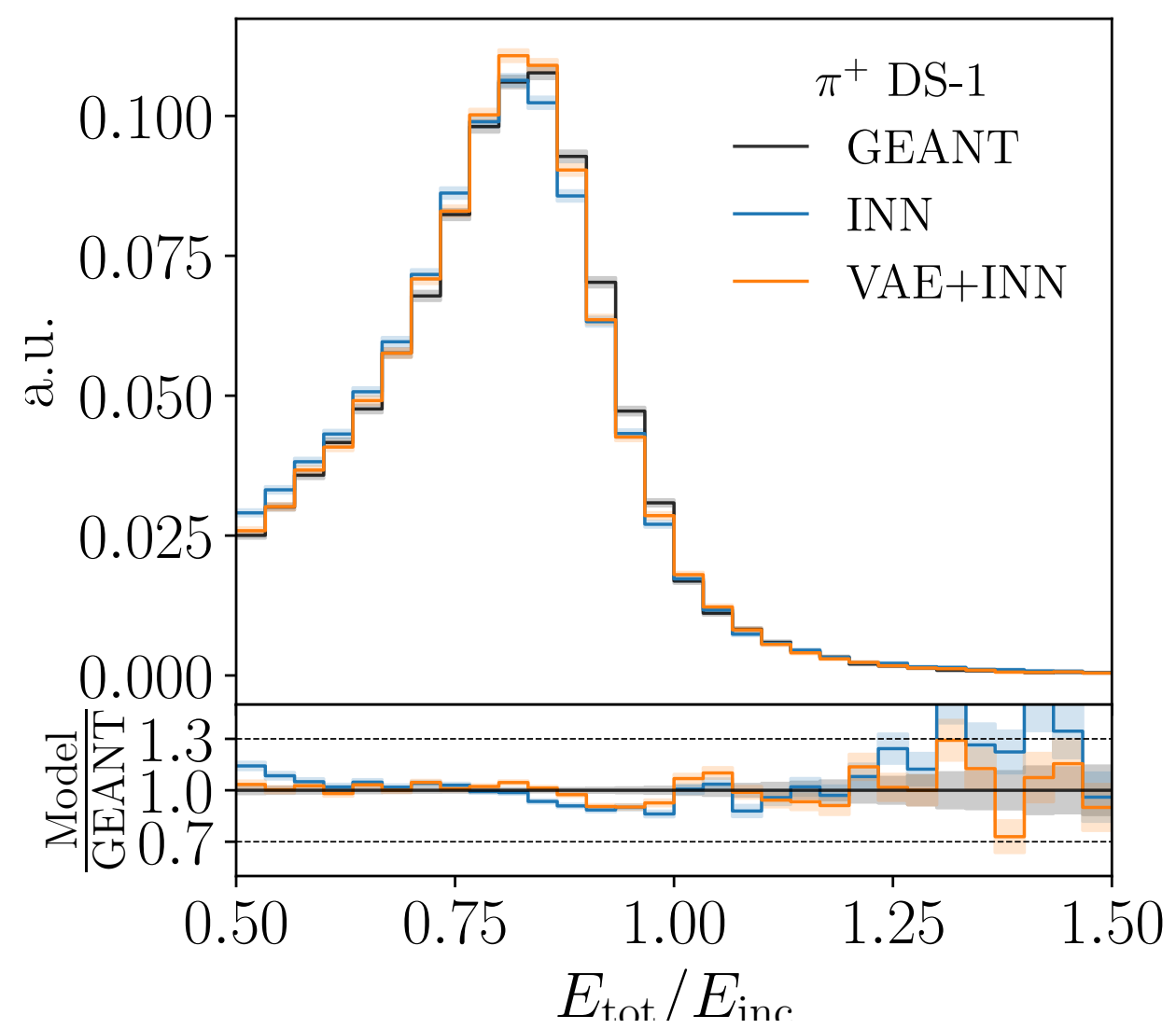


Check out the articles for more info on the architectures and open-source code!

