

Deformation of Quantum Dynamics in Phase Space

Olivier Mattelaer

CP3

Plan

- Introduction

Plan

- Introduction
- Path Integral
 1. Definition
 2. Regularisation
 3. Deformation

Plan

- Introduction
- Path Integral
 1. Definition
 2. Regularisation
 3. Deformation
- Harmonic Oscillator
 1. Bosonic case
 2. Supersymmetric Case

Plan

- Introduction
- Path Integral
 1. Definition
 2. Regularisation
 3. Deformation
- Harmonic Oscillator
 1. Bosonic case
 2. Supersymmetric Case
- Field Theory

Plan

- Introduction
- Path Integral
 1. Definition
 2. Regularisation
 3. Deformation
- Harmonic Oscillator
 1. Bosonic case
 2. Supersymmetric Case
- Field Theory
- Conclusions and Perspectives

Introduction

Introduction

- non commutative geometry

Introduction

- non commutative geometry
 1. String theory

Introduction

- non commutative geometry
 1. String theory
 2. gravitation

Introduction

- non commutative geometry

1. String theory

2. gravitation

- Darboux theorem

$$\begin{array}{ll} \{x_i, x_j\} = \theta_{ij}^1 & \{ \tilde{x}_i, \tilde{x}_j \} = 0 \\ \{x_i, p_j\} = \theta_{ij}^2 & \longmapsto \{ \tilde{x}_i, \tilde{p}_j \} = \delta_{ij} \\ \{p_i, p_j\} = \theta_{ij}^3 & \{ \tilde{p}_i, \tilde{p}_j \} = 0 \end{array}$$

Introduction

- non commutative geometry

1. String theory

2. gravitation

- Darboux theorem

$$\begin{array}{ll} \{x_i, x_j\} = \theta_{ij}^1 & \{ \tilde{x}_i, \tilde{x}_j \} = 0 \\ \{x_i, p_j\} = \theta_{ij}^2 & \longmapsto \{ \tilde{x}_i, \tilde{p}_j \} = \delta_{ij} \\ \{p_i, p_j\} = \theta_{ij}^3 & \{ \tilde{p}_i, \tilde{p}_j \} = 0 \end{array}$$

- need an intrinsic meaning for x and p

Introduction

- non commutative geometry

1. String theory

2. gravitation

- Darboux theorem

$$\begin{array}{ll} \{x_i, x_j\} = \theta_{ij}^1 & \{ \tilde{x}_i, \tilde{x}_j \} = 0 \\ \{x_i, p_j\} = \theta_{ij}^2 & \longmapsto \{ \tilde{x}_i, \tilde{p}_j \} = \delta_{ij} \\ \{p_i, p_j\} = \theta_{ij}^3 & \{ \tilde{p}_i, \tilde{p}_j \} = 0 \end{array}$$

- need an intrinsic meaning for x and p
- Ultra-violet divergencies

Path Integral

Path Integral : Definition

- Quantum Mechanics : We have to Consider All trajectory

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

Path Integral : Definition

- Quantum Mechanics : We have to Consider All trajectory

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- What is the measure ?

Path Integral : Definition

- Quantum Mechanics : We have to Consider All trajectory

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- What is the measure ?
- What is S ?

Path Integral : Definition

- Quantum Mechanics : We have to Consider All trajectory

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- What is the measure ?
 - What is S ?
- Origin of this equation

Path Integral : Classical Description

- Start from an infinitesimal time generator $\hat{H}$. (Hamiltonian)

$$\lim_{T \rightarrow 0} U = e^{-\frac{i\hat{H}T}{\hbar}}$$

Path Integral : Classical Description

- Start from an infinitesimal time generator $\hat{H}$. (Hamiltonian)

$$\lim_{T \rightarrow 0} U = e^{-\frac{i\hat{H}T}{\hbar}}$$

- We will consider Time-slicing

$$U(T) = \prod_{n=1}^N U(\epsilon) = \prod_{n=1}^N e^{-\frac{i\hat{H}}{\hbar}\epsilon}$$

Path Integral : Classical Description

- Start from an infinitesimal time generator $\hat{H}$. (Hamiltonian)

$$\lim_{T \rightarrow 0} U = e^{-\frac{i\hat{H}T}{\hbar}}$$

- We will consider Time-slicing

$$U(T) = \prod_{n=1}^N U(\epsilon) = \prod_{n=1}^N e^{-\frac{i\hat{H}}{\hbar}\epsilon}$$

- We want path integral $\Rightarrow$ resolution of identity

$$\int dx dp |x, p\rangle \langle x, p| = Id$$

$$U(T) = \int \prod_{n=1}^N \langle x_{n-1}, p_{n-1} | e^{-\frac{i\hat{H}}{\hbar}\epsilon} | x_n, p_n \rangle$$

Path Integral : Classical Description

- Start from an infinitesimal time generator $\hat{H}$. (Hamiltonian)

$$\lim_{T \rightarrow 0} U = e^{-\frac{i\hat{H}T}{\hbar}}$$

- We will consider Time-slicing

$$U(T) = \prod_{n=1}^N U(\epsilon) = \prod_{n=1}^N e^{-\frac{i\hat{H}}{\hbar}\epsilon}$$

- We want path integral $\Rightarrow$ resolution of identity

$$\int dx dp |x, p\rangle \langle x, p| = Id$$

$$U(T) = \int \prod_{n=1}^N \langle x_{n-1}, p_{n-1} | e^{-\frac{i\hat{H}}{\hbar}\epsilon} | x_n, p_n \rangle$$

- Some algebraic manipulation

$$U(T) = \int \prod_{n=1}^N \langle x_{n-1}, p_{n-1} | x_n, p_n \rangle e^{-i\frac{h_n}{\hbar}\epsilon}$$

Path Integral : Classical Description

- Start from an infinitesimal time generator $\hat{H}$. (Hamiltonian)

$$\lim_{T \rightarrow 0} U = e^{-\frac{i\hat{H}T}{\hbar}}$$

- We will consider Time-slicing

$$U(T) = \prod_{n=1}^N U(\epsilon) = \prod_{n=1}^N e^{-\frac{i\hat{H}}{\hbar}\epsilon}$$

- We want path integral $\Rightarrow$ resolution of identity

$$\int dx dp |x, p\rangle \langle x, p| = Id$$

$$U(T) = \int \prod_{n=1}^N \langle x_{n-1}, p_{n-1} | e^{-\frac{i\hat{H}}{\hbar}\epsilon} | x_n, p_n \rangle$$

- Some algebraic manipulation

$$U(T) = \int \prod_{n=1}^N \langle x_{n-1}, p_{n-1} | x_n, p_n \rangle e^{-i\frac{h_n}{\hbar}\epsilon}$$

- $\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle \sim e^{\frac{i}{\hbar}\epsilon[\frac{1}{2}(\dot{x}p - x\dot{p})]}$

Path Integral : Classical Description

- Start from an infinitesimal time generator $\hat{H}$. (Hamiltonian)

$$\lim_{T \rightarrow 0} U = e^{-\frac{i\hat{H}T}{\hbar}}$$

- We will consider Time-slicing

$$U(T) = \prod_{n=1}^N U(\epsilon) = \prod_{n=1}^N e^{-\frac{i\hat{H}}{\hbar}\epsilon}$$

- We want path integral $\Rightarrow$ resolution of identity

$$\int dx dp |x, p\rangle \langle x, p| = Id$$

$$U(T) = \int \prod_{n=1}^N \langle x_{n-1}, p_{n-1} | e^{-\frac{i\hat{H}}{\hbar}\epsilon} | x_n, p_n \rangle$$

- Some algebraic manipulation

$$U(T) = \int \prod_{n=1}^N \langle x_{n-1}, p_{n-1} | x_n, p_n \rangle e^{-i\frac{h_n}{\hbar}\epsilon}$$

- $\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle \sim e^{\frac{i}{\hbar}\epsilon[\frac{1}{2}(\dot{x}p - x\dot{p})]}$

- taking explicit limit on time

$$U(T) = \int \prod_{n=1}^{N-1} dx_n dp_n e^{\frac{i}{\hbar} \int dt [\frac{1}{2}(\dot{x}p - x\dot{p}) - H(x, p)]}$$

Path Integral : Classical Description

-

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

Path Integral : Classical Description

-

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- Definition of the measure (via a limit process)

Path Integral : Classical Description

-

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- Definition of the measure (via a limit process)
- definition of the action (in coherent state representation)

Path Integral : Classical Description

-

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- Definition of the measure (via a limit process)
- definition of the action (in coherent state representation)
- But

Path Integral : Classical Description

-

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- Definition of the measure (via a limit process)
- definition of the action (in coherent state representation)
- But
 1. the limit of the measure is not defined

Path Integral : Classical Description

-

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- Definition of the measure (via a limit process)
- definition of the action (in coherent state representation)
- But
 1. the limit of the measure is not defined
 2. the correspondance principle (linked to this) doesn't work in general

Path Integral : Classical Description

-

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{iS}{\hbar}}$$

- Definition of the measure (via a limit process)
- definition of the action (in coherent state representation)
- But
 1. the limit of the measure is not defined
 2. the correspondance principle (linked to this) doesn't work in general
- We need a correct definition for the measure

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle \sim e^{\frac{i}{\hbar} \epsilon [\frac{1}{2} (\dot{x}p - x\dot{p})]}$$

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2} (\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2}(\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

- correct limit in $\epsilon \rightarrow 0$

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2}(\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

- correct limit in $\epsilon \rightarrow 0$
- Regularisation :

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{i}{\hbar} \int dt [\frac{1}{2}(\dot{x}p - x\dot{p}) - H - \frac{i}{4\Omega} \tau (\dot{x}^2 + \Omega^2 \dot{p}^2)]}$$

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2}(\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

- correct limit in $\epsilon \rightarrow 0$
- Regularisation :

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{i}{\hbar} \int dt [\frac{1}{2}(\dot{x}p - x\dot{p}) - H - \frac{i}{4\Omega} \tau (\dot{x}^2 + \Omega^2 \dot{p}^2)]}$$

- Introduction of gaussian term

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2}(\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

- correct limit in $\epsilon \rightarrow 0$
- Regularisation :

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{i}{\hbar} \int dt [\frac{1}{2}(\dot{x}p - x\dot{p}) - H - \frac{i}{4\Omega} \tau (\dot{x}^2 + \Omega^2 \dot{p}^2)]}$$

- Introduction of gaussian term
- Wiener Measur with time diffusion $=\tau$

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2}(\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

- correct limit in $\epsilon \rightarrow 0$
- Regularisation :

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{i}{\hbar} \int dt [\frac{1}{2}(\dot{x}p - x\dot{p}) - H - \frac{i}{4\Omega} \tau (\dot{x}^2 + \Omega^2 \dot{p}^2)]}$$

- Introduction of gaussian term
- Wiener Measur with time diffusion $=\tau$
- recover usual quantum mechanics for $\lim_{\tau \rightarrow 0}$

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2}(\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

- correct limit in $\epsilon \rightarrow 0$
- Regularisation :

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{i}{\hbar} \int dt [\frac{1}{2}(\dot{x}p - x\dot{p}) - H - \frac{i}{4\Omega} \tau (\dot{x}^2 + \Omega^2 \dot{p}^2)]}$$