DS1- histograms

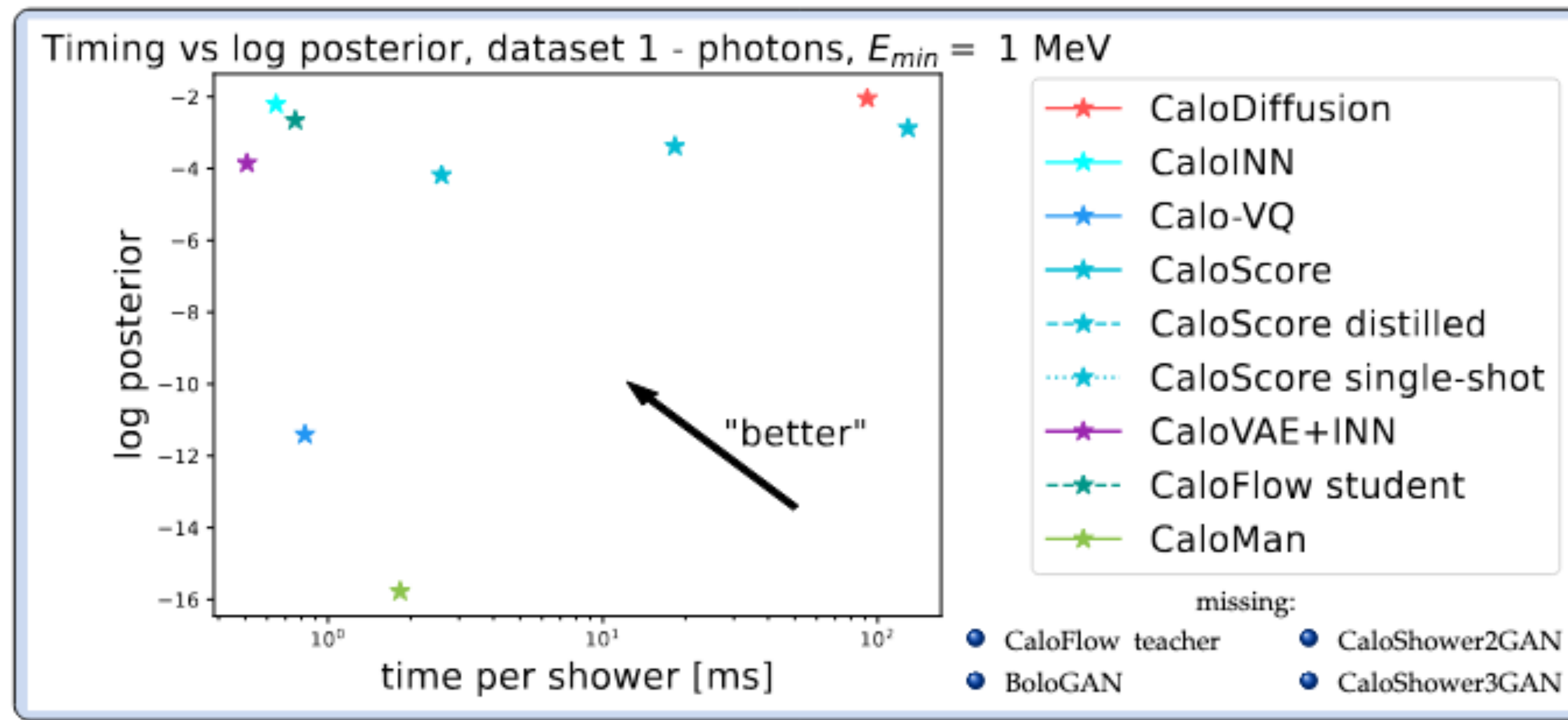


DS1- histograms



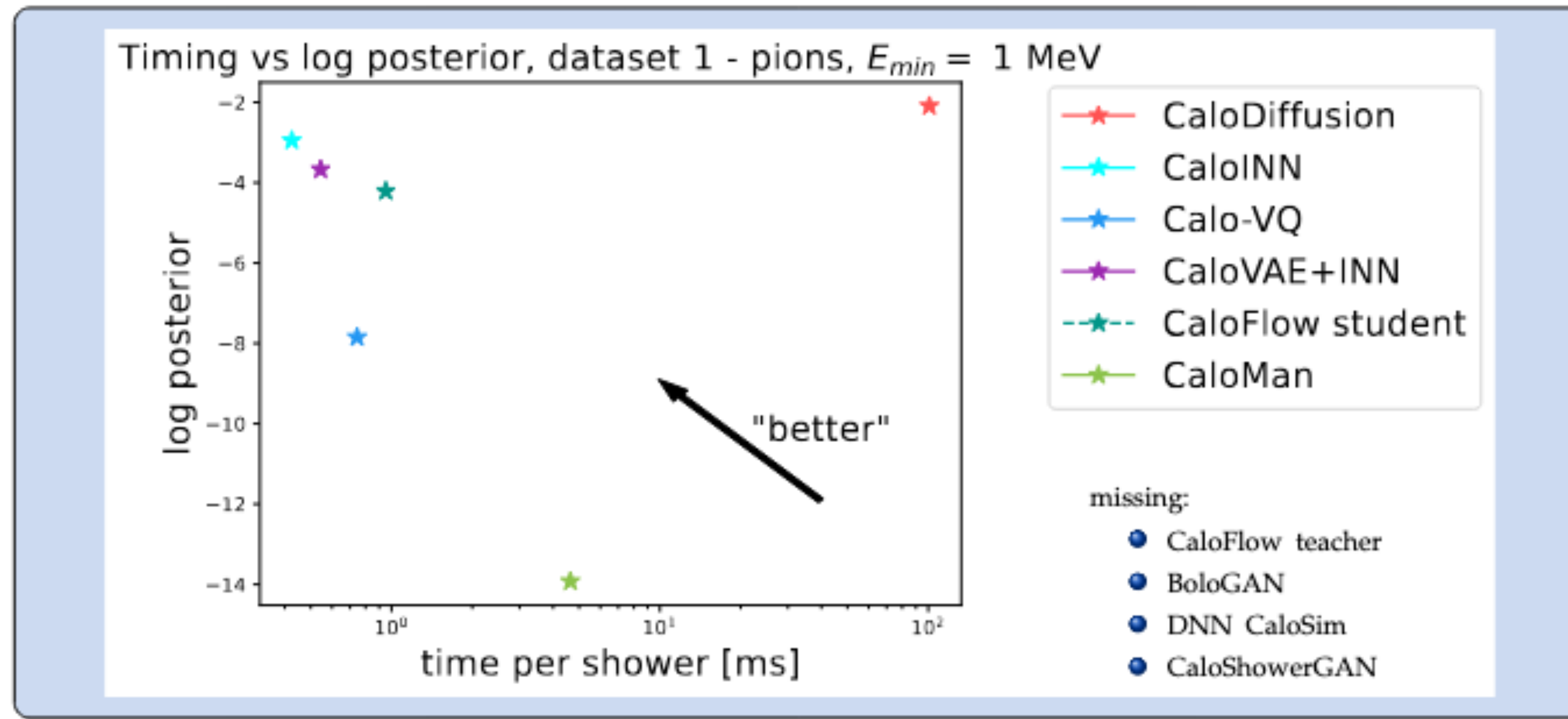
DS1 - timing

Generation Times (preliminary!) ds1 photons



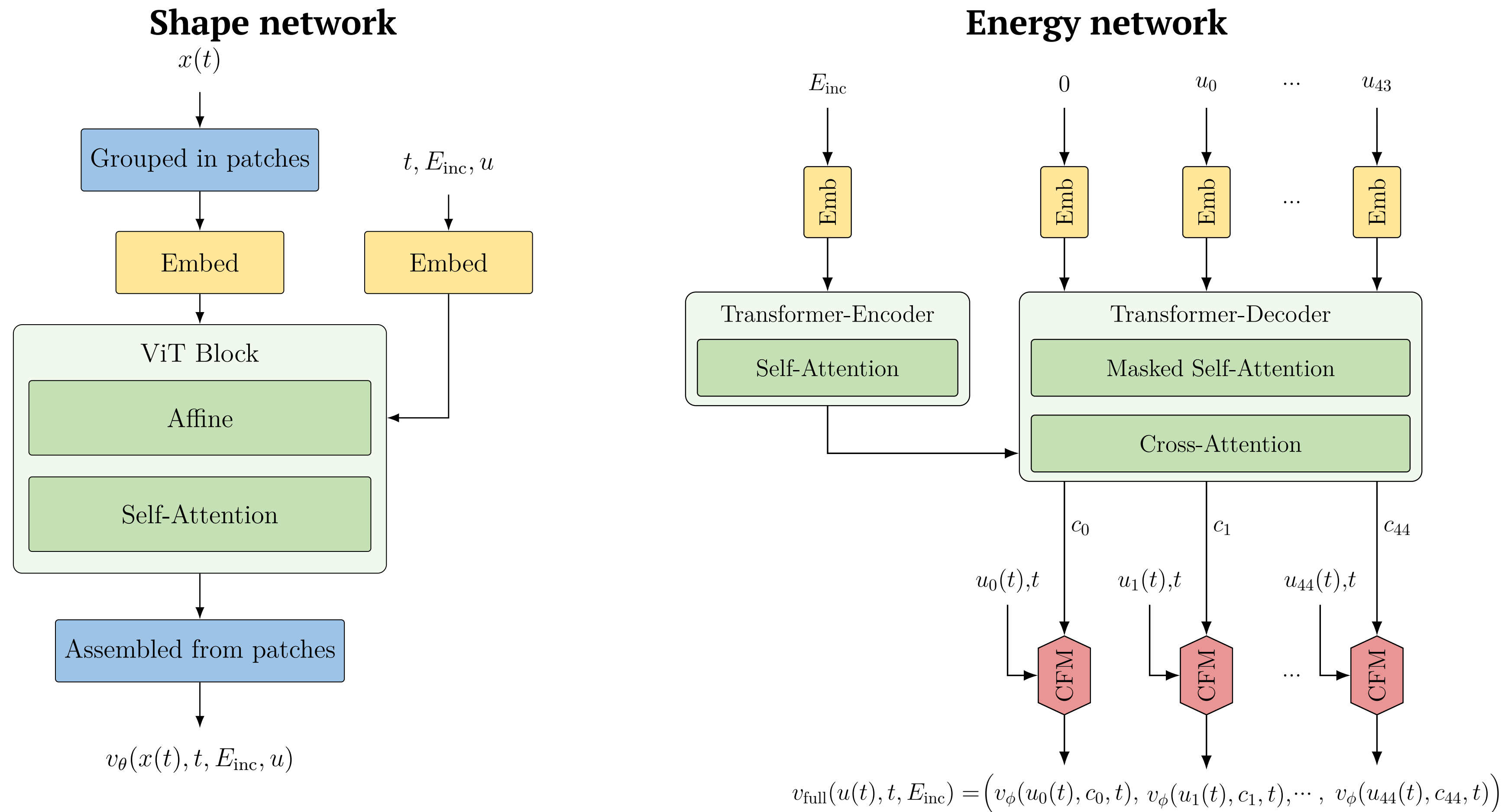
DS1 - timing

Generation Times (preliminary!) ds1 pions



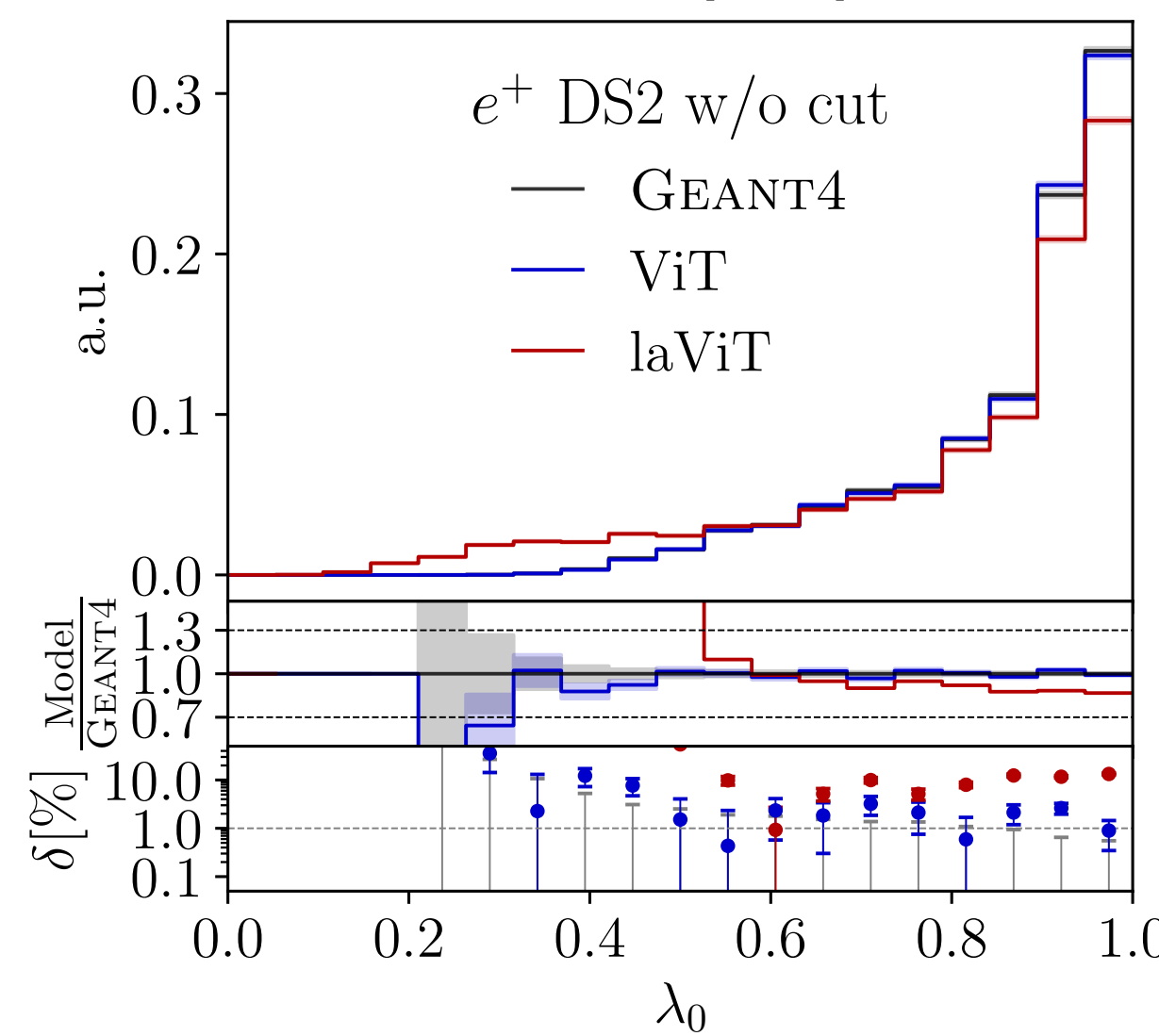
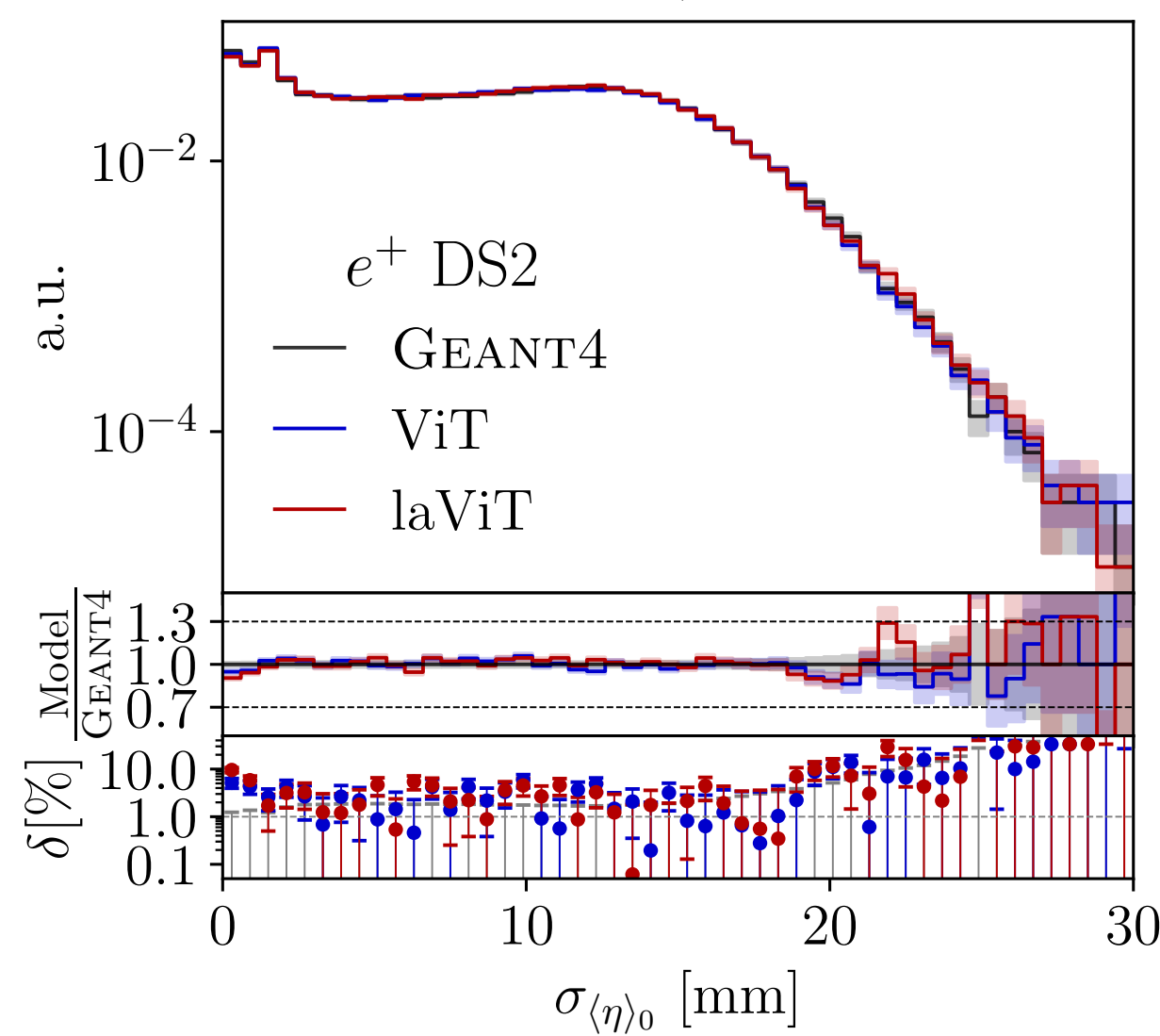