- Introduction of gaussian term
- Wiener Measur with time diffusion $=\tau$
- recover usual quantum mechanics for $\lim_{\tau \rightarrow 0}$
- metric on phase space

Path Integral : Regularisation

- overlap function

$$\langle x_{n-1}, p_{n-1} | x_n, p_n \rangle = e^{\frac{i}{\hbar} \epsilon [\frac{1}{2}(\dot{x}p - x\dot{p})]} e^{-\frac{1}{4\hbar\Omega} \epsilon^2 (\dot{x}^2 + \Omega^2 \dot{p}^2)}$$

- correct limit in $\epsilon \rightarrow 0$
- Regularisation :

$$U = \int \mathcal{D}x \mathcal{D}p e^{\frac{i}{\hbar} \int dt [\frac{1}{2}(\dot{x}p - x\dot{p}) - H - \frac{i}{4\Omega} \tau (\dot{x}^2 + \Omega^2 \dot{p}^2)]}$$

- Introduction of gaussian term
- Wiener Measur with time diffusion $=\tau$
- recover usual quantum mechanics for $\lim_{\tau \rightarrow 0}$
- metric on phase space
- more general quantification

Path Integral : Deformation

- τ is a physical parameter

Path Integral : Deformation

- τ is a physical parameter
- introduction of a fundamental length

Path Integral : Deformation

- τ is a physical parameter
- introduction of a fundamental length
- give a intrinsic sense at x, p via a metric

Path Integral : Deformation

- τ is a physical parameter
- introduction of a fundamental length
- give a intrinsic sense at x, p via a metric
- non-commutative geometry

Path Integral : Deformation

- τ is a physical parameter
- introduction of a fundamental length
- give a intrinsic sense at x, p via a metric
- non-commutative geometry
- cure UV divergencies

Some Deformation

Harmonic Oscillator

- Harmonic Oscillator

$$L(x, \dot{x}) = \frac{m}{2} \dot{x}^2 - \frac{1}{2} m \omega^2 x^2$$

$$H(x, p) = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

Harmonic Oscillator

- Harmonic Oscillator

$$L(x, \dot{x}) = \frac{m}{2} \dot{x}^2 - \frac{1}{2} m \omega^2 x^2$$

$$H(x, p) = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

- Effective Lagrangian

$$L = \frac{1}{2} (p\dot{x} - \dot{p}x) - \frac{p^2}{2m} - \frac{1}{2} m \omega^2 x^2 + i \frac{m \omega \tau_0}{2} \left[\dot{x}^2 + \frac{\dot{p}^2}{m^2 \omega^2} \right]$$

Harmonic Oscillator

- Harmonic Oscillator

$$L(x, \dot{x}) = \frac{m}{2} \dot{x}^2 - \frac{1}{2} m \omega^2 x^2$$

$$H(x, p) = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

- Effective Lagrangian

$$L = \frac{1}{2} (p\dot{x} - \dot{p}x) - \frac{p^2}{2m} - \frac{1}{2} m \omega^2 x^2 + i \frac{m \omega \tau_0}{2} \left[\dot{x}^2 + \frac{\dot{p}^2}{m^2 \omega^2} \right]$$

- Complex Lagrangian

Harmonic Oscillator

- Harmonic Oscillator
- Effective Lagrangian

$$L = \frac{1}{2} (p\dot{x} - \dot{p}x) - \frac{p^2}{2m} - \frac{1}{2} m\omega^2 x^2 + i \frac{m\omega\tau_0}{2} \left[\dot{x}^2 + \frac{\dot{p}^2}{m^2\omega^2} \right]$$

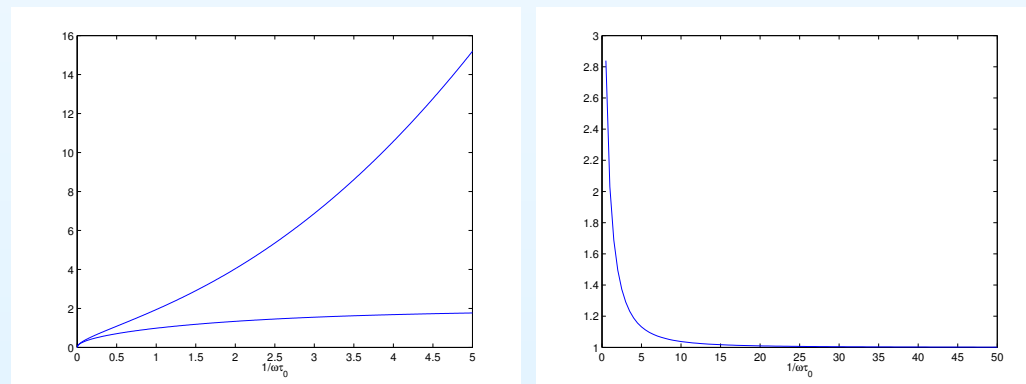
- Complex Lagrangian
- Landau problem with complex mass