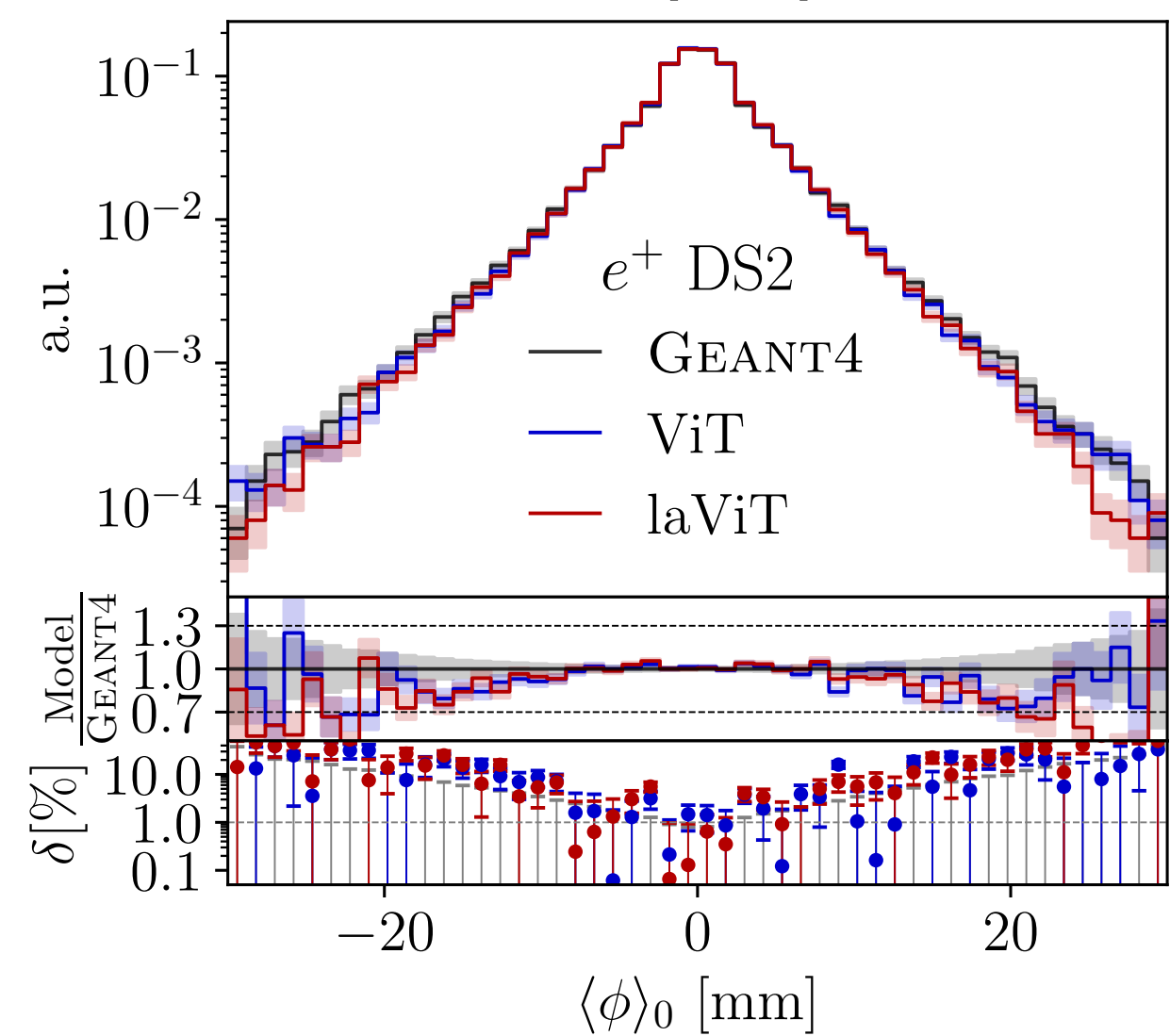
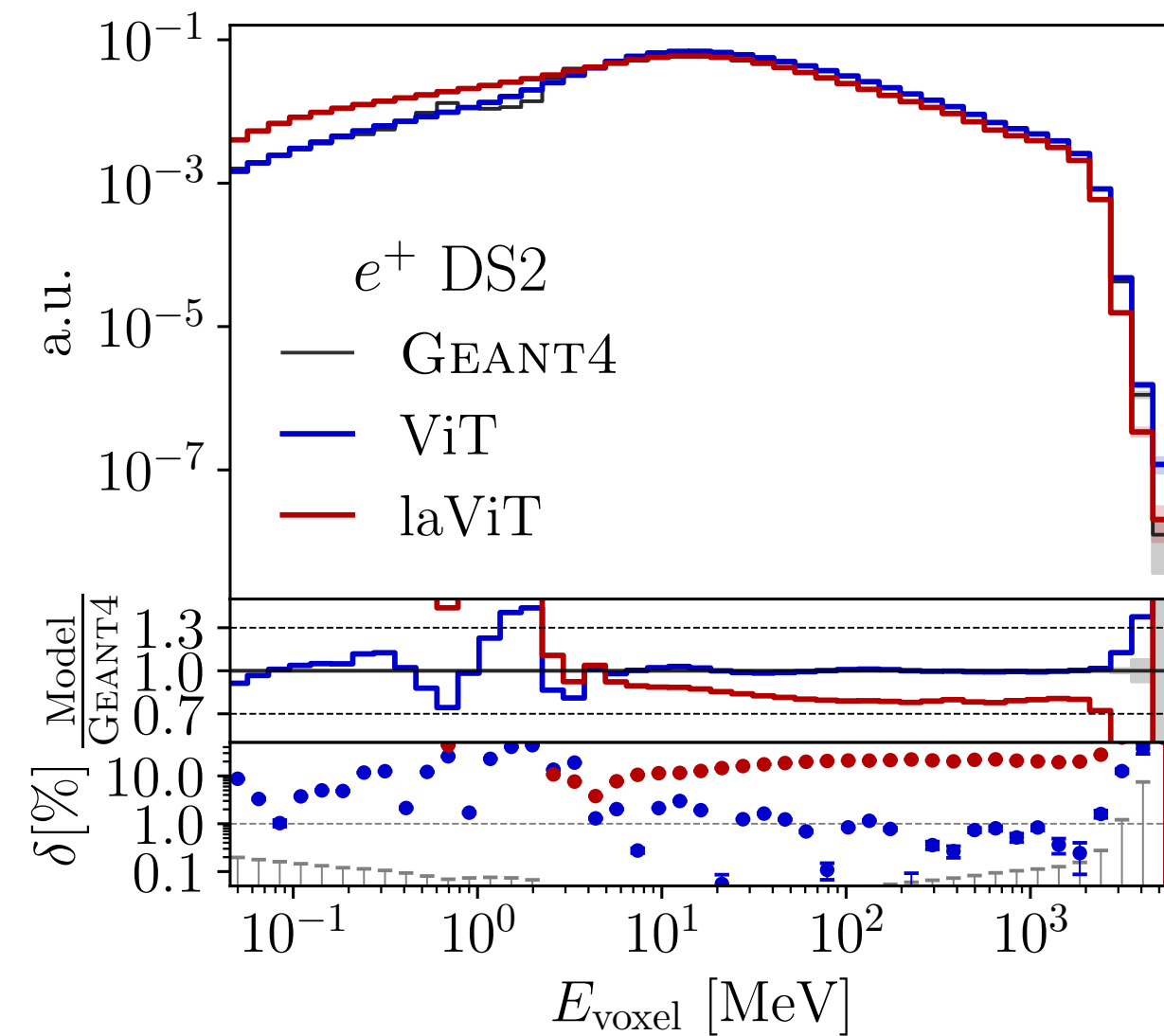
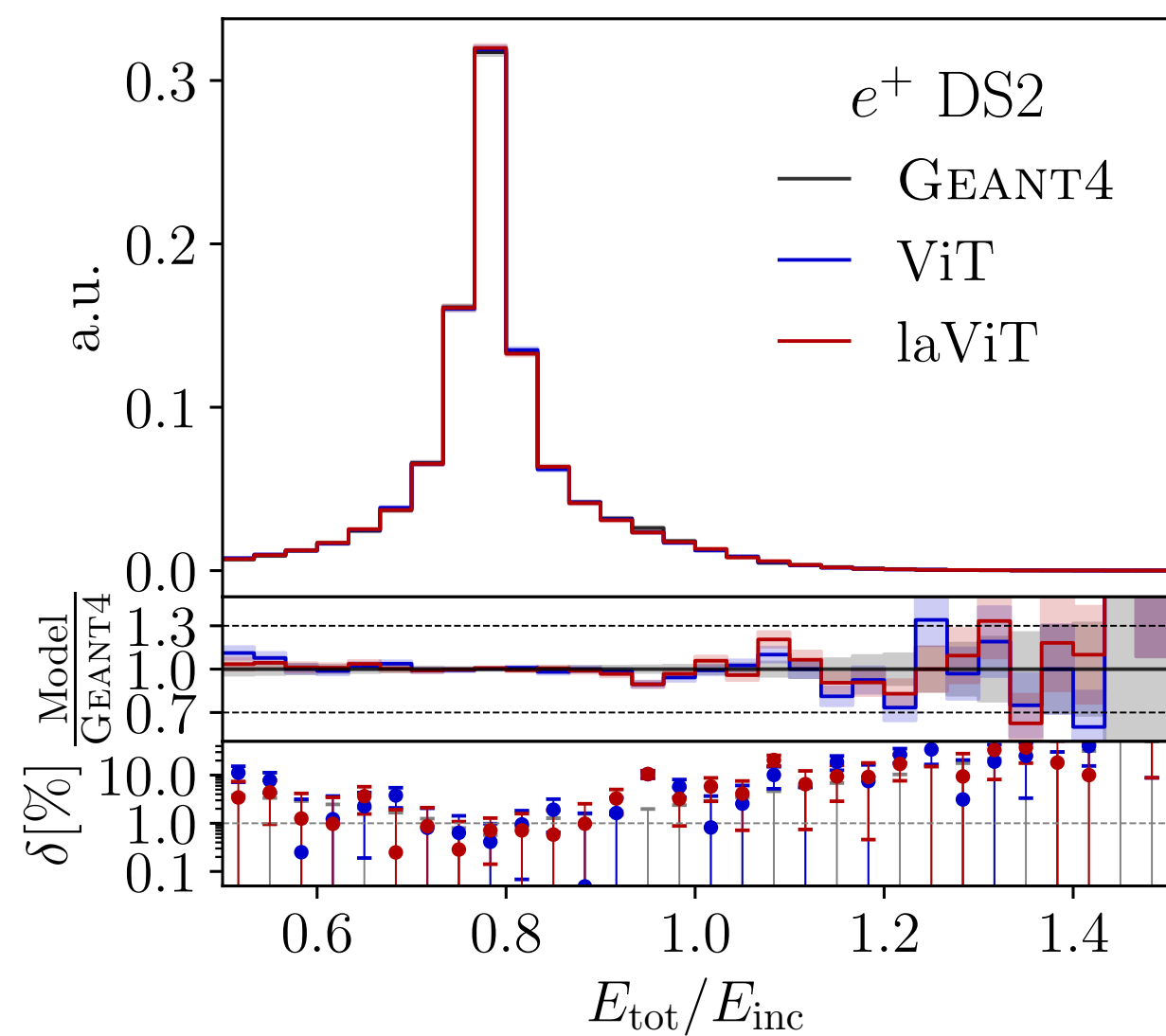
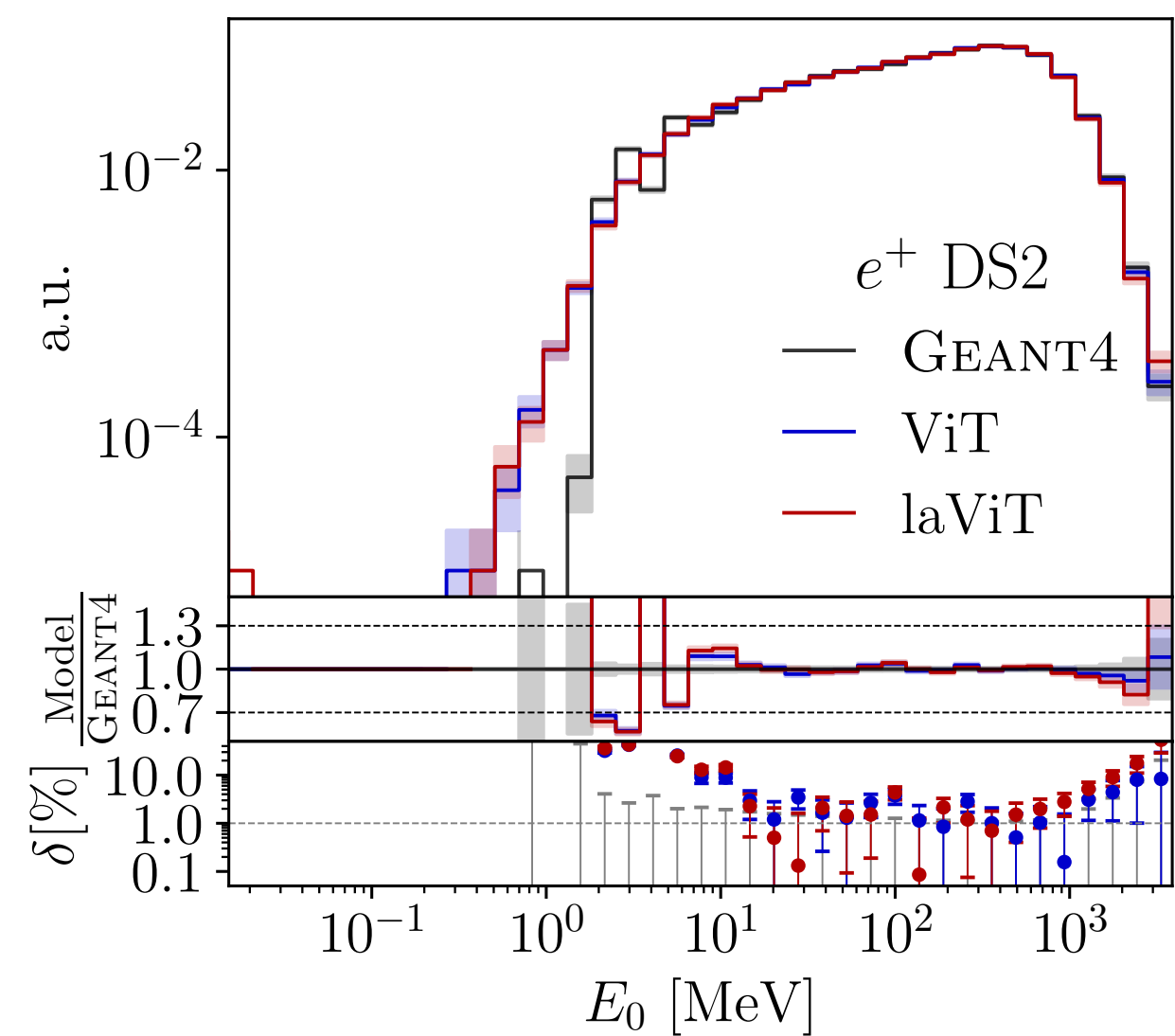
From DS1 to DS2/3

CaloDREAM

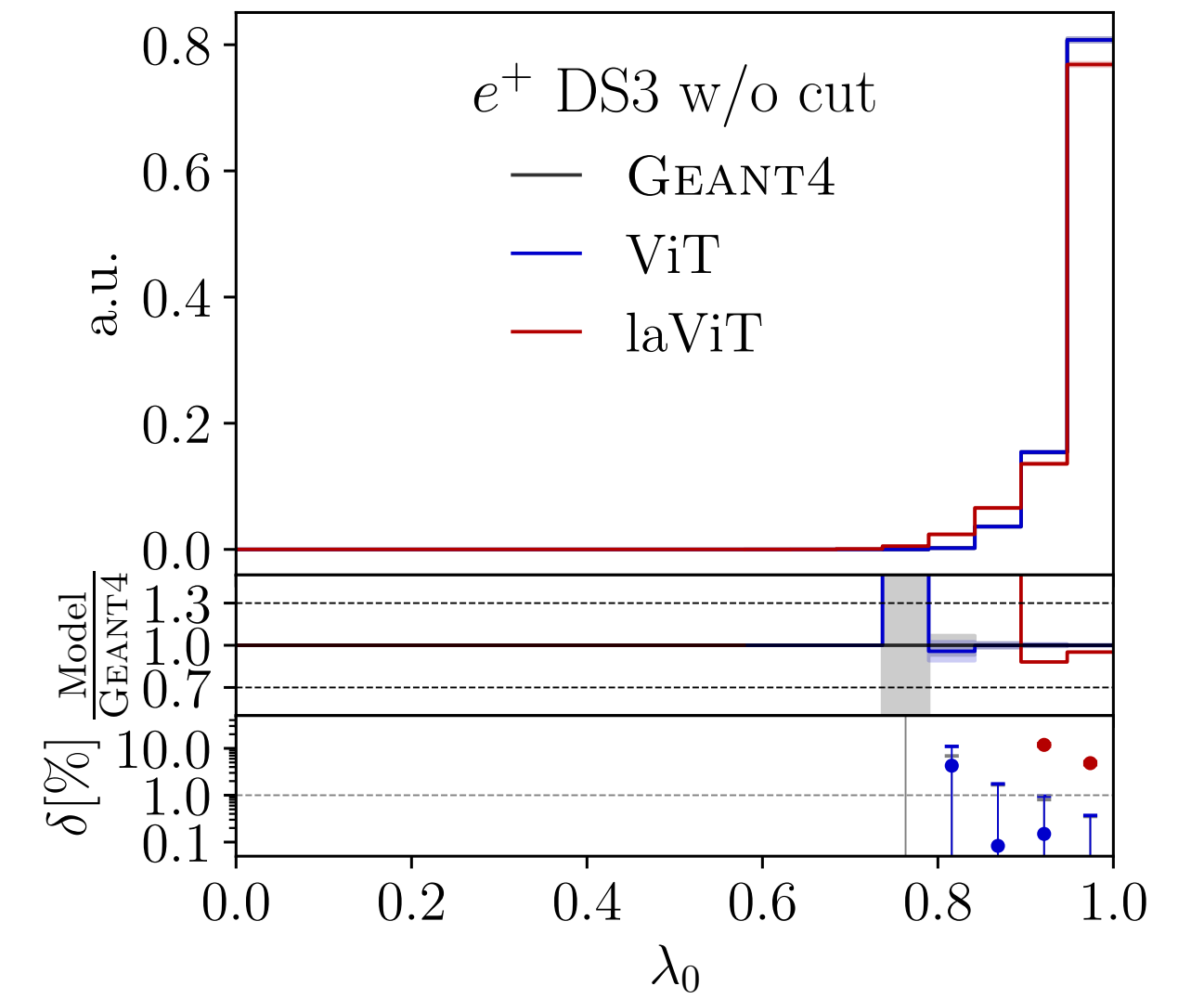
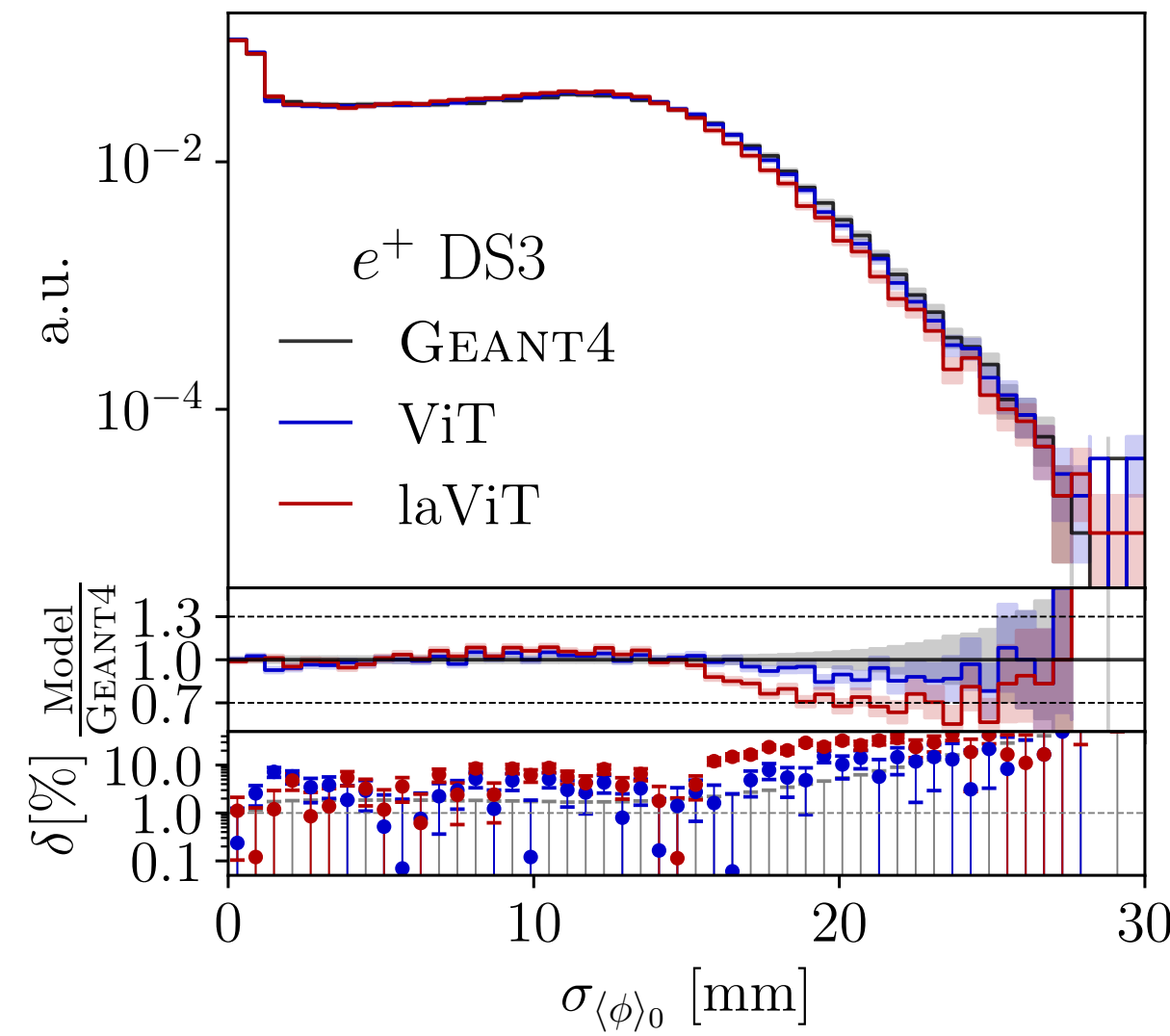
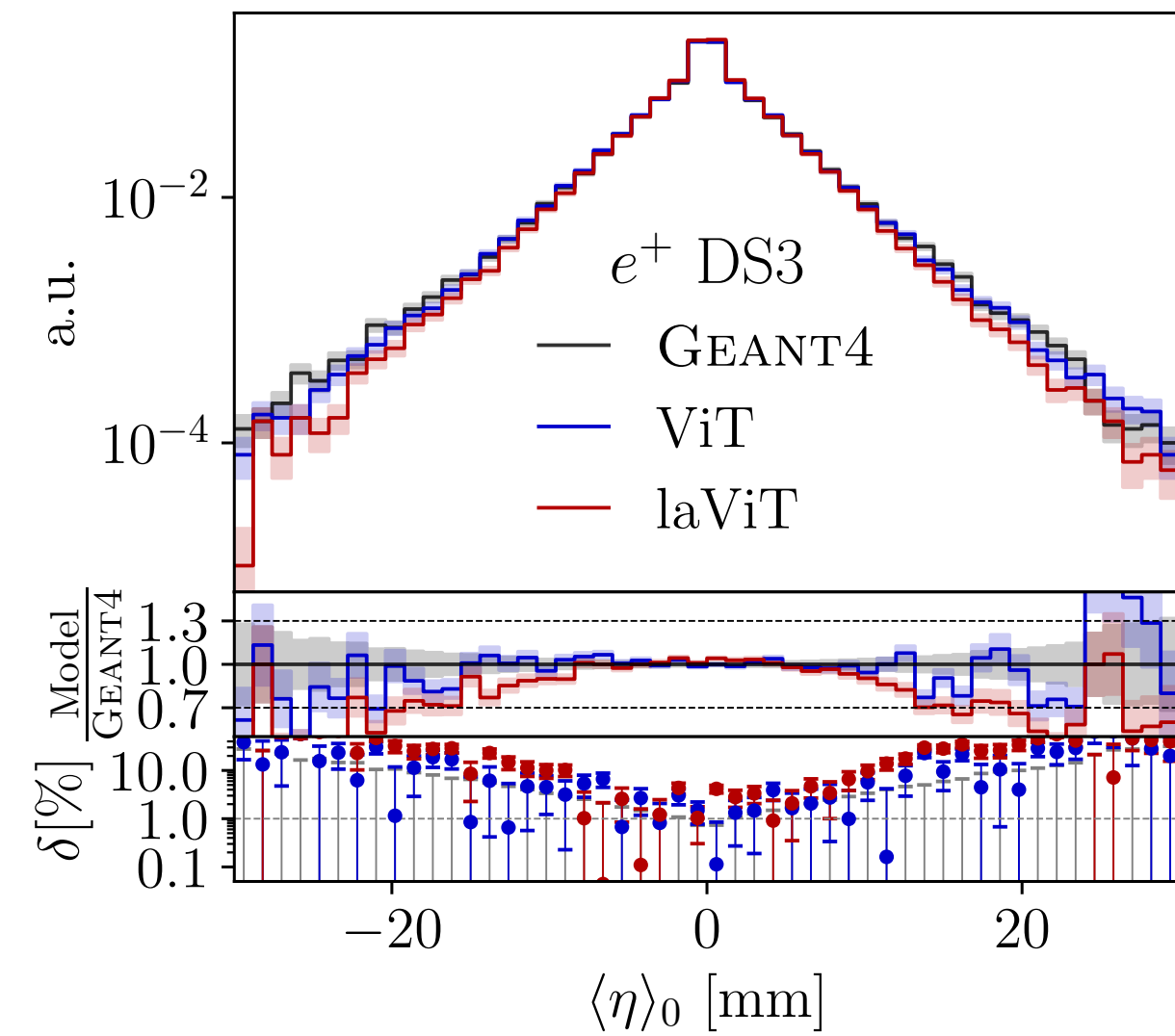