Harmonic Oscillator

- Harmonic Oscillator
- Effective Lagrangian

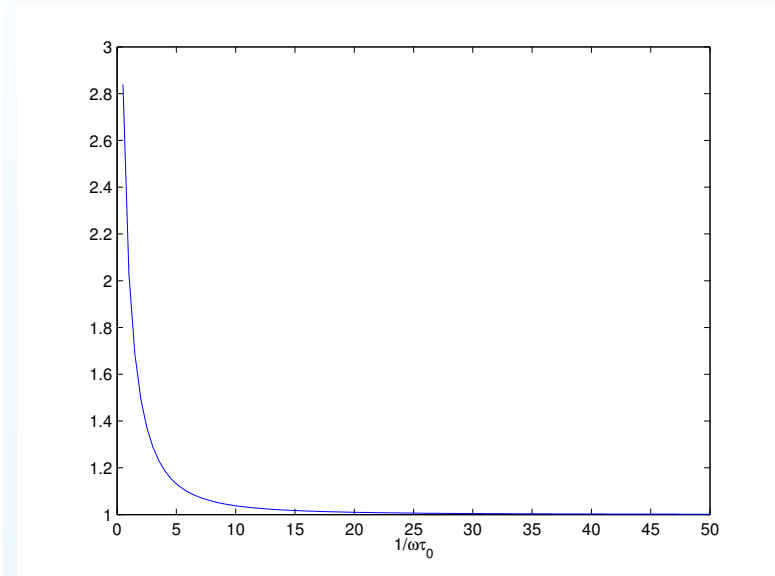
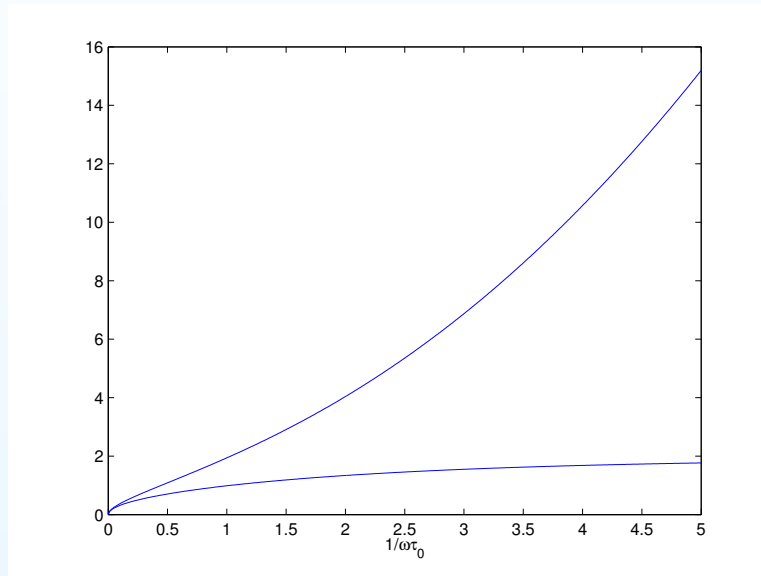
$$L = \frac{1}{2} (p\dot{x} - \dot{p}x) - \frac{p^2}{2m} - \frac{1}{2} m\omega^2 x^2 + i \frac{m\omega\tau_0}{2} \left[\dot{x}^2 + \frac{\dot{p}^2}{m^2\omega^2} \right]$$

- Complex Lagrangian
- Landau problem with complex mass
- 2 time scale : $\tau_- = \frac{2\tau_0}{R}$ $\tau_+ = \frac{2\tau_0}{R-1}$



Harmonic Oscillator

- 2 time scale : $\tau_- = \frac{2\tau_0}{R}$ $\tau_+ = \frac{2\tau_0}{R-1}$



O.H. : Hilbert Space

- $L^2(\mathbb{R}^2, dx dp)$

O.H. : Hilbert Space

- $L^2(\mathbb{R}^2, dx dp)$
- physical space : $L^2(\mathbb{R}, dx)$

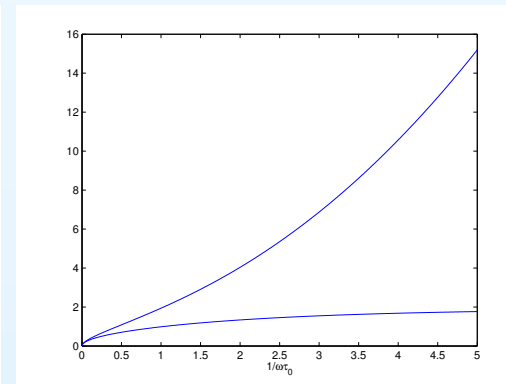
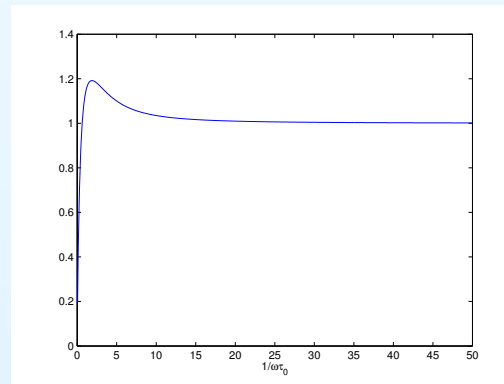
O.H. : Hilbert Space

- $L^2(\mathbb{R}^2, dx dp)$
- physical space : $L^2(\mathbb{R}, dx)$
- $\Rightarrow$ projection on coherent states

O.H. : Hilbert Space

- $L^2(\mathbb{R}^2, dx dp)$
- physical space : $L^2(\mathbb{R}, dx)$
- $\Rightarrow$ projection on coherent states
- Time Evolution

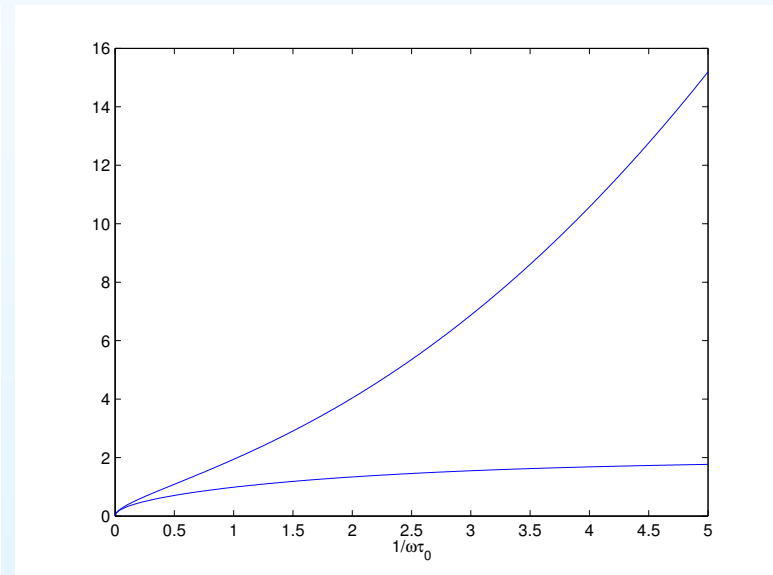
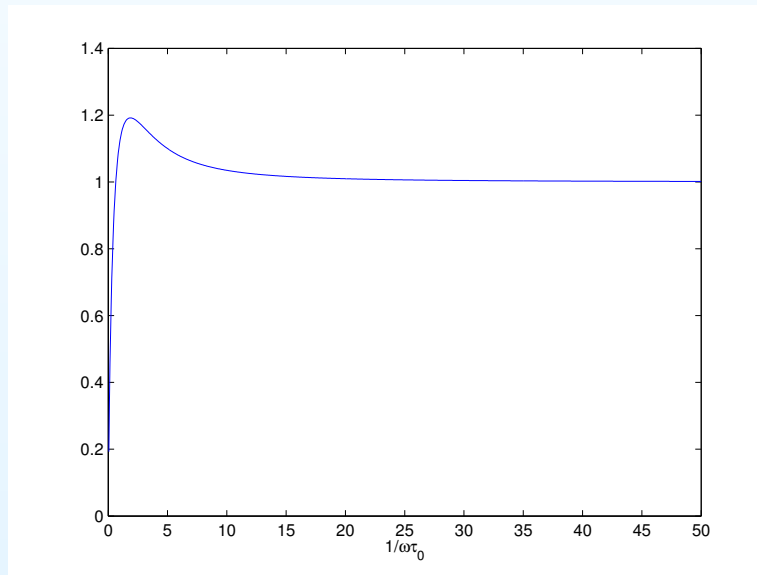
$$\begin{aligned} K_{nm} &= \langle n | \hat{K}(T_{21}) | m \rangle \\ &= F_0^{n+1}(T) e^{-(n+\frac{1}{2}) \frac{i\omega T}{R}} e^{-n \frac{T}{\tau_+}} \delta_{mn} \end{aligned}$$



O.H. : Hilbert Space

- Time Evolution

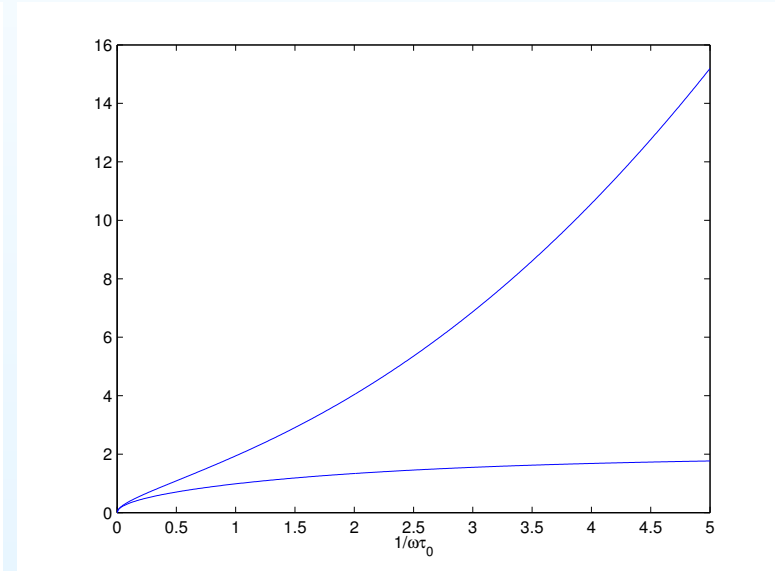
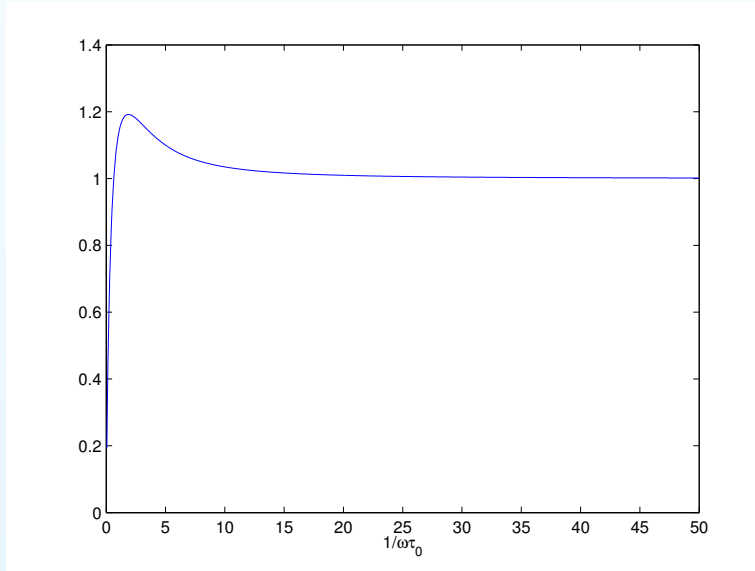
$$\begin{aligned} K_{nm} &= \langle n | \hat{K}(T_{21}) | m \rangle \\ &= F_0^{n+1}(T) e^{-(n+\frac{1}{2}) \frac{i\omega T}{R}} e^{-n \frac{T}{\tau_+}} \delta_{mn} \end{aligned}$$