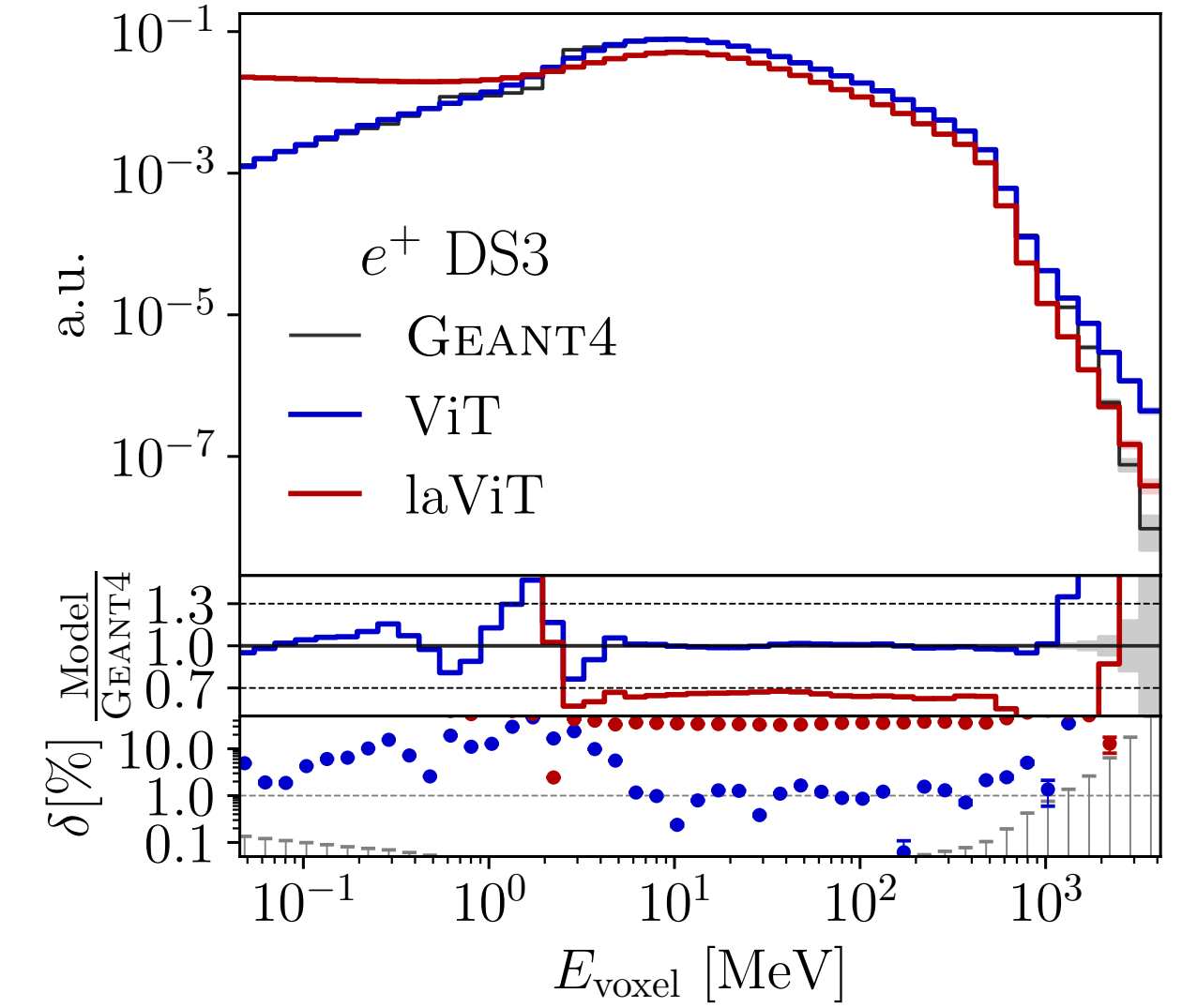
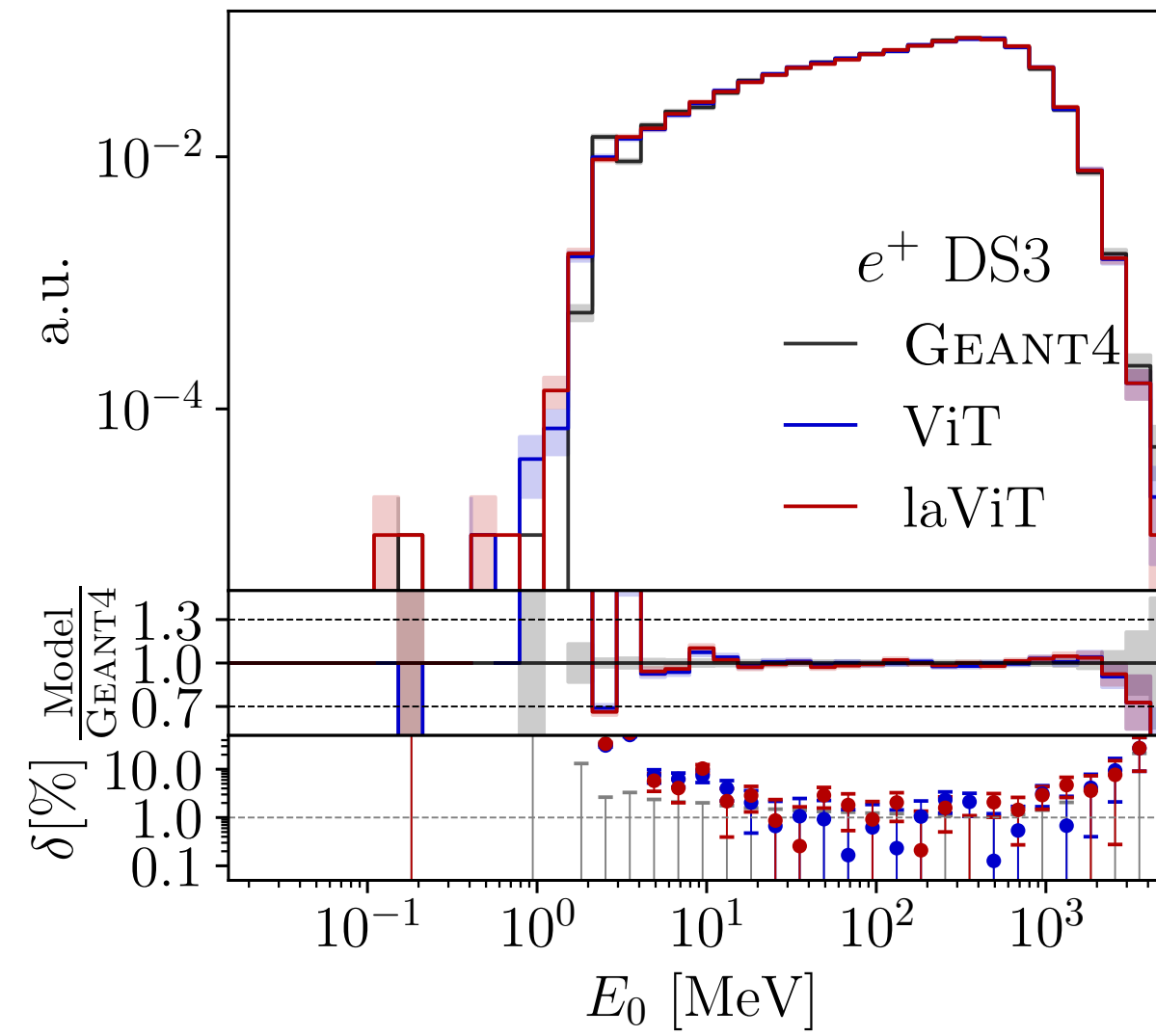
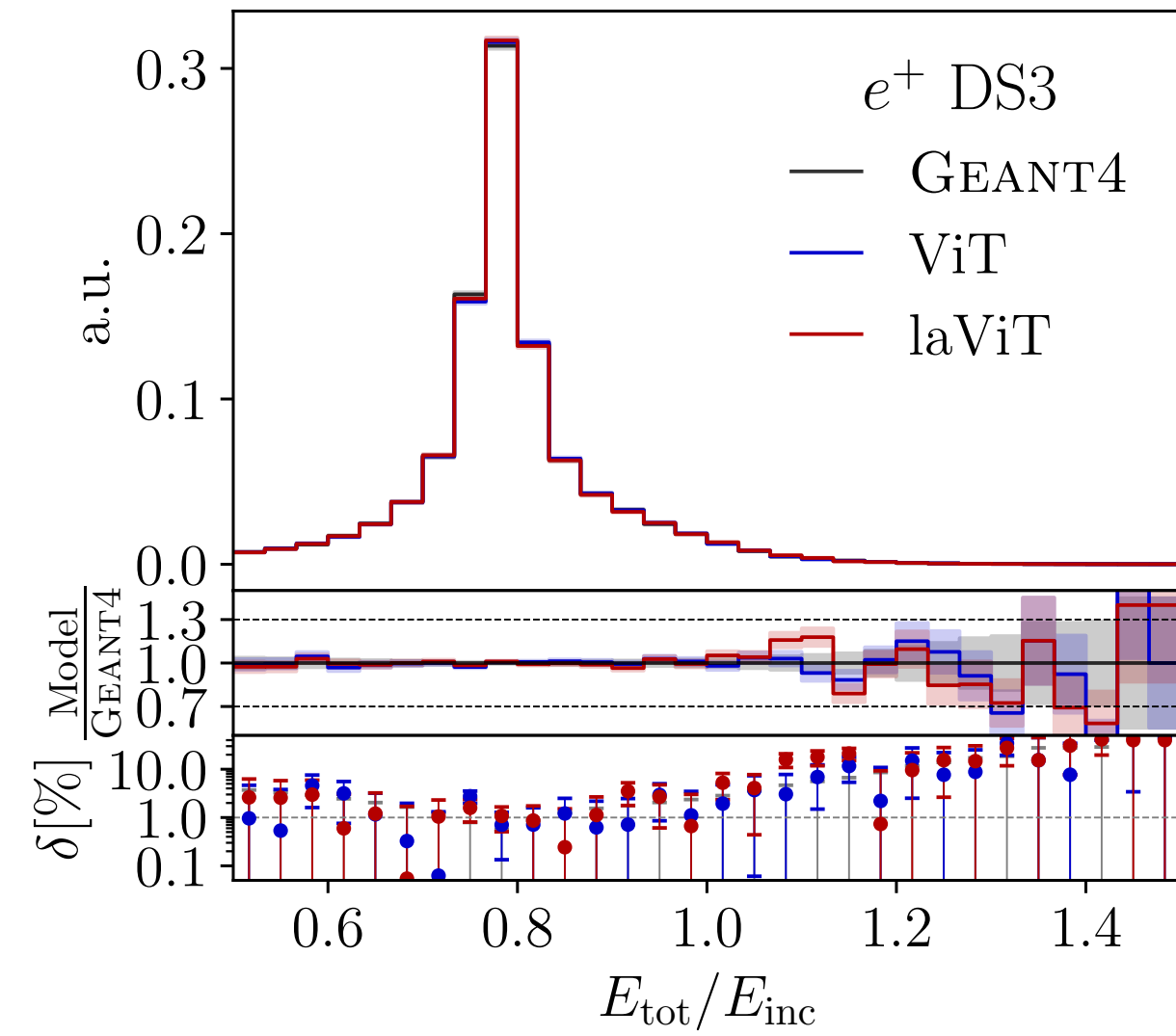


Check out the articles for more info on the architectures and open-source code!

DS2/3 - histograms



DS2/3 - histograms



The ultimate metric

from arXiv:2305.16774

- Classifiers are the best tools we have to test our generative networks;
- the output approximates the quantity:

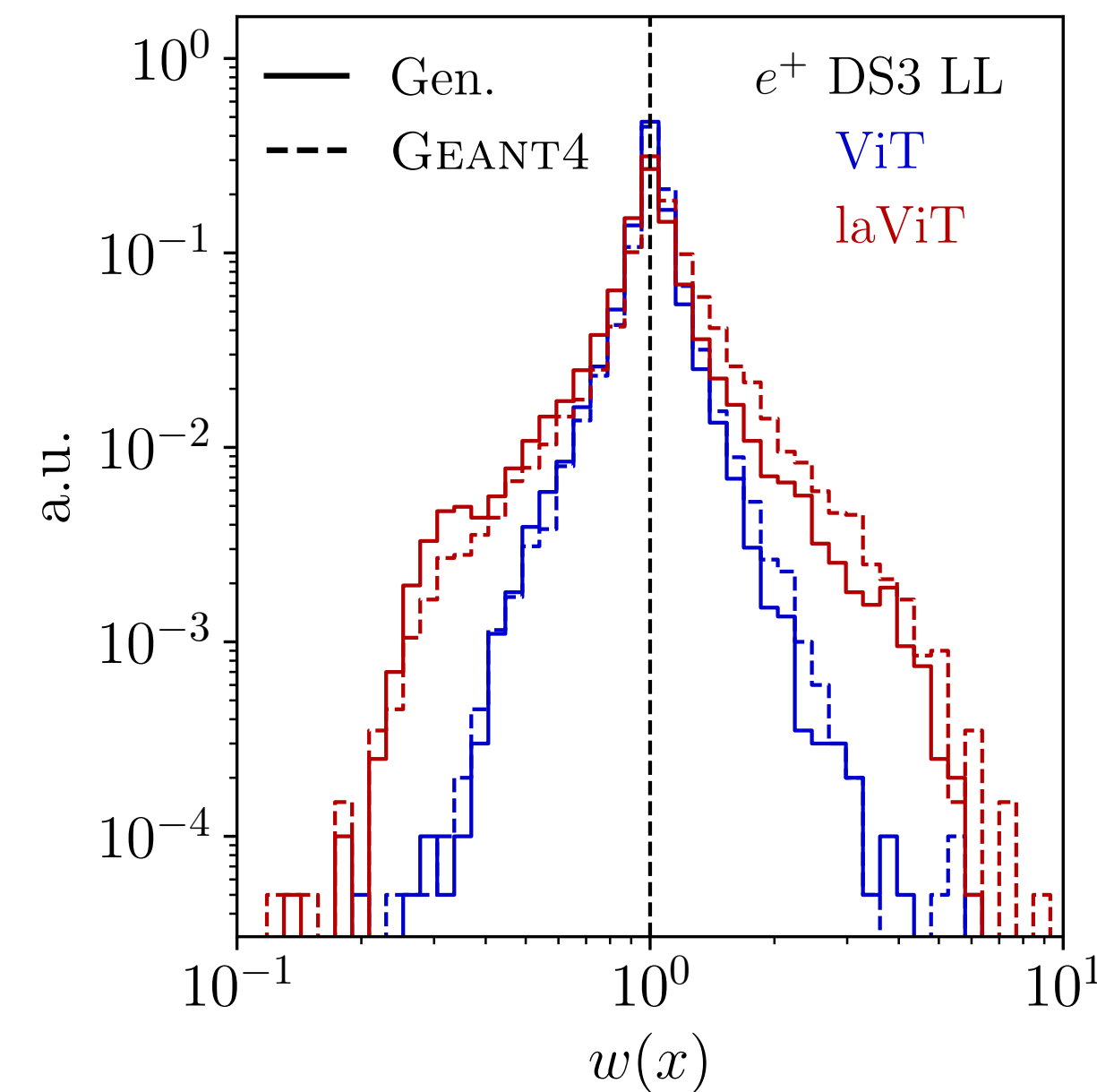
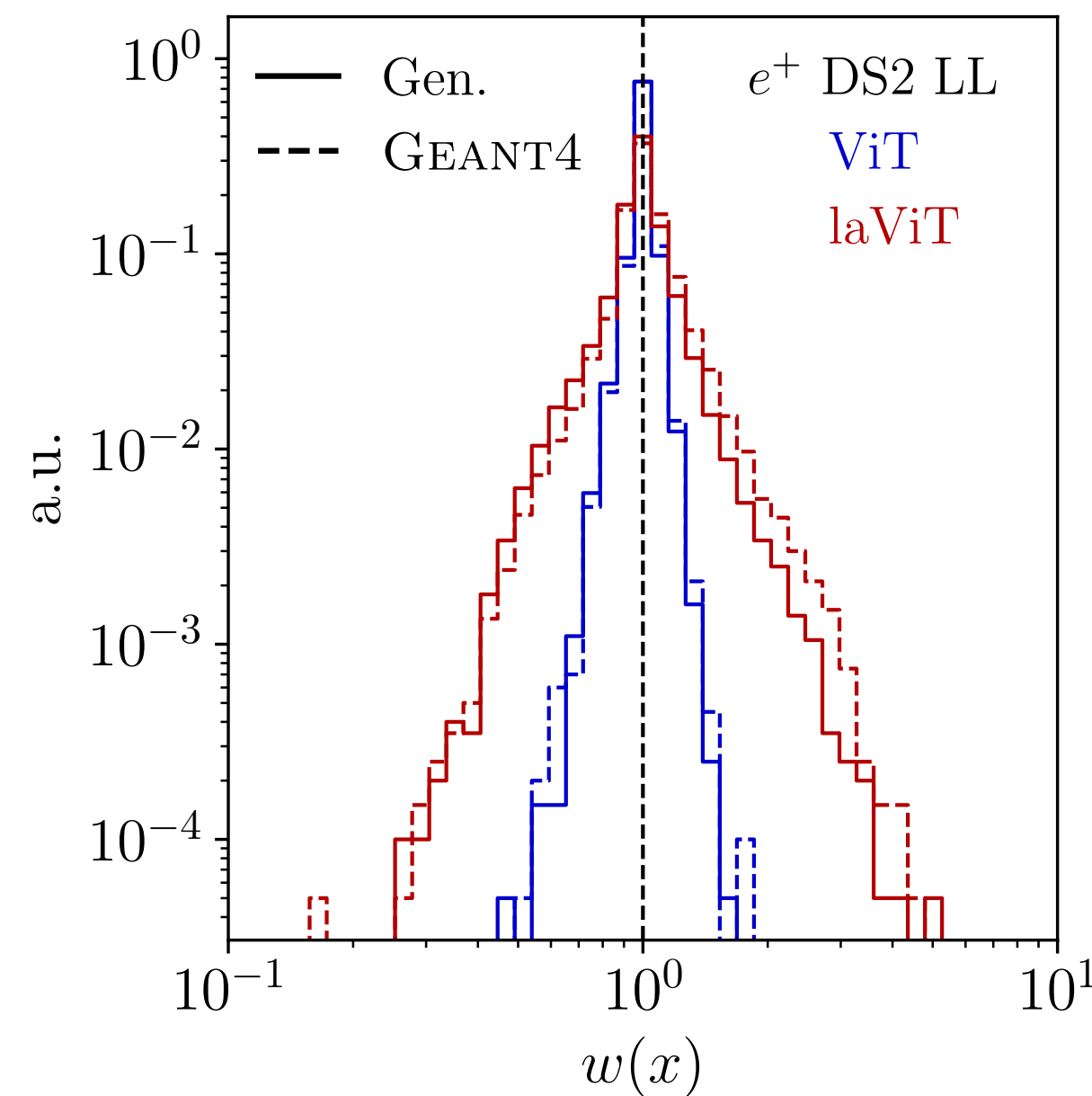
$$C(x) = \frac{P_{data}}{P_{data} + P_{\theta}} \qquad \frac{P_{data}}{P_{\theta}} = \frac{C(x)}{1 - C(x)}$$