O.H. : Hilbert Space

- Time Evolution

$$K_{nm} = F_0(T)^{n+1} e^{-(n+\frac{1}{2})\frac{i\omega T}{R}} e^{-n\frac{T}{\tau_+}} \delta_{mn}$$

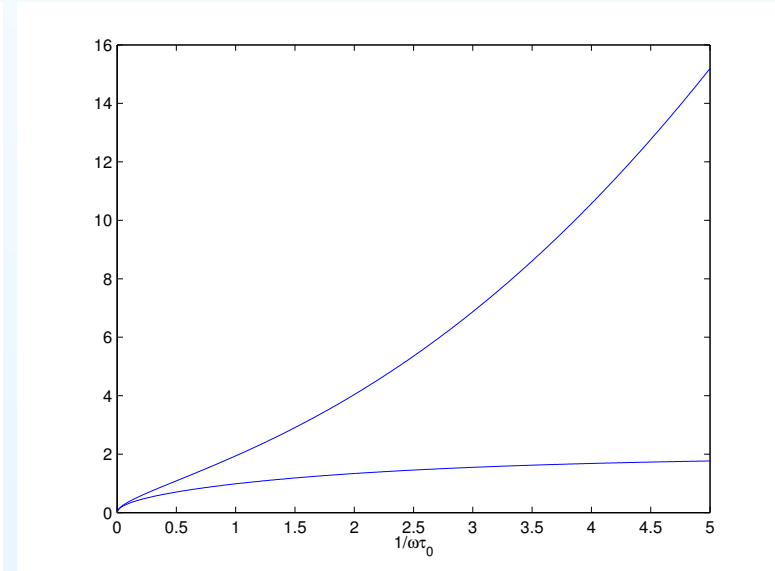
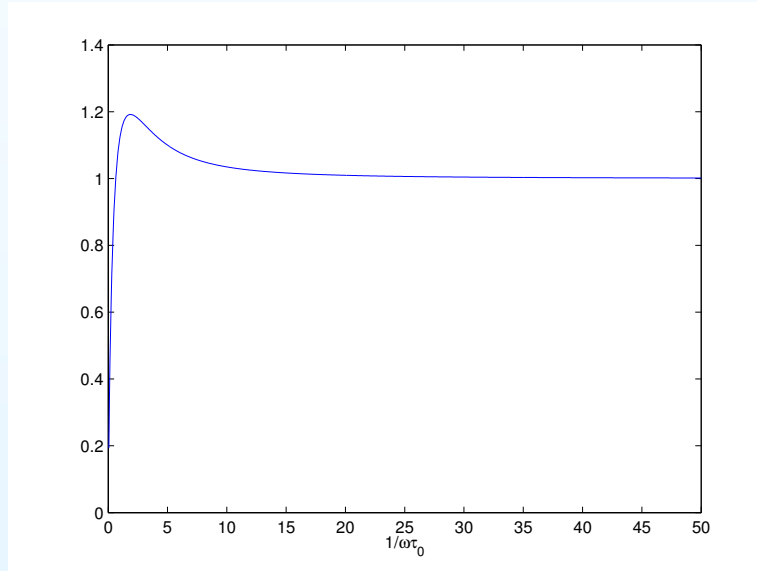


- suppression of excited states

O.H. : Hilbert Space

- Time Evolution

$$K_{nm} = F_0(T)^{n+1} e^{-(n+\frac{1}{2})\frac{i\omega T}{R}} e^{-n\frac{T}{\tau_+}} \delta_{mn}$$



- suppression of excited states
- problem for ground states

Commutativity

- Heisenberg representation

$$\hat{O}_H(t_2, t_1) = \hat{K}^\dagger(t_2, t_1) \hat{O}_S(t_1) \hat{K}(t_2, t_1)$$

Commutativity

- Heisenberg representation

$$\hat{O}_H(t_2, t_1) = \hat{K}^\dagger(t_2, t_1) \hat{O}_S(t_1) \hat{K}(t_2, t_1)$$

- computation of commutator

$$\langle n | [\hat{X}_H, \hat{P}_H] | l \rangle = -i\hbar |F_0|^{2(n+1)} e^{-n \frac{2T}{\tau_+}} \left[e^{-\frac{2T}{\tau_+}} + n |F_0|^2 e^{-\frac{2T}{\tau_+}} - n \right] \delta_{nl}$$

Commutativity

- Heisenberg representation

$$\hat{O}_H(t_2, t_1) = \hat{K}^\dagger(t_2, t_1) \hat{O}_S(t_1) \hat{K}(t_2, t_1)$$

- computation of commutator

$$\langle n | [\hat{X}_H, \hat{P}_H] | l \rangle = -i\hbar |F_0|^{2(n+1)} e^{-n \frac{2T}{\tau_+}} \left[e^{-\frac{2T}{\tau_+}} + n |F_0|^2 e^{-\frac{2T}{\tau_+}} - n \right] \delta_{nl}$$

- time dependant non commutative geometry

Susy Oscillator

- Lagrangian

$$L_{susy} = L_{bos} + L_{ferm}$$

Susy Oscillator

- Lagrangian

$$\begin{aligned} L_{susy} &= L_{bos} + L_{ferm} \\ &= \frac{1}{2} (\dot{\bar{z}}z - \dot{z}\bar{z}) - \frac{\omega}{2}\bar{z}z + i\frac{\tau_0}{2}[\dot{\bar{z}}\dot{z}] \end{aligned}$$