- Optimal observable for a two hypothesis test according to the Neyman-Pearson lemma
- Proper training is essential: architecture, over-fitting, calibration,...
- we can easily extract weights from properly trained classifiers $\longrightarrow w(x) \approx \frac{P_{data}}{P_{\theta}}(x)$

The ultimate metric

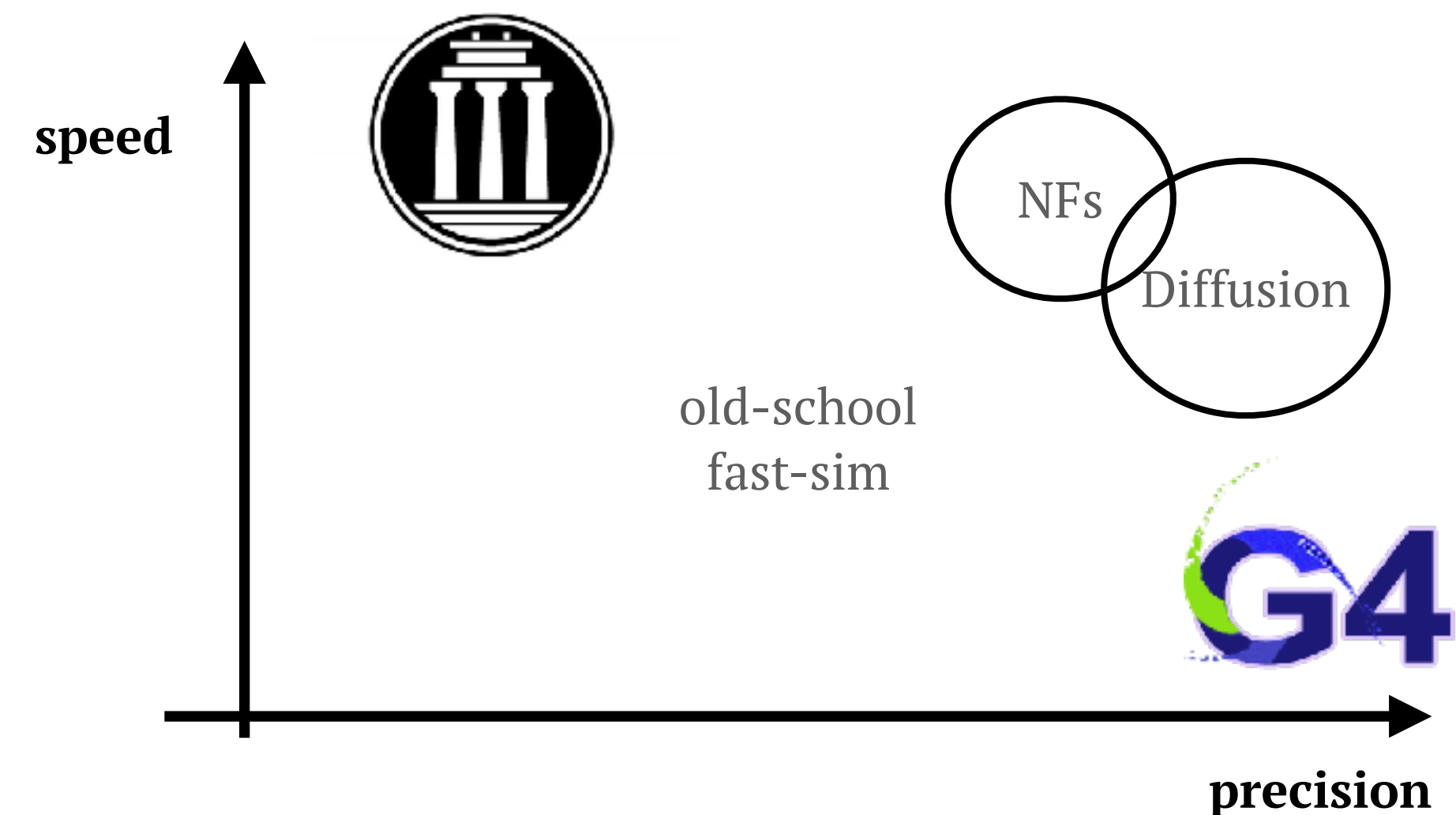
- Evaluation done in terms of the area-under-the-ROC (AUC) curve
 - indistinguishable samples if $AUC=0.5$
- Better to look at the weight distribution

	AUC (LL/HL)	
	DS2	DS3
ViT	0.54/0.52	0.63/0.53
laViT	0.58/0.53	0.62/0.59



Conclusions

- Very quick introduction on calorimeter simulations;
- even quicker introduction on the ML tools;
- Normalizing flows:
 - fast!;
 - CaloINN has even good performance on DS1;
 - non-trivial to expand to larger calorimeters.
- Conditional Flow Matching:
 - sampling requires more function evaluation;
 - a more involved architecture;
 - awesome performance.



Conclusions

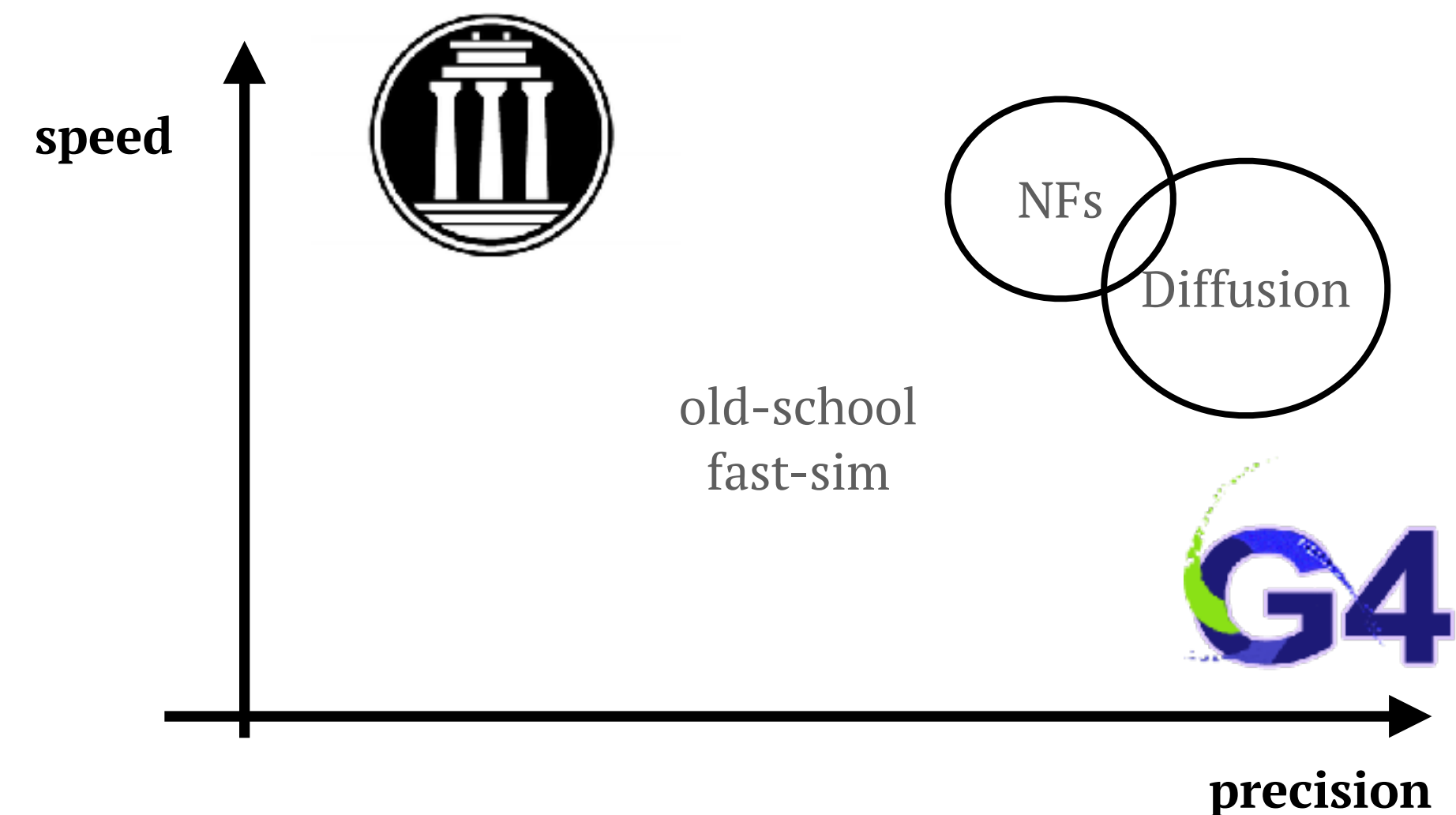
My open questions:

- is there a more efficient way of learning showers?
 - in high-dimensions sparsity is a problem;
 - point-cloud representation might be the answer.
- can we improve speed of diffusion networks?
- foundation models for detector simulation?

Looking at the future:

- how to implement such a network in the simulation chain?

Sidenote: only part of my PhD. I would also love to discuss about learning symmetries, anomaly detection, and unfolding.



Thank you for your attention!