- $z = x + ip$

Susy Oscillator

- Lagrangian

$$\begin{aligned} L_{susy} &= L_{bos} + L_{ferm} \\ &= \frac{1}{2} (\dot{z}z - \dot{z}\bar{z}) - \frac{\omega}{2}\bar{z}z + i\frac{\tau_0}{2}[\dot{z}\dot{z}] \\ &+ \frac{1}{2} (\dot{\theta}\theta - \dot{\theta}\bar{\theta}) - \frac{\omega}{2}\bar{\theta}\theta + i\frac{\tau_0}{2}[\dot{\theta}\dot{\theta}] \end{aligned}$$

- $z = x + ip$
- θ Grassman Variable ($\theta^2 = 0$)

Susy Oscillator

- Lagrangian

$$\begin{aligned} L_{susy} &= L_{bos} + L_{ferm} \\ &= \frac{1}{2} (\dot{z}z - \dot{z}\bar{z}) - \frac{\omega}{2}\bar{z}z + i\frac{\tau_0}{2}[\dot{z}\dot{z}] \\ &+ \frac{1}{2} (\dot{\theta}\theta - \dot{\theta}\bar{\theta}) - \frac{\omega}{2}\bar{\theta}\theta + i\frac{\tau_0}{2}[\dot{\theta}\dot{\theta}] \end{aligned}$$

- $z = x + ip$
- θ Grassman Variable ($\theta^2 = 0$)
- different integral

$$\int dx dp e^{a(x^2+p^2)} \sim a^{-1}$$

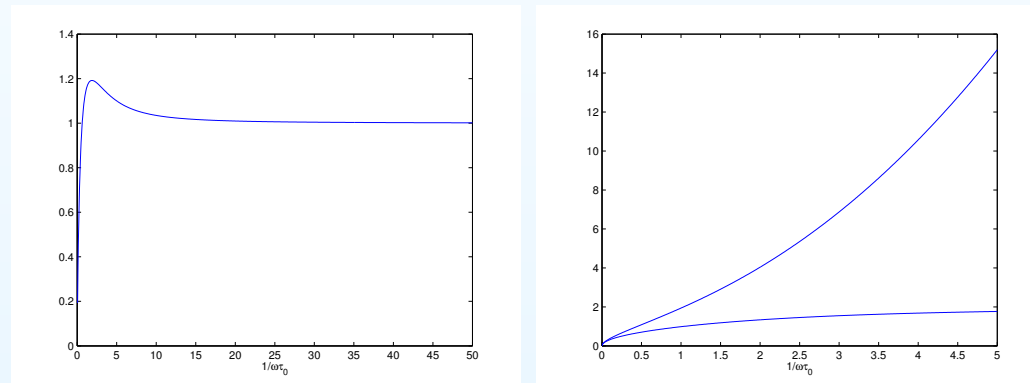
$$\int d\bar{\theta} d\theta e^{a\bar{\theta}\theta} \sim a$$

Susy Oscillator

- Time-evolution

$$K_{mn}^0 = F_0(T)^n e^{-(n) \frac{i\omega T}{R}} e^{-n \frac{T}{\tau_+}} \delta_{mn}$$

$$K_{mn}^1 = F_0(T)^{n+1} e^{-(n+1) \frac{i\omega T}{R}} e^{-(n+1) \frac{T}{\tau_+}} \delta_{mn}$$



Susy Oscillator

- Time-evolution

$$K_{mn}^0 = F_0(T)^n e^{-(n)\frac{i\omega T}{R}} e^{-n\frac{T}{\tau_+}} \delta_{mn}$$

$$K_{mn}^1 = F_0(T)^{n+1} e^{-(n+1)\frac{i\omega T}{R}} e^{-(n+1)\frac{T}{\tau_+}} \delta_{mn}$$

- ground states correctly defined

Susy Oscillator

- Time-evolution

$$K_{mn}^0 = F_0(T)^n e^{-(n)\frac{i\omega T}{R}} e^{-n\frac{T}{\tau_+}} \delta_{mn}$$

$$K_{mn}^1 = F_0(T)^{n+1} e^{-(n+1)\frac{i\omega T}{R}} e^{-(n+1)\frac{T}{\tau_+}} \delta_{mn}$$

- ground states correctly defined
- ground states preserved

Susy Oscillator

- Time-evolution

$$K_{mn}^0 = F_0(T)^n e^{-(n) \frac{i\omega T}{R}} e^{-n \frac{T}{\tau_+}} \delta_{mn}$$

$$K_{mn}^1 = F_0(T)^{n+1} e^{-(n+1) \frac{i\omega T}{R}} e^{-(n+1) \frac{T}{\tau_+}} \delta_{mn}$$

- ground states correctly defined
- ground states preserved
- preservation of the Supersymmetry

Field Theory

- hamiltonian representation

$$H = \frac{c^2 \chi^2}{2\hbar^2} + \frac{\hbar^2}{2} (\vec{\nabla} \phi)^2 + \frac{m^2 c^2}{2} \phi^2$$

Field Theory

- hamiltonian representation

$$H = \frac{c^2 \chi^2}{2\hbar^2} + \frac{\hbar^2}{2} (\vec{\nabla} \phi)^2 + \frac{m^2 c^2}{2} \phi^2$$

- holomorphe basis

$$|\phi(t_0, \vec{x}), \chi(t_0, \vec{x})\rangle$$

Field Theory

- hamiltonian representation

$$H = \frac{c^2 \chi^2}{2\hbar^2} + \frac{\hbar^2}{2} (\vec{\nabla} \phi)^2 + \frac{m^2 c^2}{2} \phi^2$$

- holomorphe basis

$$|\phi(t_0, \vec{x}), \chi(t_0, \vec{x})\rangle$$

- $\phi(\vec{k}) = \phi_1(\vec{k}) + i\phi_2(\vec{k})$

Field Theory

- hamiltonian representation

$$H = \frac{c^2 \chi^2}{2\hbar^2} + \frac{\hbar^2}{2} (\vec{\nabla} \phi)^2 + \frac{m^2 c^2}{2} \phi^2$$

- holomorphic basis

$$|\phi(t_0, \vec{x}), \chi(t_0, \vec{x})\rangle$$

- $\phi(\vec{k}) = \phi_1(\vec{k}) + i\phi_2(\vec{k})$
- 2 harmonic oscillator of same frequencies

Field Theory

- hamiltonian representation

$$H = \frac{c^2 \chi^2}{2\hbar^2} + \frac{\hbar^2}{2} (\vec{\nabla} \phi)^2 + \frac{m^2 c^2}{2} \phi^2$$

- holomorphic basis

$$|\phi(t_0, \vec{x}), \chi(t_0, \vec{x})\rangle$$

- $\phi(\vec{k}) = \phi_1(\vec{k}) + i\phi_2(\vec{k})$
- 2 harmonic oscillator of same frequencies
- $\omega(\vec{k}) = \frac{c}{\hbar} \sqrt{\vec{k}^2 + m^2 c^2}$

Feynman propagator

-

$$\Delta(x, y) = T(\langle 0 | \hat{\phi}(\vec{x}_2, t_2) \hat{\phi}(\vec{x}_1, t_1) | 0 \rangle)$$

Feynman propagator

-

$$\begin{aligned}\Delta(x, y) &= T(\langle 0 | \hat{\phi}(\vec{x}_2, t_2) \hat{\phi}(\vec{x}_1, t_1) | 0 \rangle) \\ &= \int \frac{d^3 \vec{k}}{2m\omega} K_0^\dagger(T) K_1(T) e^{-i\vec{k} \frac{\Delta \vec{x}}{\hbar}}\end{aligned}$$

Feynman propagator

-

$$\Delta(x, y) = T(\langle 0 | \hat{\phi}(\vec{x}_2, t_2) \hat{\phi}(\vec{x}_1, t_1) | 0 \rangle)$$

$$= \int \frac{d^3 \vec{k}}{2m\omega} K_0^\dagger(T) K_1(T) e^{-i\vec{k} \frac{\Delta \vec{x}}{\hbar}}$$

- exponential cut

$$K_{nm} = F_0(T)^{n+1} e^{-(n+\frac{1}{2}) \frac{i\omega T}{R}} e^{-n \frac{T}{\tau_+}} \delta_{mn}$$

Feynman propagator

-

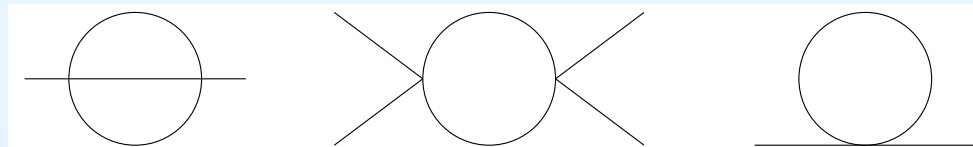
$$\Delta(x, y) = T(\langle 0 | \hat{\phi}(\vec{x}_2, t_2) \hat{\phi}(\vec{x}_1, t_1) | 0 \rangle)$$

$$= \int \frac{d^3 \vec{k}}{2m\omega} K_0^\dagger(T) K_1(T) e^{-i\vec{k} \frac{\Delta \vec{x}}{\hbar}}$$

- exponential cut

$$K_{nm} = F_0(T)^{n+1} e^{-(n+\frac{1}{2}) \frac{i\omega T}{R}} e^{-n \frac{T}{\tau_+}} \delta_{mn}$$

- supression of UV



Feynman propagator

-

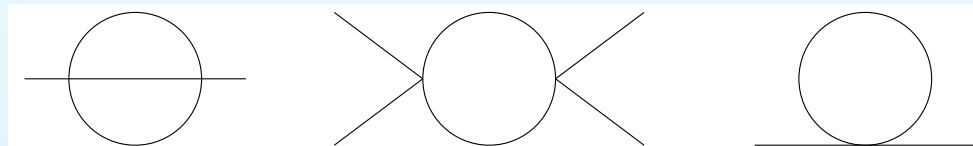
$$\Delta(x, y) = T(\langle 0 | \hat{\phi}(\vec{x}_2, t_2) \hat{\phi}(\vec{x}_1, t_1) | 0 \rangle)$$

$$= \int \frac{d^3 \vec{k}}{2m\omega} K_0^\dagger(T) K_1(T) e^{-i\vec{k} \frac{\Delta \vec{x}}{\hbar}}$$

- exponential cut

$$K_{nm} = F_0(T)^{n+1} e^{-(n+\frac{1}{2}) \frac{i\omega T}{R}} e^{-n \frac{T}{\tau_+}} \delta_{mn}$$

- supression of UV



- But this not work for “tadpole” diagram

Conclusions and Perspectives

- Conclusions
 - intrinsic development of non commutative geometry
 - still coherent with quantum mechanics
 - SUSY is the natural formalism
 - cure some UV divergencies

Conclusions and Perspectives

- **Conclusions**
 - intrinsic development of non commutative geometry
 - still coherent with quantum mechanics
 - SUSY is the natural formalism
 - cure some UV divergencies
- **Perspectives**
 - deformation of Wes-Zumino
 - cosmological applications
 - introduction of gravitations ?